

Thm 8.1 [Birkhoff invertible]

Let (X, \mathcal{B}, μ) be a proba measure space and $T: X \rightarrow X$ an invertible measure preserving transf.

Let $f \in L^1(X, \mu)$. Then there is a subset $\Omega \subset X$ of full measure such that $\forall x \in \Omega$:

$$f^+(x) = \lim_n \frac{1}{n} \sum_0^{n-1} f \circ T^k(x)$$

$$f^-(x) = \lim_n \frac{1}{n} \sum_0^{n-1} f \circ T^{-k}(x)$$

exist and $f^+(x) = f^-(x)$.

proof: f^+ and f^- exist by the usual Birkhoff. For $E = T^{-1}(E) = T(E)$ (mod 0) an invariant subset we have also.

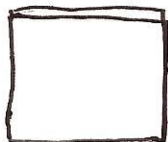
$$\int_E f = \int_E f^+ = \int_E f^-$$

Let $E = E_{\alpha, \beta} = \{f^- \leq \alpha < \beta \leq f^+\}$ for rational $\alpha < \beta$. Then E is T -invariant and

$$\beta \mu(E) \leq \int_E f^+ = \int_E f = \int_E f^- \leq \alpha \mu(E)$$

shows that $\mu(E) = 0$. so

$f^- \geq f^+$ a.e. and by symmetry the same is true for $f^+ \geq f^-$ a.e. //



$\int (1) \int (1) \int (1) \int (1)$ preserves Lebesgue

$$f^+ = f^- \text{ a.e.}$$

Flow $\mathbb{R} \times M \rightarrow M$

$$\phi(t, x) := \phi_t(x)$$

preserves $\mu \Leftrightarrow \forall f \in L^1(M, \mu)$

$$\int_M f \circ \phi_t(x) d\mu(x) = \int_M f(y) d\mu(y)$$

Thm 8.2 [Birkhoff flow]

Let (X, \mathcal{B}, μ) be a proba space and $\phi_t: X \rightarrow X, t \in \mathbb{R}$ a measure preserving flow.

Let $f \in L^1(X, \mu)$ then for a subset $\Omega \subset X$ of full measure:

$$f^+(x) = \lim_T \frac{1}{T} \int_0^T f(\phi_t(x)) dt$$

$$f^-(x) = \lim_T \frac{1}{T} \int_0^T f(\phi_{-t}(x)) dt$$

exist and are equal.

proof:



Let $\tau > 0$ and define

$$T = \phi_\tau,$$

$$F_\tau = \frac{1}{\tau} \int_0^\tau f(\phi_t(x)) dt$$

Then (X, \mathcal{B}, μ) is T -invariant and we may apply the previous thm to F :

By Fubini (or by symmetry)

$$\int F d\mu = \frac{1}{\tau} \int_0^\tau \int f \circ \phi_t d\mu dt$$

$$= \frac{1}{\tau} \int_0^\tau \int f(y) d\mu(y) dt$$

$$= \int f(y) d\mu(y)$$

so $F^+ = F^-$.

and Birkhoff states that

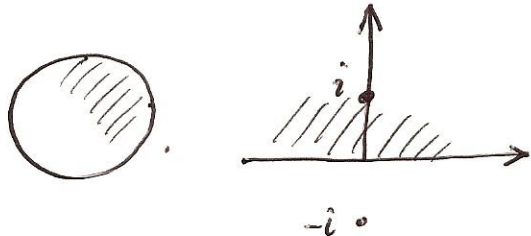
$$F^+ = \lim_n \frac{1}{n} \sum_{k=0}^{n-1} f \circ T^k \quad F^- = \lim_n \frac{1}{n} \sum_{k=0}^{n-1} f \circ T^{-k}$$

exist a.e. and are equal.

The Hyperbolic disk & plane

8.3

$$\mathbb{D} = \{ |z| < 1 \} \quad \mathbb{H}_+ = \{ \operatorname{Re} z > 0 \}$$



$$f: \mathbb{H}_+ \xrightarrow{\sim} \mathbb{D}, \quad f(w) = \frac{w-i}{w+i}$$

Poincaré metric on \mathbb{D}

$$ds^2 = \frac{4 dz d\bar{z}}{(1-z\bar{z})^2} \quad ds = \frac{2|dz|}{1-|z|^2}$$

$$= g(x,y) (dx^2 + dy^2)$$

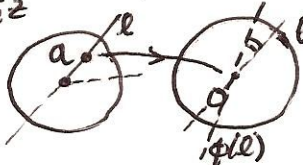
$$g(x,y) = \frac{4}{(1-(x^2+y^2))^2} =: "g(x+iy)"$$

