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Master Structural Mechanics and Coupled Systems

Applied Mathematics

Lecture 7 Length and normal of a curve

• Plane curve in the Euclidian plane

The first example is the line segment [A, B] between the two points $A(\alpha, \beta)$ and $B(\gamma, \delta)$. We have a parameterization $[0, 1] \ni t \mapsto M(t) = (X(t), Y(t)) = (1 - t)A + tB$. In particular, $X(t) = (1 - t)\alpha + t\gamma$ and $Y(t) = (1 - t)\beta + t\delta$.

The second example is a circular arc. We introduce R > 0 and θ_1 and θ_2 such that $0 \le \theta_1 < \theta_2 \le 2\pi$ to fix the ideas. Then a point $M(\theta)$ of this curve satisfies the conditions $\theta_1 \le \theta \le \theta_2$ and $M(\theta) = R(\cos \theta, \sin \theta)$.

Functional curve (third exmple). For a > b two given reals, we consider the mapping $[a, b] \ni t \longmapsto f(t) \in \mathbb{R}$ and the associate graph in the Euclidian plane: X(t) = t, Y(t) = f(t).

In general, we have two regular functions X and Y from the interval [a, b] and taking their values in \mathbb{R} . The curve Γ is composed by all the points M(t) = (X(t), Y(t)) for all $t \in [a, b]$.

• Velocity vector

When the mapping $t \mapsto M(t)$ is derivable, we set $V(t) = \frac{dM}{dt}$. The components of the velocity vector are simply $\frac{dM}{dt} = \left(\frac{dX}{dt}, \frac{dy}{dt}\right)$.

For the previous examples, we have respectively $V(t) = -A + B = \overrightarrow{AB}$ for the first example, $V(\theta) = R(-\sin\theta, \cos\theta)$ in the second case and V(t) = (1, f'(t)) for a functional curve.

• Length of a regular curve

We introduce an integer $N \ge 1$ and we first define the approximated length L_N . With $h = \frac{b-a}{N}$, we consider $a = t_0 < t_1 < ... < t_j = a + jh < t_{j+1} = t_j + h < ... < t_N = b$ and $M_j = M(t_j)$. We approach the length of the curvilear arc $\widehat{M_j M_{j+1}}$ by the length $||\overline{M_j M_{j+1}}||$ of the segment $[M_j, M_{j+1}]$. We have $||\overline{M_j M_{j+1}}|| = \sqrt{(X(t_{j+1}) - X(t_j))^2 + (Y(t_{j+1}) - Y(t_j))^2}$ and we set $L_N = \sum_{j=1}^N ||\overline{M_j M_{j+1}}||$ for the length of the polygoal approximation of the curve.

We have also the following expansions, if the functions X and Y are derivable:

 $X(t_j + h) = X(t_j) + h \frac{dX}{dt}(t_j) + h \varepsilon_j^X(h)$ and $Y(t_j + h) = Y(t_j) + h \frac{dY}{dt}(t_j) + h \varepsilon_j^Y(h)$ with $\varepsilon_j^X(h)$ and $\varepsilon_j^Y(h)$ tending to zero as h tends to zero. Then $||\overline{M_j M_{j+1}}|| = h ||\frac{dM}{dt}(t_j)|| + h \eta_j(h)$ and $\eta_j(h)$ tends to zero if h tends to zero. In consequence, we have the decomposition

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 $L_N = \sum_{j=1}^N h ||\frac{dM}{dt}(t_j)|| + h \sum_{j=1}^N \eta_j(h)$. The second term tends to zero when *h* tends to zero and the first tends to the integral $\int_a^b ||\frac{dM}{dt}(t)|| dt$ in the same conditions.

The length L of the curve Γ between the parameters a and b is given by the relation $L = \int_a^b ||\frac{dM}{dt}(t)|| dt = \int_a^b ||V(t)|| dt$.

For an arc segment, we recover the coherence $L = ||\overrightarrow{AB}|| = AB$. For an arc of circle, we have $||\frac{dM}{d\theta}|| = R$ and $L = R(\theta_2 - \theta_1)$. A functional curve satisfies $||V(t)|| = \sqrt{1 + (f'(t))^2}$ and $L = \int_a^b \sqrt{1 + (f'(t))^2} dt$.

• Regular points

A regular point M(t) of a curve Γ satisfies the condition $\frac{dM}{dt}(t) \neq 0$. All the previous examples are composed only with regular points.

