

# Square Roots of Elliptic Systems

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October 3, 2012

# What is a Square Root of an Operator?

## Definition

A square root of  $A : D(A) \subseteq X \rightarrow X$  is an operator  $A^{\frac{1}{2}}$  such that

$$A^{\frac{1}{2}} A^{\frac{1}{2}} x = Ax, \quad \text{for all } x \in D(A).$$

## Example

- ▶ Important-Constants-Matrix on  $X = \mathbb{C}^2$

$$A = \begin{pmatrix} \pi & 0 \\ 0 & e \end{pmatrix}, \quad D(A) = \mathbb{C}^2, \quad A^{\frac{1}{2}} = \begin{pmatrix} \sqrt{\pi} & 0 \\ 0 & \sqrt{e} \end{pmatrix}, \quad D(A^{\frac{1}{2}}) = \mathbb{C}^2.$$

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$$-\Delta u = \mathcal{F}^{-1}(\xi \mapsto |\xi|^2 \mathcal{F}u(\xi)), \quad D(-\Delta) = H^2(\mathbb{R}^d)$$

$$(-\Delta)^{\frac{1}{2}} u = \mathcal{F}^{-1}(\xi \mapsto |\xi| \mathcal{F}u(\xi)), \quad D((- \Delta)^{\frac{1}{2}}) = H^1(\mathbb{R}^d).$$

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# Outline

- 1 Elliptic systems and their square root
- 2 Maximal parabolic regularity on distribution spaces



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## Guideline

“In non-smooth situations, the square root behaves much better than the operator itself.”

(Saying in applied analysis)

# Setup

Let

- ▶  $A$  an  $N \times N$  system

$$Au = \begin{pmatrix} -\sum_{\alpha,\beta=1}^d \sum_{k=1}^N \partial_\alpha (a_{\alpha,\beta}^{1,k} \partial_\beta u_k) \\ \vdots \\ -\sum_{\alpha,\beta=1}^d \sum_{k=1}^N \partial_\alpha (a_{\alpha,\beta}^{N,k} \partial_\beta u_k) \end{pmatrix} = -\sum_{\alpha,\beta=1}^d \partial_\alpha (a_{\alpha,\beta} \partial_\beta u)$$

of 2nd-order differential equations in divergence form.

- ▶  $a_{\alpha,\beta}^{m,k} \in L^\infty(\mathbb{R}^d; \mathbb{C})$ ,  $a_{\alpha,\beta} = (a_{\alpha,\beta}^{m,k})_{1 \leq m,k \leq N} \in L^\infty(\mathbb{R}^d; \mathbb{C}^{N \times N})$ .

We will

- ▶ realize  $A$  as an  $m$ -accretive operator on  $L^2(\mathbb{R}^d; \mathbb{C}^N)$ .
- ▶ impose ellipticity via a Gårding inequality.

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# Properties of $A$

## Theorem (Kato)

–  $A$  generates a bounded analytic contraction  $C_0$ -semigroup  $(e^{-tA})_{t \geq 0}$ .

## Consequences

- ▶  $A$  has a unique  $m$ -accretive square root  $A^{\frac{1}{2}}$  and

$$A^{\frac{1}{2}}u = \frac{1}{\sqrt{\pi}} \int_0^{\infty} \sqrt{t} e^{-tA} Au \frac{dt}{t}, \quad u \in D(A).$$

- ▶  $D(A)$  is a core for both,  $D(A^{\frac{1}{2}})$  and  $D(a)$ .

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What can be said about  $D(A^{\frac{1}{2}})$  ?

# The Kato Square Root Problem

Theorem (Auscher, Hofmann, Lacey, McIntosh, Tchamitchian '02)

*Kato was right, i.e.  $D(A^{\frac{1}{2}}) = D(a) = W^{1,2}(\mathbb{R}^d; \mathbb{C}^N)$  and moreover,*

$$\|A^{\frac{1}{2}}u\|_{L^2} \sim \|\nabla u\|_{L^2}, \quad u \in D(A^{\frac{1}{2}}).$$

Note that

- ▶ in general  $D(A) \neq W^{2,2}(\mathbb{R}^d; \mathbb{C}^N)$ , i.e.  $A^{\frac{1}{2}}$  has the expected regularity properties and  $A$  has not.
- ▶ the Riesz transform

$$\nabla A^{-\frac{1}{2}} : L^2(\mathbb{R}^d; \mathbb{C}^N) \rightarrow L^2(\mathbb{R}^d; \mathbb{C}^{dN})$$

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What happens for integrability exponents  $p \neq 2$ ?



# The Riesz Transform

Observe that

- ▶ for  $u \in D(A) \cap \text{Rg}(A)$

$$\begin{aligned}\nabla A^{-\frac{1}{2}} u &= \nabla A^{-\frac{1}{2}} A v = \nabla A^{\frac{1}{2}} v = \nabla \frac{1}{\sqrt{\pi}} \int_0^\infty \sqrt{t} e^{-tA} A v \frac{dt}{t} \\ &= \frac{1}{\sqrt{\pi}} \int_0^\infty \sqrt{t} \nabla e^{-tA} u \frac{dt}{t}\end{aligned}$$

- ▶  $(\sqrt{t} \nabla e^{-tA})_{t>0} \subseteq \mathcal{L}(L^2(\mathbb{R}^d; \mathbb{C}^N), L^2(\mathbb{R}^d; \mathbb{C}^{dN}))$  is bounded, thus the above integral singular.