Orientation preserving (shown by max principle) automorphisms:

$$\operatorname{Aut}_+(\mathbb{D}) = \{ \phi: \mathbb{D} \xrightarrow{\sim} \mathbb{D} \}$$

$$= \left\{ \phi(z) = e^{i\theta} \frac{z-a}{1-\bar{a}z} : |a| < 1, \theta \in \mathbb{R} \right\}$$

$$\cong \mathbb{D} \times \mathbb{S}^1$$



Lemma: $\phi^*g = g$

$$\text{proof: } \phi^* = \frac{1-|a|^2}{(1-\bar{a}z)^2} \quad g \circ \phi = \frac{4(1-|a|^2)^2}{(1-|a|^2)^2(1-|z|^2)^2}$$

$$\text{so } g(z) = g(\phi(z)) |\phi'(z)|^2 \quad \omega = \phi(z)$$

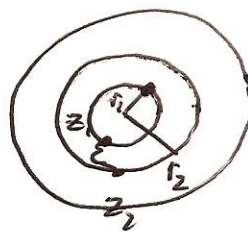
$$g(z) |dz|^2 = g(\omega) |d\omega|^2$$

Lemma: Geodesics through 0 are straight lines.



$$\text{Lemma: } \forall z_1, z_2 \in \mathbb{D} \quad d_{\mathbb{D}}(z_1, z_2) \geq \left| \ln \frac{1+r_1}{1-r_1} \frac{1-r_2}{1-r_2} \right| \frac{1}{2}$$

with $r_1 = |z_1|, r_2 = |z_2|$ and equality iff $t_2 z_2 = t_1 z_1$ for some $(t_1, t_2) \in \mathbb{R} \times \mathbb{R} \setminus \{0, 0\}$



$$0 < r_1 < r_2 < 1$$

$\gamma: [0, 1] \xrightarrow{c} \text{path } z_1 \text{ to } z_2$

$$\dot{\gamma} = r(t) e^{i\theta(t)}$$

$$\dot{\gamma} = \dot{r} e^{i\theta} + i r \dot{\theta} e^{i\theta}$$

$$|\dot{\gamma}|^2 = \dot{r}^2 + r^2 \dot{\theta}^2 \geq \dot{r}^2$$

$ds = \sqrt{g(\dot{\gamma}, \dot{\gamma})} |\dot{\gamma}| dt$ so

$$\ell(\gamma) = \int_0^1 \frac{2}{1-|\gamma|^2} |\dot{\gamma}| dt$$

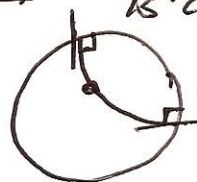
$$\geq \int_{r_1}^{r_2} \frac{2}{1-r} dr$$

$$= \frac{1}{2} \ln \frac{1+r_2}{1+r_1} \frac{1-r_1}{1-r_2}$$

equality iff $0, z_1, z_2$ are aligned (and γ straight path).

$\operatorname{Aut}_+(\mathbb{D}) = \text{Möb}(\mathbb{D})$
maps straight lines to circles preserving angles.

Prop: any geodesic in \mathbb{D} is a circular arc whose limit directions are normal to $\partial\mathbb{D}$



true for geodesics through 0 and preserved by autom.

$\mathcal{U}^1 = \mathbb{D} \times \mathbb{S}^1$ describes the unit tangent bundle of \mathbb{D} , normalized s.t. for $(z, v) \in \mathcal{U}^1$
 $\|v_z\|_{\mathbb{D}} = 1$

Def The geodesic flow on a Riemannian manifold (complete) is the unique C^1 map $\phi: \mathbb{R} \times M \rightarrow M$
 $(t, \xi) \mapsto \phi_t \xi$

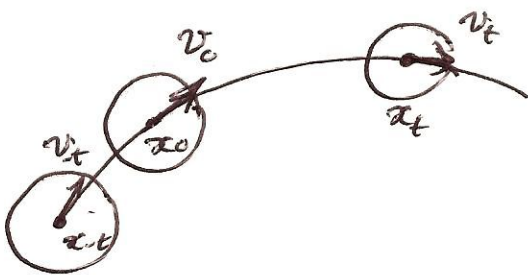
such that

$$\phi_t(x_0, v_0) = (x_t, v_t)$$

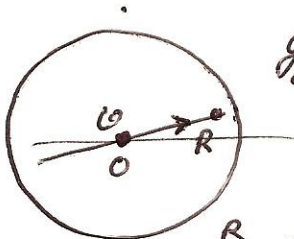
verify $v_t = \frac{d}{dt} x_t, \|v_t\| = 1$.
 and $\forall \delta > 0$

$\forall x \in M, v \in S_x M \exists \delta > 0$ s.t.

$\gamma_\delta = \phi \{ \phi_t(x) : \delta \leq t \leq \delta \}$
 is the unique geodesic from $\phi_\delta(x)$ to $\phi_\delta(x)$. We have
 $\text{len } \gamma_t = |t| \forall 0 \leq t \leq \delta$.



