# Model selection via penalization, resampling and cross-validation, with application to change-point detection

#### Sylvain Arlot

 $^{1}\mathrm{C}\mathrm{NRS}$ 

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- Model selection via penalization, with application to change-point detection
- Resampling methods for penalization, and robustness to heteroscedasticity in regression
- Cross-validation for model/estimator selection, with application to detecting changes in the mean of a signal



Regressograms 0000000	Shape of the penalty	Resampling 00000000000	Regressograms & resampling	Density 000	Conclusion

#### Part II

## Resampling methods for penalization, and robustness to heteroscedasticity in regression

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Outline					

- 1 Regressograms in heteroscedastic regression
- 2 The shape of the penalty must be estimated
- 3 Resampling
- 4 Theoretical guarantees for regressograms
- 5 Least-squares density estimation

#### 6 Conclusion

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Heteroscedastic regression framework

Regressograms

• Random design:  $(X_1, Y_1), \ldots, (X_n, Y_n) \in \mathcal{X} \times \mathbb{R}$  i.i.d.

 $Y_i = \eta(X_i) + \varepsilon_i$ 

 $\mathbb{E}\left[\varepsilon_{i} \mid X_{i}\right] = 0 \text{ and } \mathbb{E}\left[\varepsilon_{i}^{2} \mid X_{i}\right] = \sigma^{2}(X_{i})$ 

Heteroscedastic regression framework

• Random design:  $(X_1, Y_1), \ldots, (X_n, Y_n) \in \mathcal{X} \times \mathbb{R}$  i.i.d.

 $Y_i = \eta(X_i) + \varepsilon_i$  $\mathbb{E}\left[\varepsilon_i \mid X_i\right] = 0 \quad \text{and} \quad \mathbb{E}\left[\varepsilon_i^2 \mid X_i\right] = \sigma^2(X_i)$ 

Quadratic loss:

Regressograms

$$P\gamma(t) = \mathbb{E}_{(X,Y)\sim P}\left[\gamma(t;(X,Y))\right] = \mathbb{E}_{(X,Y)\sim P}\left\lfloor \left(t(X) - Y\right)^2 \right\rfloor$$

• Excess loss:  $\eta = s^*$  and

$$\ell(s^{\star},t) = P\gamma(t) - P\gamma(s^{\star}) = \mathbb{E}_{(X,Y)\sim P}\left[(s^{\star}(X) - t(X))^2\right]$$

Regressograms 0●00000	Shape of the penalty	Resampling 00000000000	Regressograms & resampling	Density 000	Conclusion
Regresso	grams				

For any finite partition m of  $\mathcal{X}$ 

$$S_m := \left\{ \sum_{\lambda \in m} \alpha_\lambda \mathbb{1}_\lambda \text{ s.t. } \alpha \in \mathbb{R}^m \right\}$$

 $\Rightarrow$  least-squares estimator over  $S_m$  (regressogram):

$$\widehat{s}_{m} \in \arg\min_{t \in S_{m}} \{P_{n}\gamma(t)\} = \arg\min_{t \in S_{m}} \left\{\frac{1}{n} \sum_{i=1}^{n} (Y_{i} - t(X_{i}))^{2}\right\}$$

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If for every  $\lambda \in m$ 

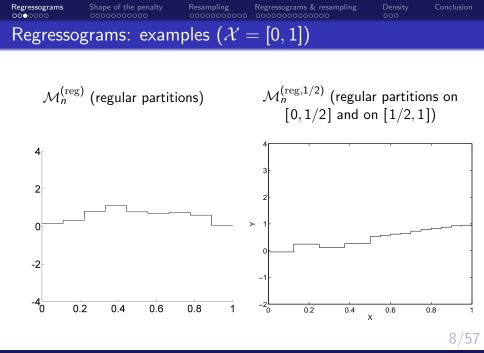
$$\widehat{p}_{\lambda} = \widehat{p}_{\lambda}(D_n) = \frac{1}{n} \operatorname{Card} \{ i \text{ s.t. } X_i \in \lambda \} > 0$$

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$$\widehat{s}_m = \sum_{\lambda \in m} \widehat{\beta}_{\lambda} \mathbb{1}_{\lambda} \qquad \widehat{\beta}_{\lambda} := \frac{1}{n \widehat{p}_{\lambda}} \sum_{i \text{ s.t. } X_i \in \lambda} Y_i$$



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Regressograms 0000000

Regressograms: bias, ideal penalty



0000000 Regressograms: bias, ideal penalty

Regressograms

$$s_{m}^{\star} = \sum_{\lambda \in m} \beta_{\lambda} \mathbb{1}_{\lambda} \qquad \beta_{\lambda} := \mathbb{E}_{(X,Y) \sim P} \left[ Y \mid X \in \lambda \right]$$
$$\ell\left(s^{\star}, s_{m}^{\star}\right) = \sum_{\lambda \in m} p_{\lambda} \left(\sigma_{\lambda}^{(d)}\right)^{2} \qquad \left(\sigma_{\lambda}^{(d)}\right)^{2} := \mathbb{E} \left[ \left(\beta_{\lambda} - s^{\star}(X)\right)^{2} \mid X \in \lambda \right]$$