• Curvilinear abscissa

With the notations used previously, we define the curvilinear abscissa by the relation

 $s(t) = \int_{a}^{t} ||\frac{dM}{dt}(t)|| dt$. Then we have s(a) = 0, s(b) = L, the function $t \mapsto s(t)$ is derivable and $\frac{ds}{dt} = ||\frac{dM}{dt}(t)|| > 0$ if all the points are regular. Then this function is continuous and strictly increasing. It realizes a bijection from the interval [a, b] onto the interval [0, L]. Its reciprocal mapping $T: [0, L] \ni s \mapsto T(s) \in [a, b]$ gives the value of the parameter t when the value of the curvilinear absissa is known. Moreover, this reciprocal function $s \mapsto t = T(s)$ is derivable and we have the classical relation $\frac{dT}{ds} = \frac{1}{\frac{ds}{dt}} = \frac{1}{||\frac{dM}{dt}||}$.

Tangent vector

We use the intrinsic parametrization of the curve Γ by the curvilinear abscissa. We consider the composed map $[0, L] \ni s \longmapsto P(s) = (M_{\circ}T)(s) = M(T(s))$. Then its derivate

 $\tau(s) = \frac{dP}{ds} = \frac{dM}{dt} \frac{dT}{ds} = \frac{1}{\|\frac{dM}{dt}\|} \frac{dM}{dt}$ is a unitary vector: $\|\tau(s)\| = 1$. It is by definition the tangent vector to the curve Γ .

For the previous examples, we have $\tau(s) = \frac{1}{||\overrightarrow{AB}||} \overrightarrow{AB}$ for the line segment, $\tau(s) = (-\sin\theta, \cos\theta)$ for the arc of circle and $\tau(s) = \frac{1}{\sqrt{1+(f'(t))^2}} (1, f'(t))$ for a functional curve.

Normal vector

The normal vector n(s) is defined in these lectures as the result of a rotation of angle $-\frac{\pi}{2}$ on the tangent vector $\tau(s)$. We have the relation $n(s) = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \tau(s)$ and looking to the components: $n_x = \tau_y$, $n_y = -\tau_x$. Then the local basis $(n(s), \tau(s))$ is a direct orthonormal basis of the vector plane \mathbb{R}^2 .

For the arc of circle, we have $M(\theta) = (R \cos \theta, R \sin \theta)$ and the normal proposed in this section is simply given by $n = (\cos \theta, \sin \theta)$. We observe that it is pointing outside the disc of radius *R* centered at the origin.

APPLIED MATHEMATICS

Exercices

• Catenary curve

We recall some elements of hyperbolic trigonometry: $\cosh x = \frac{1}{2} (\exp(x) + \exp(-x))$ and $\sinh x = \frac{1}{2} (\exp(x) - \exp(-x))$.

a) Prove that for each real number x, we have $(\cosh x)^2 - (\sinh x)^2 = 1$.

b) Prove the following rules for the derivatives of hyperbolic cosine and hyperbolic sinus: $\frac{d}{dx} \cosh x = \sinh x$ and $\frac{d}{dx} \sinh x = \cosh x$.

We suppose given a > 0 and $X \ge 0$. A catenary curve has a cartesian equation given by the relation $y = a \cosh\left(\frac{x}{a}\right)$ in an orthonormal frame of reference.

c) Draw the catenary curve.

d) What is the length of the catenary curve between the points of abscissa x = 0 and x = X? $[L = a \sinh(\frac{X}{a})]$

• Length of an arch of parabola

We use hyperbolic cosine and hyperbolic sinus recalled in the previous exercice.

a) Show that the hyperbolic sinus map is continuous, strictly increasing, that $\sinh x$ approaches $+\infty$ [respectively $-\infty$] if x approaches $+\infty$ [respectively $-\infty$].

b) Deduce from the previous question that the hyperbolic sinus map is bijective from \mathbb{R} to \mathbb{R} . We denote by argsh the inverse function: $x = \operatorname{argshy}$ is equivalent to $y = \sinh x$.

c) What is the derivative of the function argsh?

d) Prove that we have $\operatorname{argsh} x = \log(x + \sqrt{1 + x^2})$.

We set $F(x) = \frac{1}{2} (\operatorname{argsh} x + x \sqrt{1 + x^2}).$

e) Show that the function F is derivable for $x \in \mathbb{R}$ and evaluate the derivative $\frac{dF}{dx}$.

We introduce a > 0 and the parabola of equation $y = \frac{x^2}{2a}$ in an orthonormal frame of reference. We suppose also given an abscissa $X \ge 0$.

f) Compute the lenght of an arc of this parabola between the ponts with abscissa x = 0 and x = X. We can explicit the result with the function *F* introduced previously. $[L = aF(\frac{X}{a})]$

• Length of a cycloid

A cycloid associated with a circle of radius R > 0 admits the following parametric representation $x(\theta) = R(\theta - \sin \theta), y(\theta) = R(1 - \cos \theta).$

a) Draw this curve for $0 \le \theta \le 2\pi$.

b) Express the element of length ds in terms of the variable θ and the infinitesimal d θ .

c) What is the length of the arch of cycloid between the points A corresponding to $\theta = 0$ and B associated with $\theta = 2\pi$? [8R]