Ex: Poincaré disc
 let $z_0 = 0 \in \mathbb{D}$ (the center)



geodesics through a are straight lines

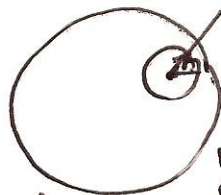
$$s = \int_0^R \frac{2dr}{1-r^2} = \ln \frac{1+R}{1-R}$$

$$\text{or } R = \frac{e^s - 1}{e^s + 1} = \text{th } \frac{s}{2}$$

$$v_0 = e^{i\theta} e^{s^1}$$

$$\phi_t(0, e^{i\theta}) = \left(\text{th } \frac{t}{2}, e^{i\theta} \left(\frac{1 - \text{th}^2 \frac{t}{2}}{2} \right) \right)$$

$$(z_t, \theta_t) = \left(e^{i\theta} \text{th } \frac{t}{2}, \theta \right)$$



$$\xi = \frac{e^{i\theta} (1 - |z_t|^2)}{2}$$

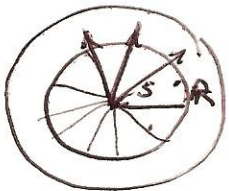
natural coordinates: (z, θ)

geodesic (z_t, θ_t)

$$\frac{dz_t}{dt} = e^{i\theta} \frac{(1 - |z_t|^2)}{2}$$

$$\|\xi_t\|_{\mathbb{D}} = 1$$

Horocycles and stable/unstable nfls.



$$S \Rightarrow \int ds = \int \frac{2Rz}{1-z^2} = \int_0^R \frac{2dr}{1-r^2} = \ln \frac{1+R}{1-R}$$

$$\Leftrightarrow R = \frac{e^S - 1}{e^S + 1} = \text{th} \frac{S}{2}$$

$$B_{\mathbb{D}}(0, s) = B_{\mathbb{D}}(0, R(s))$$

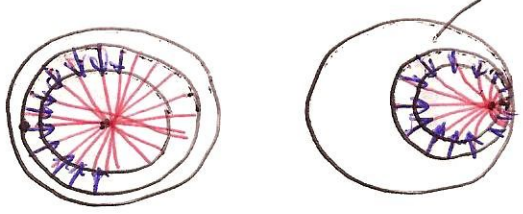
- Equal time (s) circle centered at the origin "horocycle"
- Geodesics are normal to the circle

The Möbius transformation

$$\Phi_a(z) = \frac{z+a}{1-\bar{a}z} \quad a = \text{th} \frac{s_0}{2}$$

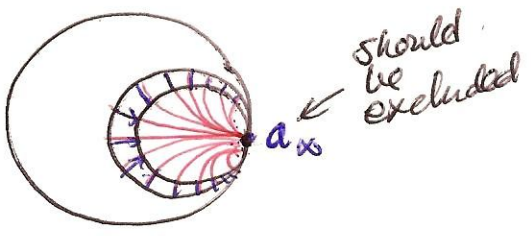
maps 0 to a circle
If $s = s_0 + t$ then $r_0 = \text{th} \frac{s_0}{2}$

$$\Phi_a = e^{ix} \text{th} \frac{s_0}{2} \rightarrow \partial\mathbb{D} \quad \text{equal time circles}$$



$$B_{\mathbb{D}}(a, s) = \Phi_a(B_{\mathbb{D}}(0, s))$$

Letting $a_j \rightarrow \partial\mathbb{D}$ and keeping $s = s_0 + t$ we get the so-called "horocycles" $H_{\mathbb{D}}^s(a_{\infty})$



should be excluded

Let $H_{\mathbb{D}}^s(a_{\infty})$ denote the "inward" normal bundle of $H_{\mathbb{D}}(a_{\infty}) \setminus \{a_{\infty}\}$

Prop: The flow ϕ_t maps $\Phi_t: H_{\mathbb{D}}^s(a_{\infty}) \rightarrow H_{\mathbb{D}}^s(a_{\infty}) \quad t \in \mathbb{R}$

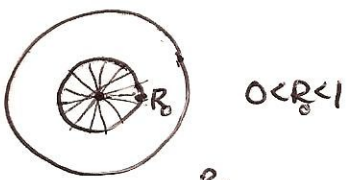
Proof true for $B_{\mathbb{D}}(0, s_0)$ (normal) $\phi_t: B_{\mathbb{D}}^s(0, s_0) \rightarrow B_{\mathbb{D}}^s(0, s_0 + t) \quad t \in \mathbb{R}$ and preserved by Möbius and taking limit $s_0 \rightarrow \infty$

Def: Let

Let $\xi_{s_0} = (z_0, v_0) \in S_{\mathbb{D}}$ and let $\xi_t = \lim_{s \rightarrow \infty} \Phi_s(\xi_{s_0}) \in \partial\mathbb{D}$ be the so-called "ideal" limit points