Regressograms: bias, ideal penalty

Regressograms

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$$pen_{id}(m) = p_1(m) + p_2(m) - \delta(m)$$

$$p_1(m) = P\left(\gamma\left(\widehat{s}_m\right) - \gamma\left(s_m^{\star}\right)\right) = \sum_{\lambda \in m} p_\lambda \left(\widehat{\beta}_\lambda - \beta_\lambda\right)^2$$

$$p_2(m) = P_n\left(\gamma\left(s_m^{\star}\right) - \gamma\left(\widehat{s}_m\right)\right) = \sum_{\lambda \in m} \widehat{p}_\lambda \left(\widehat{\beta}_\lambda - \beta_\lambda\right)^2$$

$$\delta(m) = (P_n - P)\gamma\left(s_m^{\star}\right)$$

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Regressograms: conditional expectations

$$\mathcal{P}_m := (\mathbb{1}_{X_i \in \lambda})_{1 \le i \le n, \lambda \in m}$$

$$\mathbb{E}\left[p_1(m) \mid \mathcal{P}_m\right] = \frac{1}{n} \sum_{\lambda \in m} \frac{p_\lambda}{\widehat{p}_\lambda} \sigma_\lambda^2$$
$$\mathbb{E}\left[p_2(m) \mid \mathcal{P}_m\right] = \frac{1}{n} \sum_{\lambda \in m} \sigma_\lambda^2$$

$$\sigma_{\lambda}^{2} := \mathbb{E}_{(X,Y)\sim P} \left[ (Y - \beta_{\lambda})^{2} \middle| X \in \lambda \right] = \left( \sigma_{\lambda}^{(d)} \right)^{2} + \left( \sigma_{\lambda}^{(r)} \right)^{2} \\ \left( \sigma_{\lambda}^{(r)} \right)^{2} := \mathbb{E}_{(X,Y)\sim P} \left[ (\sigma(X))^{2} \middle| X \in \lambda \right]$$

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#### Regressograms: expectations

$$\mathbb{E}[p_1(m)] = \frac{1}{n} \sum_{\lambda \in m} \sigma_{\lambda}^2 (1 + \delta_{n, p_{\lambda}})$$
$$\mathbb{E}[p_2(m)] = \frac{1}{n} \sum_{\lambda \in m} \sigma_{\lambda}^2$$

$$\delta_{n,p_{\lambda}} := \mathbb{E}\left[\left. rac{p_{\lambda}}{\widehat{p}_{\lambda}} \right| \ \widehat{p}_{\lambda} > 0 
ight] - 1$$
  
 $-\exp(-np) \le \delta_{n,p} \le \min\left\{ 1 + rac{\kappa_1}{(np)^{1/4}} \ , \ \kappa_2 
ight\}$ 

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Regressograms: risk, expectation of the ideal penalty

$$\mathbb{E}\left[\ell\left(s^{\star},\widehat{s}_{m}\right)\right] = \sum_{\lambda \in m} p_{\lambda}\left(\sigma_{\lambda}^{(d)}\right)^{2} + \frac{1}{n} \sum_{\lambda \in m} \left(1 + \delta_{n,p_{\lambda}}\right) \sigma_{\lambda}^{2}$$

$$\mathbb{E}\left[\mathsf{pen}_{\mathrm{id}}(m)\right] = \frac{1}{n} \sum_{\lambda \in m} \left(2 + \delta_{n, p_{\lambda}}\right) \sigma_{\lambda}^{2}$$

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$$Y = s^{\star}(X) + \varepsilon \quad \text{with} \quad X \sim \mathcal{U}([0,1])$$
$$\mathbb{E}\left[\varepsilon^{2} \mid X\right] = \sigma(X) \quad \text{and} \quad \int_{0}^{1/2} (\sigma(x))^{2} dx \neq \int_{1/2}^{1} (\sigma(x))^{2} dx$$

$$m \in \mathcal{M}_n^{(\mathrm{reg},1/2)}$$
:  $D_{m,1}$  pieces on  $\begin{bmatrix} 0, \frac{1}{2} \end{bmatrix}$   
 $D_{m,2}$  pieces on  $\begin{bmatrix} \frac{1}{2}, 1 \end{bmatrix}$ 

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 $D_{m,2}$  pieces on  $\begin{bmatrix} \frac{1}{2}, 1 \end{bmatrix}$ 

$$\mathbb{E}\left[\mathsf{pen}_{\mathrm{id}}(m)\right] \approx \frac{4}{n} \left[ D_{m,1} \int_0^{1/2} (\sigma(x))^2 \, dx + D_{m,2} \int_{1/2}^1 (\sigma(x))^2 \, dx \right]$$

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Shape of the penalty Drawbacks of pen = pen $(D_m)$ : an example

$$Y = s^{\star}(X) + \varepsilon \quad \text{with} \quad X \sim \mathcal{U}([0,1])$$
$$\mathcal{L}(\varepsilon \mid X) = \mathcal{N}(0, \sigma(X)^2)$$
$$s^{\star}(X) = X \qquad \sigma(X) = \mathbb{1}_{X \le \frac{1}{2}} + \frac{1}{20}\mathbb{1}_{X > 1/2}$$
$$\mathbb{E}\left[\mathsf{pen}_{\mathrm{id}}(m)\right] \approx \frac{2}{n} \left[D_{m,1} + \frac{D_{m,2}}{400}\right]$$

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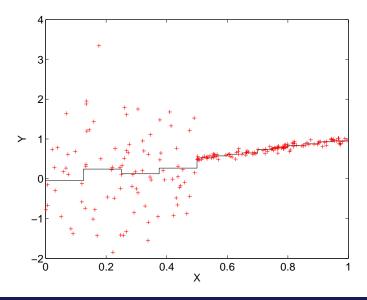
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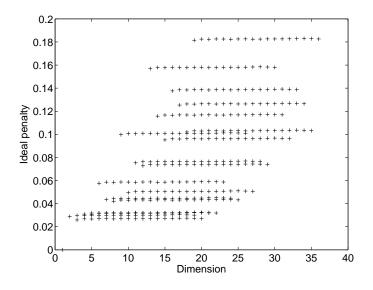
#### Example: data and oracle (n = 200)



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#### Example: $pen_{id}(m)$ as a function of $D_m$



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#### Penalties function of the dimension

#### Lemma

For any 
$$D \in \mathcal{D}_n = \{ D_m \text{ s.t. } m \in \mathcal{M}_n \}$$

$$\mathcal{M}_{\mathsf{dim}}(D) := \operatorname{argmin}_{m \in \mathcal{M}_n \, \mathrm{s.t.} \, D_m = D} \left\{ P_n \gamma\left(\widehat{s}_m\right) \right\}$$
  