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Obtain boundedness on  $L^p$ -spaces

- ▶ **via** Calderón-Zygmund-Type results due to Blunck-Kunstmann ( $p < 2$ ) and Auscher, Coulhon, Duong, Hofmann ( $p > 2$ )
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# The Main Result

## Theorem (Auscher '07)

*The sets*

$$\mathcal{I}(A) := \left\{ p \in (1, \infty) \mid \nabla A^{-\frac{1}{2}} \text{ is } L^p\text{-bounded} \right\},$$

$$\mathcal{N}(A) := \left\{ p \in [1, \infty] \mid (\sqrt{t} \nabla e^{-tA})_{t>0} \text{ is uniformly } L^p\text{-bounded} \right\}$$

*share the same interior. Moreover,*

$$\|A^{\frac{1}{2}} u\|_{L^p} \sim \|\nabla u\|_{L^p}, \quad u \in C_c^\infty(\mathbb{R}^d; \mathbb{C}^N)$$

*if, and only if  $p \in \mathcal{I}(A)$ .*

Note that

- ▶ this is the  $L^p$ -analogon of the solution to the Square Root Problem.
- ▶  $[\frac{2d}{d+2}, 2] \in \mathcal{I}(A)$  but  $\mathcal{I}(A) \neq (1, \infty)$  in general.

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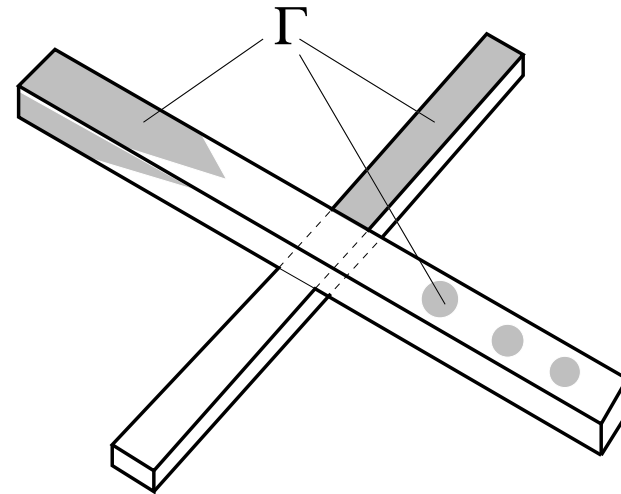
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# Elliptic Differential Equations on Rough Domains

Let

- ▶  $\Omega$  a bounded Lipschitz domain
- ▶  $\Gamma$  an open subset of  $\partial\Omega$
- ▶  $\mu \in \mathbb{R}^{d \times d}$  symmetric
- ▶  $J = (T_0, T)$  bounded.



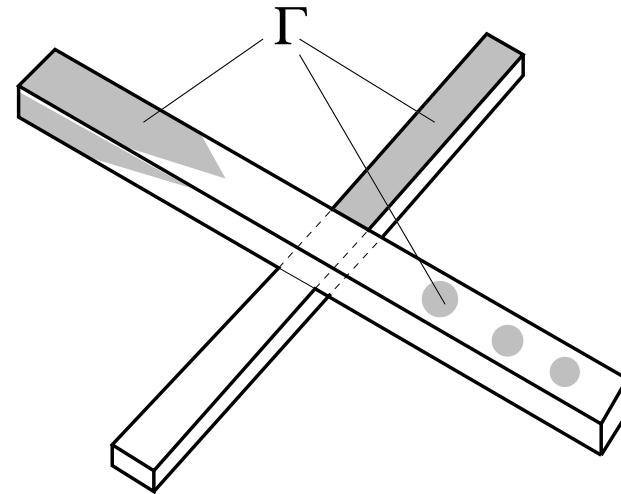
Consider

$$(PB) \quad \begin{cases} \frac{d}{dt}u(t)(x) - (\nabla \cdot \mu \nabla)u(t)(x) & = f(t)(x), & t \in J, x \in \Omega \\ u(t)(x) & = 0, & t \in J, x \in \partial\Omega \setminus \Gamma \\ \nu^t \mu \nabla u(t)(x) & = 0, & t \in J, x \in \Gamma \\ u(T_0)(x) & = 0, & x \in \Omega. \end{cases}$$