Prop: $\xi_0 \in H_{\mathbb{D}} \xi_0$





$$s_0 = d_{\mathbb{D}}(O, R_0) = \int_0^{R_0} \frac{2r}{1-r^2} = \ln \frac{1+R_0}{1-R_0} \text{ or}$$

$$R_0 = R(s_0) = \tanh \frac{s_0}{2} = \text{th } s_0/2$$

so $B_{\mathbb{D}}(O, R_0) = B_{\mathbb{D}}(O, R(s_0))$

Equal time circle centered at O. "horocycle"
geodesics are normal to (through) the circle

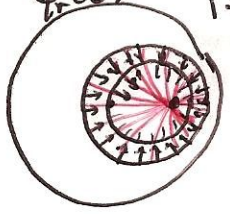
Let $s = s_0 + t$ and $r = \text{th } s/2$
The Möbius transf.

$$\phi_r(z) = \frac{z+r}{1+rz}$$

$$\phi_r(r_0) = \frac{r-r_0}{1+r r_0} = \text{th} \left(\frac{s-s_0}{2} \right) = \text{th} \left(\frac{t}{2} \right)$$

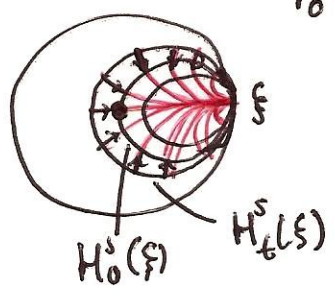
$$\phi_r(r_0) = \frac{r+r_0}{1+r r_0} = \text{th} \left(\frac{s+s_0}{2} \right) = \text{th} \left(\frac{s_0+t}{2} \right)$$

$$\phi_r(O) = \frac{r}{1+0} = r = \text{th} \left(\frac{s_0+t}{2} \right)$$

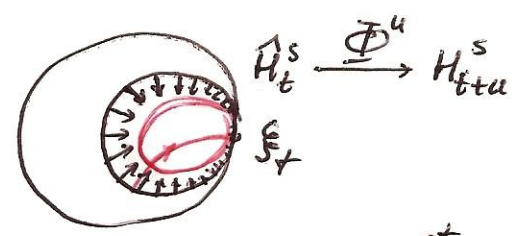


$B_{\mathbb{D}}(r_t, s_0) = \phi_r(B_{\mathbb{D}}(O, s_0))$
describes the geodesic disk centered at $r_t = \text{th} \left(\frac{s_0+t}{2} \right)$ of radius (geod) s_0

Letting $s_0 \rightarrow \infty$ we obtain the family of horocycles
 $r_0 \rightarrow \xi \in \partial \mathbb{D}$



Let $\hat{H}_t^s(\xi)$ be the forward normal bundle of $H_t^s(\xi)$



Then Φ for $(z, v) \in \hat{H}_t^s(\xi_+)$
 $\Phi^u(z, v) \in H_{t+u}^s(\xi)$

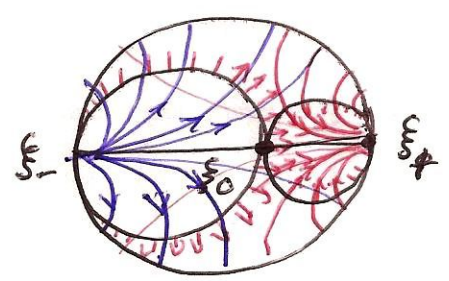
Theorem Wheelock Top
Let $(z_0, v_0) \in \mathcal{U}^1(\mathbb{D})$ and

$\xi_{\mp} = \lim_{t \rightarrow \pm\infty} \Phi^t(z_0, v_0) \in \partial \mathbb{D}$ be the ideal limit point
Then $\hat{H}_{t_0}^s(z_0, v_0) \in \hat{H}_{t_0}^s(\xi_{\mp})$ for some t_0 and

$\hat{H}_{t_0}^s(\xi_{\mp})$ is the stable manifold of (z_0, v_0)

Similarly $(z_0, v_0) \in \hat{H}_{t_0}^-(\xi_{\mp})$ for some t_0 and

$H_{t_0}^-(\xi_{\mp})$ is the unstable manifold of (z_0, v_0)



$$\forall \eta \in \hat{H}^s(\xi_0), x \in \hat{H}^u(\xi_0)$$

$$d_{\mathbb{D}}(\Phi^t \eta, \Phi^t \xi_0) \xrightarrow{t \rightarrow +\infty} 0$$

$$d_{\mathbb{D}}(\Phi^t \eta, \Phi^t \xi_0) \xrightarrow{t \rightarrow -\infty} \infty$$

$$ds = \frac{2|dz|}{1-|z|^2}$$

$$s = \int_0^r \frac{2r dr}{1-r^2} = \ln \frac{1+r}{1-r} \Leftrightarrow r = \tanh \frac{s}{2}$$