 $\mathcal{M}_{\mathsf{dim}} := \bigcup_{D \in \mathcal{D}_n} \mathcal{M}_{\mathsf{dim}}(D)$ 

Then,  $\forall F : \mathcal{M}_n \mapsto \mathbb{R} \ \forall (X_i, Y_i)_{1 \leq i \leq n}$ 

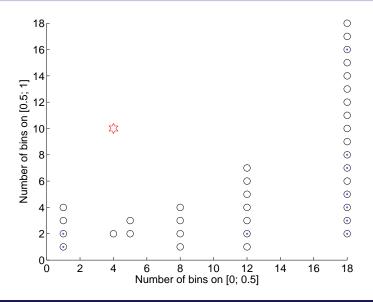
 $\operatorname{argmin}_{m \in \mathcal{M}_n} \left\{ P_n \gamma\left(\widehat{s}_m\right) + F(D_m) \right\} \subset \mathcal{M}_{\operatorname{dim}}$ 

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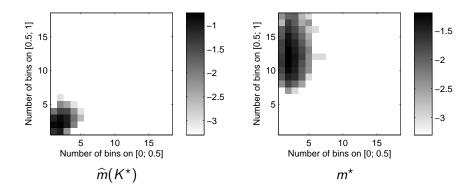
#### Models that can be selected with $pen(D_m)$



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Densities of  $(D_{\widehat{m}(D^*),1}, D_{\widehat{m}(D^*),2})$  and  $(D_{m^*,1}, D_{m^*,2})$  over N = 1000 samples



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Towards a proof: concentration of pen<sub>id</sub>

 $\text{Assumption:} \quad \left\| Y \right\|_{\infty} \leq A < \infty \quad \text{and} \quad \sigma(\cdot) \geq \sigma_{\min} > 0$ 

• Concentration of  $p_1$  and  $p_2$ :

if  $\min_{\lambda \in m} \{ np_{\lambda} \} \ge \Diamond \ln(n)$ , with probability at least  $1 - Ln^{-\gamma}$ , for i = 1, 2

$$|p_i(m) - \mathbb{E}\left[p_i(m)
ight]| \leq rac{L_{A,\sigma_{\min},\gamma}\left(\ln(n)
ight)^2}{\sqrt{D_m}}\mathbb{E}\left[p_2(m)
ight]$$

• Bernstein's inequality: with probability at least  $1 - 2e^{-x}$ ,

$$\forall \theta \in (0,1] \ , \ |(P_n - P)(\gamma(s_m^{\star}) - \gamma(s^{\star}))| \leq \theta \ell(s^{\star}, s_m^{\star}) + \frac{6A^2x}{\frac{\theta n}{21/57}}$$

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Heuristical proof: expectations

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$$\mathbb{E}[p_1(m)] \approx \mathbb{E}[p_2(m)] \approx \frac{\beta_1 D_{m,1}}{n} + \frac{\beta_2 D_{m,1}}{n}$$
$$\beta_1 = 2 \int_0^{1/2} \sigma^2 \qquad \beta_2 = 2 \int_{1/2}^1 \sigma^2$$

$$\ell\left(s^{\star}, s_{m}^{\star}\right) \approx \frac{\alpha_{1}}{D_{m,1}^{2}} + \frac{\alpha_{2}}{D_{m,2}^{2}}$$
$$\alpha_{1} = \frac{1}{48} \int_{0}^{1/2} \left(s^{\star\prime}\right)^{2} \qquad \alpha_{2} = \frac{1}{48} \int_{1/2}^{1} \left(s^{\star\prime}\right)^{2}$$

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#### Heuristical proof: expectations

$$\beta_1 = 2 \int_0^{1/2} \sigma^2 \qquad \beta_2 = 2 \int_{1/2}^1 \sigma^2$$
$$\alpha_1 = \frac{1}{48} \int_0^{1/2} (s^{\star\prime})^2 \qquad \alpha_2 = \frac{1}{48} \int_{1/2}^1 (s^{\star\prime})^2$$

$$P_{n}\gamma\left(\widehat{s}_{m}\right) - P\gamma\left(s^{\star}\right) \approx \frac{\alpha_{1}}{D_{m,1}^{2}} + \frac{\alpha_{2}}{D_{m,2}^{2}} - \frac{\beta_{1}D_{m,1}}{n} - \frac{\beta_{2}D_{m,1}}{n}$$
$$\ell\left(s^{\star}, \widehat{s}_{m}\right) \approx \frac{\alpha_{1}}{D_{m,1}^{2}} + \frac{\alpha_{2}}{D_{m,2}^{2}} + \frac{\beta_{1}D_{m,1}}{n} + \frac{\beta_{2}D_{m,1}}{n}$$

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#### Heuristical proof: expectations

$$\beta_1 = 2 \int_0^{1/2} \sigma^2 > \beta_2 = 2 \int_{1/2}^1 \sigma^2$$
$$\alpha_1 = \frac{1}{48} \int_0^{1/2} (s^{\star\prime})^2 \qquad \alpha_2 = \frac{1}{48} \int_{1/2}^1 (s^{\star\prime})^2$$

$$P_n\gamma\left(\hat{s}_m\right) - P\gamma\left(s^{\star}\right) \approx \frac{\alpha_1}{D_{m,1}^2} + \frac{\alpha_2}{D_{m,2}^2} - \frac{\beta_1 D_{m,1}}{n} - \frac{\beta_2 D_{m,1}}{n}$$
$$\ell\left(s^{\star}, \hat{s}_m\right) \approx \frac{\alpha_1}{D_{m,1}^2} + \frac{\alpha_2}{D_{m,2}^2} + \frac{\beta_1 D_{m,1}}{n} + \frac{\beta_2 D_{m,1}}{n}$$

$$m^{\star} \approx \left( \left( \frac{2\alpha_1 n}{\beta_1} \right)^{1/3} , \left( \frac{2\alpha_2 n}{\beta_2} \right)^{1/3} \right)$$