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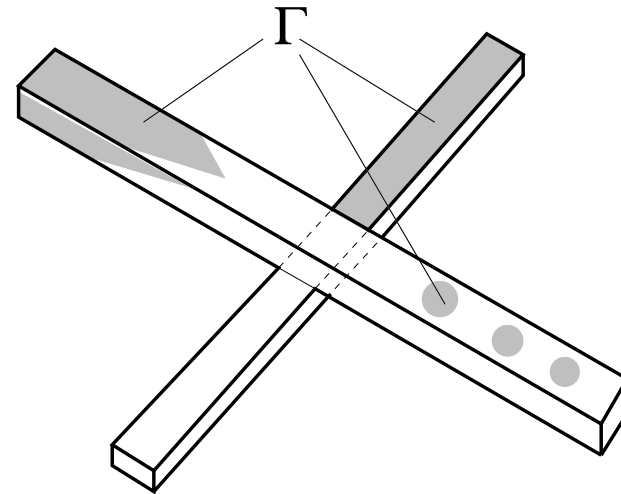
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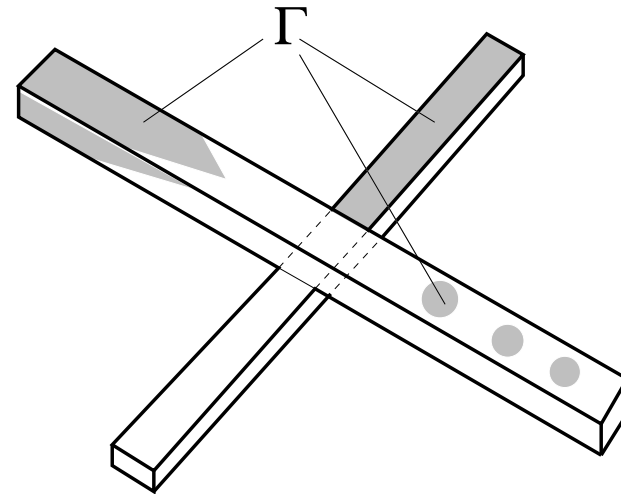
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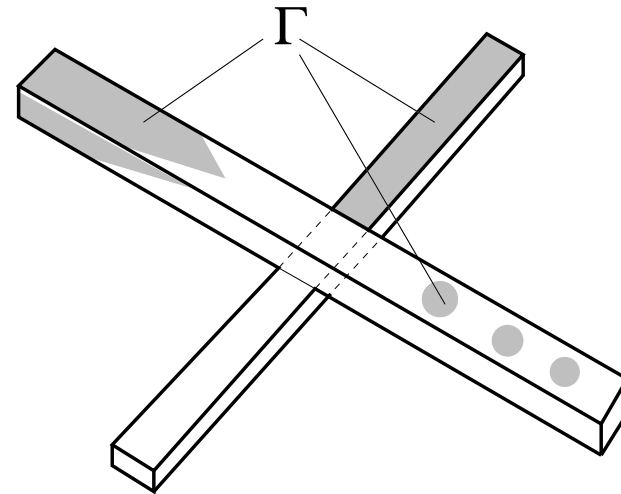
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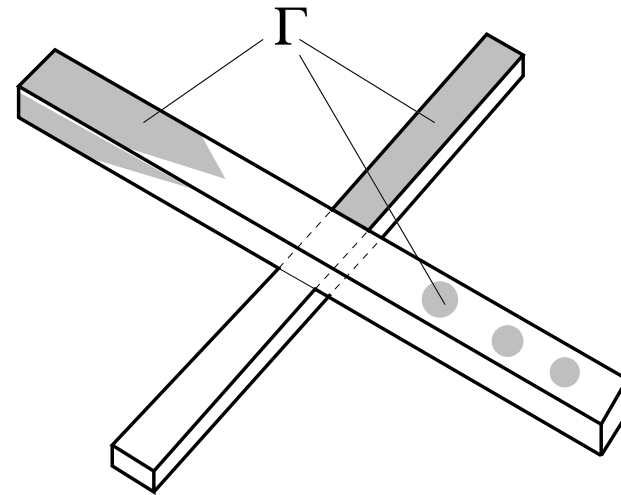
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- ▶ Incorporate **spatial boundary conditions** into definition of  $A_{W_\Gamma^{1,p}} := -(\nabla \cdot \mu \nabla) : D(A_{W_\Gamma^{1,p}}) \subseteq W_\Gamma^{1,p}(\Omega) \rightarrow L^p(\Omega)$ .

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Parabolic solution operator

$$\left(\frac{d}{dt} + A_{W_\Gamma^{1,p}}\right)^{-1} : L^s(J; L^p(\Omega)) \rightarrow W^{1,s}(J; L^p(\Omega)) \cap L^s(J; D(A_{W_\Gamma^{1,p}}))$$

- ▶ for  $p, s \in (1, \infty)$  well-defined and continuous.

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- ▶ for  $p, s \in (1, \infty)$  well-defined and continuous.



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As before,

$$(PB) \quad \begin{cases} \frac{d}{dt} u(t) + A_{W_\Gamma^{1,p}} u(t) & = f(t), & t \in J \\ u(T_0) & = 0 \end{cases}$$

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Can we carry over max. reg. from  $L^p$ - to  $W_\Gamma^{-1,p}$ -spaces?

# Maximal Parabolic Regularity on Distribution Spaces

## Idea

- ▶ Find isomorphism  $B : L^p(\Omega) \rightarrow W_\Gamma^{-1,p}(\Omega)$  that “suits”  
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Upcoming project: no self-adjointness, complex coefficients,  $N > 1$

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