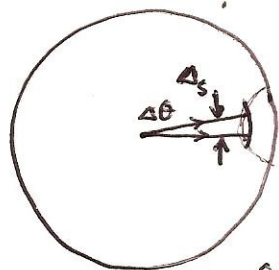
$$d(\cdot, \cdot)_{\mathbb{D}} \quad B_{\mathbb{D}}(0, s) = B_{\mathbb{C}}(0, \tanh \frac{s}{2})$$



$$l_s = |\partial B| = \int \frac{2r d\theta}{1-r^2} = 2\pi \frac{2r}{1-r^2} = 2\pi \cdot 2 \operatorname{sh} \frac{s}{2} \operatorname{ch} \frac{s}{2} = 2\pi \operatorname{sh} s$$

$$\text{or } l_s = 2\pi(e^s - e^{-s}) = \dots$$

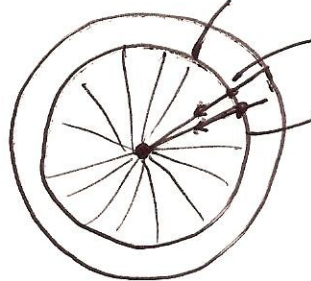
dist between radial trajectories



$$\Delta_s \approx \Delta \theta \cdot \operatorname{sh} s \approx \Delta \theta \cdot \frac{1}{2} e^s \quad (s \text{ large})$$

$$\frac{\Delta \theta}{2\pi} \cdot l_s \approx \Delta \theta \cdot \frac{e^s}{2}$$

time s_0 ~~ball~~ circle centered at 0 .



radial flow

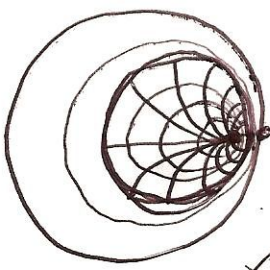
$$\Delta_{s_0+t} \approx \Delta \theta \cdot \operatorname{sh}(s_0+t) = \Delta \theta \cdot \frac{1}{2}(e^{s_0+t} - e^{-s_0-t})$$

$$\approx \Delta \theta \cdot e^t \quad (s_0 \gg 1)$$

nearby trajectories

$$\frac{\Delta_{s_0+t}}{\Delta_{s_0}} \approx e^t$$

valid when $s_0 \gg 1, |t| \ll s_0$

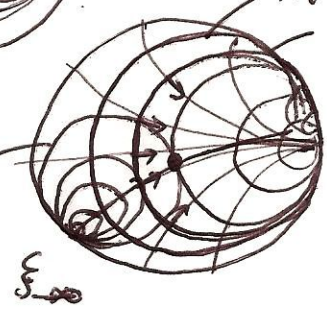


$$\varphi_{a_0} (B_{\mathbb{D}}(0, s_0+t)) \quad |a_0| = \tanh \frac{s_0}{2}$$

$$a_0 \rightarrow \xi \in \partial \mathbb{D}$$

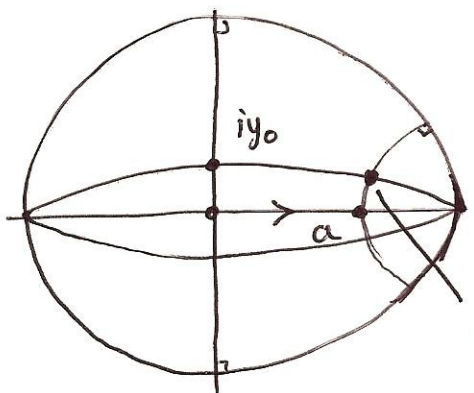
$$H_t(\xi) = \lim_{s \rightarrow \infty} \varphi_{a_0}(B_{\mathbb{D}}(0, s_0+t))$$

$$H^+(\xi_{\infty})$$



$\hat{H}_t(\xi_{\infty})$ inward normal ~~inward~~ bundle

More precise



$$\xi_{y_0} = \tanh \frac{s_0}{2} \quad d_{\mathbb{D}}(0, iy_0) = s_0$$

$$d_{\mathbb{D}}(-iy_0, iy_0) = 2s_0$$

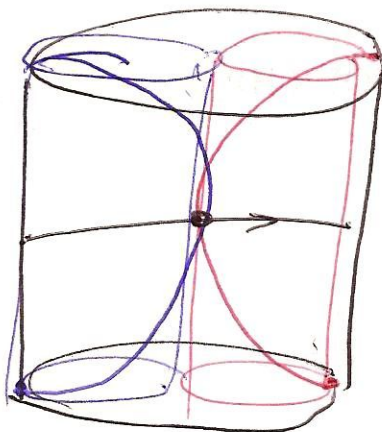
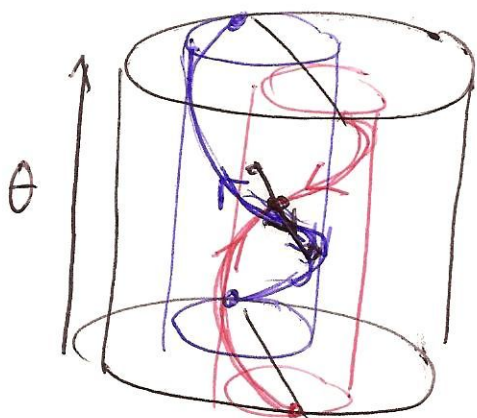
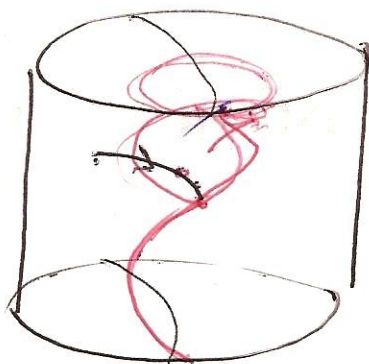
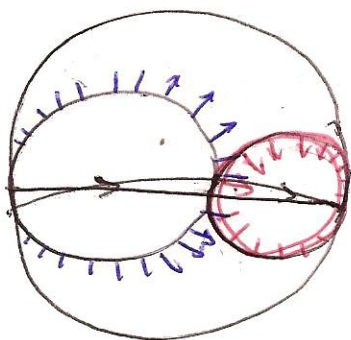
$$\varphi_a(z) = \frac{z+a}{1+\bar{a}z}$$