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### Drawbacks of pen = pen $(D_m)$ : theory

$$Y = s^{\star}(X) + \varepsilon \quad \text{with} \quad X \sim \mathcal{U}([0,1]) \quad , \qquad \mathbb{E}\left[\varepsilon^{2} \mid X\right] = \sigma(X)$$
  
and 
$$\sigma_{a}^{2} = \int_{0}^{1/2} (\sigma(x))^{2} dx \neq \int_{1/2}^{1} (\sigma(x))^{2} dx = \sigma_{b}^{2}$$

Regressograms & resampling

Density

#### Theorem (A. 2008)

Shape of the penalty

Regressograms

$$\begin{split} & If \ \mathcal{M} = \mathcal{M}_{n}^{(\mathrm{reg},1/2)}, \ under \ "reasonable" \ assumptions \ on \ (s^{\star},\varepsilon,\sigma), \\ & \exists \eta(\sigma_{a}^{2}/\sigma_{b}^{2}) > 0 \ such \ that \ with \ probability \ at \ least \\ & 1 - C(\|\varepsilon\|_{\infty}, \sigma_{a}^{2}, \sigma_{b}^{2}, \|s^{\star'}\|_{\infty}, \|s^{\star''}\|_{\infty})n^{-2} \\ & \forall F \ , \ \forall \widehat{m}_{F} \in \arg \ \min_{m \in \mathcal{M}_{n}} \{P_{n}\gamma(\widehat{s}_{m}) + F(D_{m})\} \ , \\ & \ell\left(s^{\star}, \widehat{s}_{\widehat{m}_{F}}\right) \geq \left(1 + \eta\left(\frac{\sigma_{a}^{2}}{\sigma_{b}^{2}}\right)\right) \inf_{m \in \mathcal{M}_{n}} \{\ell(s^{\star}, \widehat{s}_{m})\} \end{split}$$

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 Why should we estimate the shape of the penalty?

#### • $pen(D) = F(D) \Rightarrow loss of a factor <math>(1 + \eta) > 1$

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- $pen(D) = F(D) \Rightarrow loss of a factor <math>(1 + \eta) > 1$
- $pen(m) = 2\mathbb{E}\left[\sigma(X)^2\right] D_m/n \Rightarrow possible burst of the risk$

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- $pen(D) = F(D) \Rightarrow loss of a factor <math>(1 + \eta) > 1$
- $pen(m) = 2\mathbb{E}\left[\sigma(X)^2\right] D_m/n \Rightarrow possible burst of the risk$
- $pen(m) = 2 \|\sigma\|_{\infty}^2 D_m/n \Rightarrow \text{ oracle-inequality with constant}$  $\mathcal{O}(\max \sigma^2 / \min \sigma^2)$



- $pen(D) = F(D) \Rightarrow loss of a factor <math>(1 + \eta) > 1$
- $pen(m) = 2\mathbb{E}\left[\sigma(X)^2\right] D_m/n \Rightarrow possible burst of the risk$
- $pen(m) = 2 \|\sigma\|_{\infty}^2 D_m/n \Rightarrow$  oracle-inequality with constant  $\mathcal{O}(\max \sigma^2 / \min \sigma^2)$
- ⇒ must estimate  $\mathbb{E}[\text{pen}_{id}(m)]$  for an oracle inequality with constant (1 + o(1)) and for avoiding overfitting



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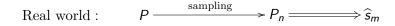
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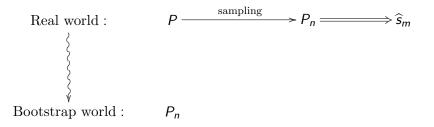




$$\operatorname{pen}_{\operatorname{id}}(m) = (P - P_n)\gamma(\widehat{s}_m) = F(P, P_n)$$

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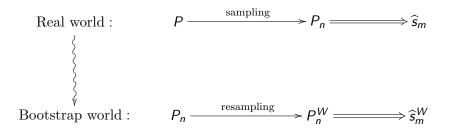


$$\operatorname{pen}_{\operatorname{id}}(m) = (P - P_n)\gamma(\widehat{s}_m) = F(P, P_n)$$

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$$(P - P_n)\gamma(\widehat{s}_m) = F(P, P_n) \longrightarrow F(P_n, P_n^W) = (P_n - P_n^W)\gamma(\widehat{s}_m^W)$$

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Exchangeable weighted resampling

$$P_n^W := \frac{1}{n} \sum_{i=1}^n W_i \delta_{\xi_i}$$

• Bootstrap:

$$W \sim \mathcal{M}\left(n; \frac{1}{n}, \ldots, \frac{1}{n}\right)$$

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# Exchangeable weighted resampling

$$P_n^W := \frac{1}{n} \sum_{i=1}^n W_i \delta_{\xi_i}$$

• Efron(*m*) or *m* out of *n* bootstrap:

$$\frac{m}{n}W \sim \mathcal{M}\left(m;\frac{1}{n},\ldots,\frac{1}{n}\right)$$

Exchangeable weighted resampling

$$P_n^W := \frac{1}{n} \sum_{i=1}^n W_i \delta_{\xi_i} \quad \text{or} \quad \frac{1}{\sum_k W_k} \sum_{i=1}^n W_i \delta_{\xi_i} = \frac{1}{n} \sum_{i=1}^n \frac{W_i}{\overline{W}} \delta_{\xi_i}$$

• Efron(m) or m out of n bootstrap:

$$\frac{m}{n}W \sim \mathcal{M}\left(m;\frac{1}{n},\ldots,\frac{1}{n}\right)$$

Subsampling:

• Random-hold out(q),  $q \in \{1, ..., n-1\}$ :

$$W_i = rac{n}{q} \mathbb{1}_{i \in I}$$
 with  $I \sim \mathcal{U}\left(\mathfrak{P}_q(\{1, \dots, n\})\right)$ 

• Rademacher(p) or Bernoulli:

$$pW_1,\ldots,pW_n$$
 i.i.d.  $\sim \mathcal{B}(p)$ 

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# Theoretical justification: asymptotics

Theorem (van der Vaart & Wellner, 1996)

Let  $(W_{n,1}, \ldots, W_{n,n}) \in \mathbb{R}^n$  be a non-negative random vector, exchangeable, independent from  $\xi_{1...n}$ , bounded and such that

$$n^{-1}\sum_{i=1}^{n} \left(W_{n,i} - \overline{W}_n\right)^2 \xrightarrow{(p)} c^2 > 0$$

Then, as n goes to infinity,

$$\sup_{h\in BL_1} \left| \mathbb{E}_W \left[ h\left( \sqrt{n} \left( P_n^W - \overline{W}_n P_n \right) \right) \right] - \mathbb{E} \left[ h\left( c \mathbb{G} \right) \right] \right| \xrightarrow{(p)} 0$$

where  $\mathbb{G}$  is a Gaussian process, limit of  $\sqrt{n(P_n - P)}$ , with zero mean and covariance function cov(f, g) = P(fg) - P(f)P(g).

### Classical uses of resampling

- estimating a variance, a quadratic risk
- estimation and/or bias correction
- confidence intervals, *p*-values
- estimation of prediction error, model selection
- stabilization (bagging, random forests)

• ...

Regressograms Shape of the penalty conclusion concerns the penalty c

### A resampling-based estimator of variance

Framework:

$$\xi_1, \ldots, \xi_n \text{ i.i.d. } \sim P \qquad \mathbb{E}\left[\xi_i\right] = \mu \quad \mathbb{E}\left[\left(\xi_i - \mu\right)^2\right] = \sigma^2$$

$$\sigma^{2} = n\mathbb{E}\left[\left(\frac{1}{n}\sum_{i=1}^{n}\xi_{i}-\mu\right)^{2}\right] = n\mathbb{E}\left[\left(\mathbb{E}_{\xi\sim P_{n}}\xi-\mathbb{E}_{\xi\sim P}\xi\right)^{2}\right]$$
$$= n\mathbb{E}\left[F(P,P_{n})\right]$$

 $\Rightarrow$  resampling-based estimator

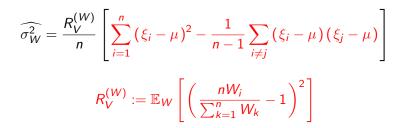
$$\widehat{\sigma_W^2} = n \mathbb{E}_W \left[ F(P_n, P_n^W) \right]$$

Model selection via penalization, resampling and cross-validation, with application to change-point detection

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#### A resampling-based estimator of variance

$$\widehat{\sigma_W^2} = n \mathbb{E}_W \left[ F(P_n, P_n^W) \right]$$



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Classical unbiased estimator of variance:

$$\widehat{\sigma^2} = \frac{1}{n-1} \sum_{i=1}^n \left( \xi_i - \frac{1}{n} \sum_{k=1}^n \xi_k \right)^2$$

Model selection via penalization, resampling and cross-validation, with application to change-point detection



Classical unbiased estimator of variance:

$$\widehat{\sigma^2} = \frac{1}{n-1} \sum_{i=1}^n \left( \xi_i - \frac{1}{n} \sum_{k=1}^n \xi_k \right)^2$$

$$\widehat{\sigma_W^2} = R_V^{(W)} \widehat{\sigma^2}$$
$$\Rightarrow \qquad \mathbb{E}\left[\widehat{\sigma_W^2}\right] = R_V^{(W)} \sigma^2$$

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Regressograms 0000000	Shape of the penalty	Resampling 000000000000000000000000000000000000	Regressograms & resampling	Density 000	Conclusion
Resampli	ng and struc	ture			

- Properties of  $F(P, P_n) = (\mathbb{E}_{\xi \sim P_n} \xi \mathbb{E}_{\xi \sim P} \xi)^2$ :
  - exchangeable
  - translation-invariance
  - homogeneity
  - polynomial function of  $\xi_i$  and  $\mathbb{E}_{\xi \sim P} \xi$
- $\Rightarrow \mathbb{E}_{W}[F(P_{n}, P_{n}^{W})]$  has similar properties

Regressograms 0000000	Shape of the penalty	Resampling 000000●0000	Regressograms & resampling	Density 000	Conclusion
Resampli	ng and struc	ture			

- Properties of  $F(P, P_n) = (\mathbb{E}_{\xi \sim P_n} \xi \mathbb{E}_{\xi \sim P} \xi)^2$ :
  - exchangeable
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  - homogeneity
  - polynomial function of  $\xi_i$  and  $\mathbb{E}_{\xi \sim P} \xi$
- $\Rightarrow \mathbb{E}_{W}[F(P_{n}, P_{n}^{W})]$  has similar properties

$$\Rightarrow \qquad \mathbb{E}_{W}\left[F(P_{n},P_{n}^{W})\right]\propto\widehat{\sigma^{2}}$$

 Regressograms
 Shape of the penalty
 Resampling
 Regressograms & resampling
 Density
 Conclusion

 Resampling and concentration
 Conclusion
 Conclusion

# Over-concentration phenomenon for the resampling-based estimator:

$$\operatorname{var}\left(n\left(\frac{1}{n}\sum_{i=1}^{n}\xi_{i}-\mu\right)^{2}\right)=2\sigma^{4}+\frac{\mathbb{E}\left[\left(\xi_{1}-\mu\right)^{4}\right]-3\sigma^{4}}{n}$$
$$\operatorname{var}\left(\frac{1}{R_{V}^{(W)}\widehat{\sigma_{W}^{2}}}\right)=\frac{1}{n}\left(\mathbb{E}\left[\left(\xi_{1}-\mu\right)^{4}\right]-\sigma^{4}\right)+\frac{2}{n(n-1)}\sigma^{4}$$