$$d_{\mathbb{D}}(\varphi_a(iy_0), \varphi_a(-iy_0)) = 2s_0 \quad (\text{isometry } \varphi_a)$$

$$a \frac{1+y_0^2}{1+a^2 y_0^2} + iy_0 \frac{1-a^2}{1+a^2 y_0^2}$$

$$\varphi_a(0) = a \quad \varphi_a(\infty) = \frac{1}{\bar{a}}$$

4th



Lagrange + Hamiltonian

(5)

$$L = \frac{1}{2} g_x(v, v) = \frac{1}{2} g_z(\dot{z}, \dot{z})$$

$$\frac{d}{dt} \frac{\partial L}{\partial \dot{z}} = \frac{\partial L}{\partial z}$$

$$L(z, \dot{z}) = \frac{1}{2} g_z(\dot{z}, \dot{z}) = \frac{1}{2} \frac{1}{(1-|z|^2)^2} |\dot{z}|^2$$

$$= \frac{1}{2} \frac{1}{(1-(x^2+y^2))^2} (x^2 + y^2)$$

$$L = \frac{1}{2} g_{\alpha\beta} \dot{z}^\alpha \dot{z}^\beta$$

$$p_x = \frac{\partial L}{\partial \dot{x}} \quad p_y = \frac{\partial L}{\partial \dot{y}} = \frac{1}{(1-|z|^2)^2} \dot{y}$$

$$= \frac{1}{2(1-|z|^2)^2} \dot{x}$$

$$H(z, p) = (\dot{z} p - L(z)) \quad |p = \frac{\partial L}{\partial \dot{z}}$$

$$p_\alpha = g_{\alpha\beta} \dot{z}^\beta$$

$$\dot{z}^\beta = g^{\beta\alpha} p_\alpha$$

↑
inverse matrix

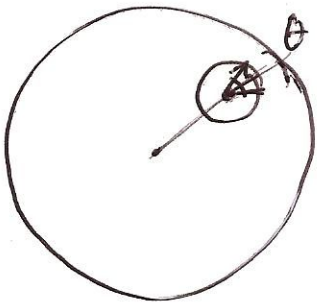
$$H = \frac{1}{2} g^{\alpha\beta} p_\alpha p_\beta$$

$$H(z, p) = \frac{1}{2} (1-|z|^2)^2 (p_x^2 + p_y^2)$$

$$\begin{cases} \dot{x} = \frac{\partial H}{\partial p_x} & \dot{y} = \frac{\partial H}{\partial p_y} \\ \dot{p}_x = -\frac{\partial H}{\partial x} & \dot{p}_y = -\frac{\partial H}{\partial y} \end{cases}$$

preserves H and $dx \wedge dp_x + dy \wedge dp_y = \omega$
 whence also $\omega \lrcorner \omega = dx dy dp_x dp_y = \Omega$
 and $\mu = \Omega \delta(H-1)$ unit tangent bundle

$$p_{\mathbb{R}^2}(p_x, p_y) = |p| (\cos \theta, \sin \theta)$$



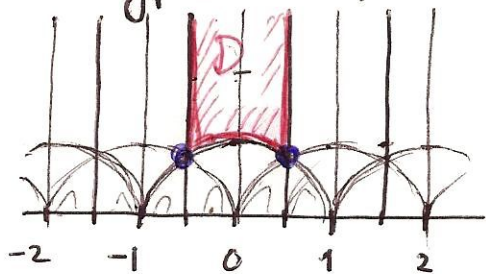
$(x, y), \theta$

$$dp = dx dy d\theta \cdot \frac{1}{|p|} = dx dy d\theta \cdot \frac{1}{(1-|z|^2)}$$

$$\text{Area}(\mathbb{D}^2 \times S^1) = \infty$$

To get finite area we need to take a quotient

Quotient of The hyperbolic plane / disc.