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Resampling 000000000000

## Computation of the multiplicative factor

$$R_V^{(W)} := \mathbb{E}_W \left[ \left( \frac{nW_i}{\sum_{k=1}^n W_k} - 1 \right)^2 \right]$$

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$$R_V^{(W)} := \mathbb{E}_W \left[ \left( \frac{nW_i}{\sum_{k=1}^n W_k} - 1 \right)^2 \right]$$

Efron(m):  
Rademacher(p):  
Random hold-out(q):  
Leave-one-out = Rho(n-1):  

$$R_V^{(W)} = \frac{n-1}{m}$$
  
 $R_V^{(W)} = \frac{1+\delta_{n,p}}{p} - 1 \approx \frac{1}{p} - 1$   
 $R_V^{(W)} = \frac{n}{q} - 1$   
 $R_V^{(W)} = \frac{1}{n-1}$ 

Model selection via penalization, resampling and cross-validation, with application to change-point detection

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• Ideal penalty:

$$(P-P_n)(\gamma(\widehat{s}_m))=F(P,P_n)$$

• Resampling-based estimator of  $\mathbb{E}[F(P, P_n)]$ :

$$\mathsf{pen}(m) = C_W \mathbb{E}\left[ (P_n - P_n^W)(\gamma(\widehat{s}_m^W)) \middle| (X_i, Y_i)_{1 \le i \le n} \right]$$

- bootstrap (Efron, 1983; Shibata, 1997), m out of n bootstrap for identification (Shao, 1996), general exchangeable weights (A. 2009)
- Multiplicative factor C<sub>W</sub>: why? how can we estimate it?

Regressograms 0000000	Shape of the penalty	Resampling ○○○○○○○○○●	Regressograms & resampling	Density 000	Conclusion
Rademac	her penalties				

• Global penalties:

$$\operatorname{\mathsf{pen}}_{\operatorname{id}}(m) \le \operatorname{\mathsf{pen}}_{\operatorname{id}}^{\operatorname{glo}}(m) = \sup_{t \in S_m} (P - P_n)\gamma(t)$$

 Regressograms
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 Rademacher penalties
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 Conclusion
 Conclusion

• Global penalties:

$$\operatorname{pen}_{\operatorname{id}}(m) \leq \operatorname{pen}_{\operatorname{id}}^{\operatorname{glo}}(m) = \sup_{t \in S_m} (P - P_n)\gamma(t)$$

• Global Rademacher penalties in classification (Koltchinskii & Panchenko, 2001; Bartlett, Boucheron & Lugosi, 2002), exchangeable weights (Fromont, 2004)

$$\mathbb{E}\left[\sup_{t\in S_m}\left\{\frac{1}{n}\sum_{i=1}^n\varepsilon_i\gamma(t;\xi_i)\right\}\middle|P_n\right]$$
  
with  $\varepsilon_1,\ldots,\varepsilon_n$  i.i.d.  $\sim \mathcal{U}(\{-1,+1\})$ 

• Local Rademacher complexities (Bartlett, Bousquet & Mendelson, 2004; Koltchinskii, 2006)

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Regressograms 0000000	Shape of the penalty	Resampling 00000000000	Regressograms & resampling	Density 000	Conclusion
Outline					

- Regressograms in heteroscedastic regression
- 2 The shape of the penalty must be estimated
- 3 Resampling
- 4 Theoretical guarantees for regressograms
- 5 Least-squares density estimation

#### 6 Conclusion

Regressograms 0000000	Shape of the penalty	Resampling 00000000000	Regressograms & resampling	Density 000	Conclusion
Reminde	r .				

$$\widehat{s}_{m} = \sum_{\lambda \in m} \widehat{\beta}_{\lambda} \mathbb{1}_{\lambda} \quad \text{with} \quad \widehat{\beta}_{\lambda} := \frac{1}{n \widehat{p}_{\lambda}} \sum_{i \text{ s.t. } X_{i} \in \lambda} Y_{i}$$
$$\widehat{p}_{\lambda} = \widehat{p}_{\lambda}(D_{n}) = \frac{1}{n} \operatorname{Card} \left\{ i \text{ s.t. } X_{i} \in \lambda \right\}$$

$$pen_{id}(m) = p_1(m) + p_2(m) - \delta(m)$$

$$p_1(m) = P\left(\gamma\left(\widehat{s}_m\right) - \gamma\left(s_m^{\star}\right)\right) = \sum_{\lambda \in m} \left[p_\lambda\left(\widehat{\beta}_\lambda - \beta_\lambda\right)^2\right]$$

$$p_2(m) = P_n\left(\gamma\left(s_m^{\star}\right) - \gamma\left(\widehat{s}_m\right)\right) = \sum_{\lambda \in m} \left[\widehat{p}_\lambda\left(\widehat{\beta}_\lambda - \beta_\lambda\right)^2\right]$$

$$\delta(m) = (P_n - P)\gamma\left(s_m^{\star}\right)$$

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### Resampling-based penalty

$$\mathsf{pen}_{W}(m) = \frac{C_{W}}{n} \sum_{\lambda \in m} \frac{R_{1,W} + R_{2,W}}{n \widehat{p}_{\lambda} - 1} \left( S_{\lambda,2} - \frac{1}{n \widehat{p}_{\lambda}} S_{\lambda,1}^{2} \right) \mathbb{1}_{n \widehat{p}_{\lambda} \ge 2}$$

with 
$$S_{\lambda,1} := \sum_{X_i \in \lambda} (Y_i - \beta_\lambda)$$
  $S_{\lambda,2} := \sum_{X_i \in \lambda} (Y_i - \beta_\lambda)^2$   
 $R_{1,W}(n, \widehat{p}_\lambda) := \mathbb{E} \left[ \frac{(W_1 - \widehat{W}_\lambda)^2}{\widehat{W}_\lambda^2} \middle| X_1 \in \lambda, \ \widehat{W}_\lambda > 0 \right]$   
and  $R_{2,W}(n, \widehat{p}_\lambda) := \mathbb{E} \left[ \frac{(W_1 - \widehat{W}_\lambda)^2}{\widehat{W}_\lambda} \middle| X_1 \in \lambda \right]$ 

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Resampling

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Value of  $R_1$  and  $R_2$ : examples

$${\it R}_{1,W}(n,\widehat{p}_{\lambda})\sim {\it R}_{2,W}(n,\widehat{p}_{\lambda})$$
 as  $n\widehat{p}_{\lambda}
ightarrow\infty$ 

$$C_{W,\infty}(n) := \lim_{n\widehat{p}_{\lambda} \to \infty} \frac{1}{R_{2,W}(n,\widehat{p}_{\lambda})}$$

Efron(m):  

$$R_{2,W}(n,\widehat{p}_{\lambda}) = \frac{n}{m} \left(1 - \frac{1}{n\widehat{p}_{\lambda}}\right) \quad C_{W,\infty} = \frac{m}{n}$$
Rademacher(p):  

$$R_{2,W}(n,\widehat{p}_{\lambda}) = \frac{1}{p} - 1 \qquad C_{W,\infty} = \frac{p}{1-p}$$
Random hold-out(q):  

$$R_{2,W}(n,\widehat{p}_{\lambda}) = \frac{n}{q} - 1 \qquad C_{W,\infty} = \frac{q}{n-q}$$
Leave-one-out:  

$$R_{2,W}(n,\widehat{p}_{\lambda}) = \frac{1}{n-1} \qquad C_{W,\infty} = n-1$$

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Regressograms 0000000	Shape of the penalty	Resampling 00000000000	Regressograms & resampling	Density 000	Conclusion
Expectat	ions				

$$\mathbb{E}\left[\left.Y_{i}-\beta_{\lambda}\right| \ X_{i}\in\lambda\right]=0 \quad \text{and} \quad \mathbb{E}\left[\left.\left(\left.Y_{i}-\beta_{\lambda}\right.\right)^{2}\right| \ X_{i}\in\lambda\right]=\sigma_{\lambda}^{2}\right]$$

$$\mathbb{E}\left[\mathsf{pen}_{W}(m) \mid \mathcal{P}_{m}\right] = \frac{C_{W}}{n} \sum_{\lambda \in m} \left(R_{1,W} + R_{2,W}\right) \sigma_{\lambda}^{2} \mathbb{1}_{n\widehat{p}_{\lambda} \geq 2}$$
$$\mathbb{E}\left[\mathsf{pen}_{W}(m)\right] = \frac{C_{W}}{C_{W,\infty}} \frac{1}{n} \sum_{\lambda \in m} \left(2 + \overline{\delta}_{n,p_{\lambda}}^{(\mathrm{penW})}\right) \sigma_{\lambda}^{2}$$

with  $\overline{\delta}_{n,p_{\lambda}}^{(\text{penW})} \rightarrow 0$  quand  $np_{\lambda} \rightarrow +\infty$  $\Rightarrow$  adaptation to heteroscedasticity

Model selection via penalization, resampling and cross-validation, with application to change-point detection

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Regressograms

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Regressograms & resampling

Density Concl

# Concentration

#### Proposition (A. 2009)

- Bounded data:  $\|Y_i\|_{\infty} \leq A < \infty$
- Lower-bounded noise:  $\sigma(X_i) \ge \sigma_{\min} > 0$
- $\mathcal{L}(W)$  among Efr(n), Rad(1/2), Rho(n/2), Loo

For every  $A_n \ge 2$ , with probability at least  $1 - L_1 n^{-\gamma}$ ,

$$pen_{W}(m) - \mathbb{E}\left[pen_{W}(m) \mid \mathcal{P}_{m}\right] | \mathbb{1}_{\min_{\lambda \in m} \{n\hat{p}_{\lambda}\} \ge A_{n}}$$
$$\leq \frac{C_{W}}{C_{W,\infty}} \frac{L_{2}(A/\sigma_{\min}, \gamma) \ln(n)}{\sqrt{A_{n}D_{m}}} \mathbb{E}\left[p_{2}(m)\right]$$

Model selection via penalization, resampling and cross-validation, with application to change-point detection

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#### Pathwise non-asymptotic oracle inequality

- $\mathcal{L}(W)$  among Efr(n), Rad(1/2), Rho(n/2), Loo
- $C_W \approx C_{W,\infty}$

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#### Pathwise non-asymptotic oracle inequality

- $\mathcal{L}(W)$  among Efr(n), Rad(1/2), Rho(n/2), Loo
- $C_W \approx C_{W,\infty}$
- $Card(\mathcal{M}_n) \leq C_{\mathcal{M}} n^{\alpha_{\mathcal{M}}}$
- Bounded data:  $\|Y_i\|_{\infty} \leq A < \infty$
- Lower-bounded noise:  $\sigma(X_i) \ge \sigma_{\min} > 0$

# Regressograms Shape of the penalty Resampling Regressograms & resampling Density 000000000 0000000000 0000000000 0000000000 0000000000 0000 Pathwise non-asymptotic oracle inequality 0000000000 0000000000 0000000000 0000000000

- $\mathcal{L}(W)$  among Efr(n), Rad(1/2), Rho(n/2), Loo
- $C_W \approx C_{W,\infty}$
- $Card(\mathcal{M}_n) \leq C_{\mathcal{M}} n^{\alpha_{\mathcal{M}}}$
- Bounded data:  $\|Y_i\|_{\infty} \leq A < \infty$
- Lower-bounded noise:  $\sigma(X_i) \ge \sigma_{\min} > 0$
- $s^{\star} \in \mathcal{H}(\alpha, R)$  non-constant
- Pre-selected models:  $\forall m \in \mathcal{M}$  ,  $\min_{\lambda \in m} n \widehat{p}_{\lambda} \geq 3$

# Pathwise non-asymptotic oracle inequality

Regressograms & resampling

Density

- $\mathcal{L}(W)$  among Efr(n), Rad(1/2), Rho(n/2), Loo
- $C_W \approx C_{W,\infty}$