$$H = \{Im z > 0\}$$

Fundamental domain

$$D = \{z \in H : |z| \leq 1, |Re z| \leq \frac{1}{2}\} \cong H / \Gamma$$

$$\Gamma = PSL(2, \mathbb{Z}) \subset PSL(2, \mathbb{R})$$

identif of bag-pls

ΓD tessellates the plane

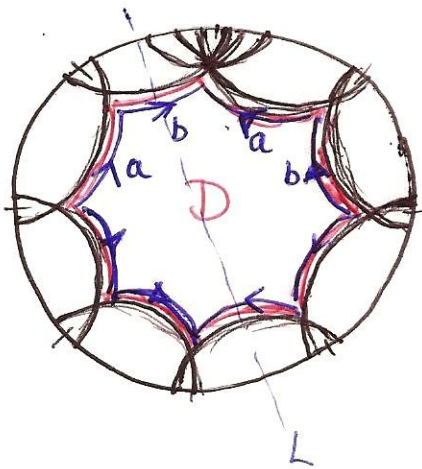
$$\partial D \cap \partial' D \neq \emptyset \Leftrightarrow \gamma = \gamma'$$

ΓD is dense in H

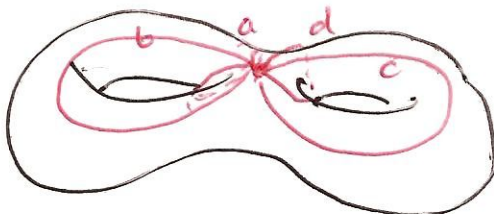
Edge points: $\pm \frac{1}{2} + i \frac{\sqrt{3}}{2}, \infty$

angles $\frac{\pi}{3}, \frac{\pi}{3}, 0$.

But does not yield a compact mfd.



21



genus 2 surface

Stable and Unstable sets

(M, g) Riem. mfd.
 ϕ_t complete flow on M .

Def For $p \in M$

$$W^s(p) = \{q \in M : d(\phi_t p, \phi_t q) \xrightarrow[t \rightarrow +\infty]{} 0\} \quad \text{(stable set of } p)$$

$$W^u(p) = \{q \in M : d(\phi_t p, \phi_t q) \xrightarrow[t \rightarrow -\infty]{} 0\} \quad \text{(unstable set of } p)$$

Lemma: Let $f \in C^0(M)$ be unif cont.
 Let $p \in M$ and suppose that

$$f^+(p) := \lim_{T \rightarrow +\infty} \frac{1}{T} \int_0^T f \circ \phi_t(p) dt \quad \text{and}$$

$$f^-(p) := \lim_{T \rightarrow +\infty} \frac{1}{T} \int_0^T f \circ \phi_{-t}(p) dt \quad \text{exist.}$$

Then $\forall q \in W^s(p) : f^+(p) = f^+(q)$ and
 $\forall r \in W^u(p) : f^-(p) = f^-(r)$.

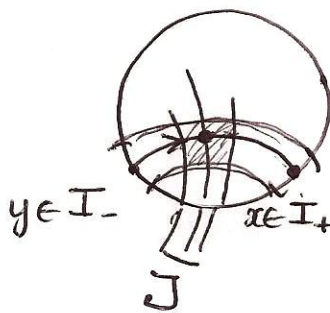
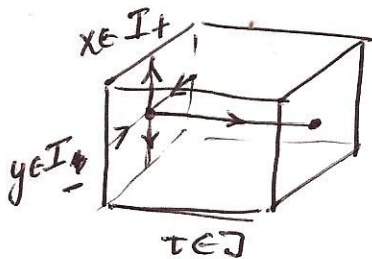
proof: By unif cont of f :

$$\lim_{t \rightarrow +\infty} d(\phi_t q, \phi_t p) \Rightarrow 0 \Rightarrow$$

$$\lim_{t \rightarrow +\infty} |f \circ \phi_t(q) - f \circ \phi_t(p)| = 0$$

so $f^+(p) = f^+(q)$
 (similarly for $f^-(r) = f^-(p)$). //

$\exists \Omega \subset B = I_+ \times I_+ \times J$
of full measure s.t.
 $f^+(w) = \bar{f}(w), \forall w \in \Omega.$



"Good local coordinates"

$f^+(x)$ depends only upon unstable coord.

(1^s) $f^+(x, y, \tau) = f^+(x)$ indep of y, τ

(1^u) $\bar{f}(x, y, \tau) = \bar{f}(y)$ indep of x, τ

Fubini $\Rightarrow \exists A_+ \subset I_+$ of full measure such that $\forall x \in A_+$:

$U_x := \{(y, \tau) \in I_- \times J : (x, y, \tau) \in \Omega\}$
is of full measure

Lemma $\forall x, x' \in A_+ : a^+(x) = a^+(x')$

proof Since U_x and $U_{x'}$ have full measure they intersect so
(*) $\exists (\tilde{y}, \tilde{\tau}) \in U_x \cap U_{x'}$. Then

$$\begin{aligned} a^+(x) &= f^+(x, \tilde{y}, \tilde{\tau}) \quad \text{since } (x, \tilde{y}, \tilde{\tau}) \in \Omega \\ &= \bar{f}(x, \tilde{y}, \tilde{\tau}) \\ &= \bar{f}(x', \tilde{y}, \tilde{\tau}) \quad \text{by (1^u)} \\ &= f^+(x', \tilde{y}, \tilde{\tau}) \quad (x', \tilde{y}, \tilde{\tau}) \in \Omega \\ &= a^+(x') \end{aligned}$$

Prop $f^+(x, y, \tau) = \bar{f}(x, y, \tau) = \text{const}$
a.e. on B .

proof: On $A_+ \times I_- \times J : f^+$ is const.
Similarly there is $A_- \subset I_-$ of full meas so \bar{f} is const on $A_- \times A_+ \times J$
and they are equal on a full measure set.

~~This is on the compact~~
Theorem ~~g is surface~~
 g_t is ergodic with respect to Liouville measure on $S_1 M$. (when M is compact quotient of \mathbb{H}^2 (finite vol surface))

proof [Hopf, '35]

Given $f \in L^1(S_1 M, \mu)$
let approximate f by a cont. fct. (where unif cont fct) on $S_1 M$.
Birkhoff $\Rightarrow f^+$ and f^- are equal a.e.
By coroll —

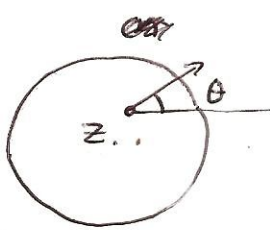
f^+ and f^- are const along stable and unst. mflds respectively

By prop — f^+ and f^- are locally a.e const whence a.e const on M .
(the const = $\int_M f d\mu$)
So g_t is ergodic.

Complement

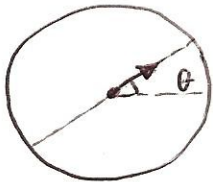
Unit tangent bundle

$S_1\mathbb{D} \cong \{(z, \theta) : z \in \mathbb{D}, \theta \in \mathbb{R}/2\pi\mathbb{Z}\}$
 we associate to (z, θ)
 a tangent vector in $T_z\mathbb{D}$ $v = v_{z, \theta}$



$v = e^{i\theta} \frac{1-|z|^2}{2}$ which makes $|v|_{\mathbb{D}} = 1$

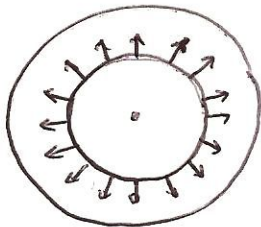
$\pi : S_1\mathbb{D} \rightarrow \mathbb{D}$
 $(z, \theta) \mapsto z$ natural projection



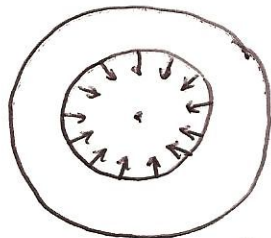
geodesic flow at z
 $g_t(z, \theta) = (e^{i\theta} \operatorname{th} \frac{t}{2}, \theta)$

Horocircles

Let $\hat{0} = \pi^{-1}(0) = \{(0, \theta) : \theta \in \mathbb{R}/2\pi\mathbb{Z}\}$
 be the unit vectors based at the origin in \mathbb{D} .



$g_t(\hat{0})$ for $t > 0$



$g_t(\hat{0})$ for $t < 0$

Complement

Hyperbolic set.

Def M smooth manifold
 $U \subset M$ open subset, $T: U \rightarrow M$
 a C^1 -diffeomorphism onto
 its image and Λ a
 compact T -invariant set.

$$T(\Lambda) = \Lambda.$$

Lemma: E_x^+ and E_x^-
 depends continuously
 on x . and.
 $\dim E_x^+$ and $\dim E_x^-$
 are locally constant.

1) Def Λ is called a
 hyperbolic set for T if
 there is a Riemannian
 metric on U (open nhd of Λ)
 and $\theta < 1$ such that DT
 admits a hyperbolic
 θ -splitting, i.e. $\forall x \in \Lambda$ we
 have $T_x^k \mathbb{R}^n = E_{x,k}^+ \oplus E_{x,k}^-$ with

$$\|DT_x|_{E_{x,k}^-}\| \leq \theta$$

$$\|DT_x^{-1}|_{E_{x,k}^+}\| \leq \theta$$

and $E_{x,k}^+, E_{x,k}^-$ depends
 continuously on x
 and $\forall DT_x E_{x,k}^\pm = E_{T(x),k}^\pm$

2) The hyperbolic set is ^{locally- or basic} maximal
 if \exists open nhd U of Λ s.t:

$$\bigcap_{n \in \mathbb{Z}} T^n U = \Lambda$$

3) The diffeo T is called
 ANOSOV if $\Lambda = M$.