Regressograms

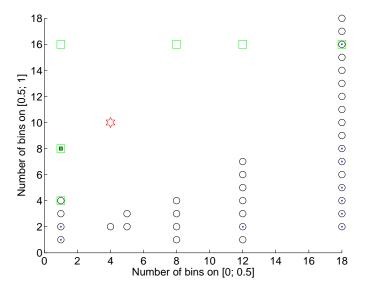
- $Card(\mathcal{M}_n) \leq C_{\mathcal{M}} n^{\alpha_{\mathcal{M}}}$
- Bounded data:  $\|Y_i\|_{\infty} \leq A < \infty$
- Lower-bounded noise:  $\sigma(X_i) \ge \sigma_{\min} > 0$
- $s^{\star} \in \mathcal{H}(\alpha, R)$  non-constant
- Pre-selected models:  $\forall m \in \mathcal{M}$  ,  $\min_{\lambda \in m} n \widehat{p}_{\lambda} \geq 3$

#### Theorem (A. 2009)

With probability at least  $1 - \Diamond n^{-2}$ ,

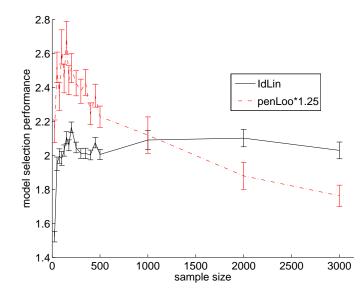
$$\ell(s^{\star}, \widehat{s}_{\widehat{m}}) \leq \left(1 + (\ln(n))^{-1/5}\right) \inf_{m \in \mathcal{M}} \left\{\ell(s^{\star}, \widehat{s}_{m})\right\}$$





Model selection via penalization, resampling and cross-validation, with application to change-point detection

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Model selection via penalization, resampling and cross-validation, with application to change-point detection

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Regressograms 0000000	Shape of the penalty	Resampling 00000000000	Regressograms & resampling	Density 000	Conclusion
Adaptatio	on				

 $\widetilde{s} := \widehat{s}_{\widehat{m}} \quad \text{with} \quad \widehat{m} \in \operatorname*{argmin}_{\substack{m \in \mathcal{M}_n^{(\text{reg})} \\ \min_{\lambda \in m} \{ n \widehat{p}_{\lambda} \} \ge 3}} \{ P_n \gamma (\widehat{s}_m) + \operatorname{pen}_W(m) \}$ 

Assumptions:

- Bounded data:  $\|Y_i\|_{\infty} \leq A < \infty$
- Lower-bounded noise:  $\sigma(X_i) \ge \sigma_{\min} > 0$
- Lower-bounded density of X:  $\forall I \subset \mathcal{X}$ ,  $\mathbb{P}(X \in I) \ge c_X^{\min} \operatorname{Leb}(I)$
- $s^{\star} = \eta \in \mathcal{H}(\alpha, R)$  with  $\alpha \in (0, 1]$ :

$$ert x_1, x_2 \in \mathcal{X} \hspace{0.2cm}, \hspace{0.2cm} |s^{\star}(x_1) - s^{\star}(x_2)| \leq R \, \|x_1 - x_2\|_{\infty}^{lpha}$$

Regressograms 0000000	Shape of the penalty	Resampling 00000000000	Regressograms & resampling	Density 000	Conclusion
Adaptatio	on				

$$\widetilde{s} := \widehat{s}_{\widehat{m}} \quad \text{with} \quad \widehat{m} \in \operatorname*{argmin}_{\substack{m \in \mathcal{M}_{n}^{(\text{reg})} \\ \min_{\lambda \in m} \{ n \widehat{p}_{\lambda} \} \ge 3}} \{ P_{n} \gamma \left( \widehat{s}_{m} \right) + \operatorname{pen}_{W}(m) \}$$

$$\mathbb{E}\left[\ell\left(s^{\star},\widetilde{s}\right)\right] \leq K_2 R^{\frac{2d}{2\alpha+d}} n^{\frac{-2\alpha}{2\alpha+d}} \left\|\sigma\right\|_{\infty}^{\frac{4\alpha}{2\alpha+d}} + \frac{K_3 A^2}{n^2}$$

Model selection via penalization, resampling and cross-validation, with application to change-point detection

Regressograms 0000000	Shape of the penalty	Resampling 00000000000	Regressograms & resampling	Density 000	Conclusion
Adaptati	on				

$$\widetilde{s} := \widehat{s}_{\widehat{m}} \quad \text{with} \quad \widehat{m} \in \operatorname*{argmin}_{\substack{m \in \mathcal{M}_{n}^{(\text{reg})} \\ \min_{\lambda \in m} \{ n \widehat{p}_{\lambda} \} \ge 3}} \{ P_{n} \gamma \left( \widehat{s}_{m} \right) + \operatorname{pen}_{W}(m) \}$$

$$\mathbb{E}\left[\ell\left(s^{\star},\widetilde{s}\right)\right] \leq K_2 R^{\frac{2d}{2\alpha+d}} n^{\frac{-2\alpha}{2\alpha+d}} \left\|\sigma\right\|_{\infty}^{\frac{4\alpha}{2\alpha+d}} + \frac{K_3 A^2}{n^2}$$

and if  $\sigma(\cdot)$  is  $K_{\sigma}$ -Lipschitz with at most  $J_{\sigma}$  jumps:

$$\mathbb{E}\left[\ell\left(s^{\star},\widetilde{s}\right)\right] \leq K_2 R^{\frac{2d}{2\alpha+d}} n^{\frac{-2\alpha}{2\alpha+d}} \left\|\sigma\right\|_{L^2(\mathsf{Leb})}^{\frac{4\alpha}{2\alpha+d}} + \frac{K_4 A^2}{n^2}$$

Model selection via penalization, resampling and cross-validation, with application to change-point detection

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Regressograms

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Resampling

Regressograms & resampling

Density Cond

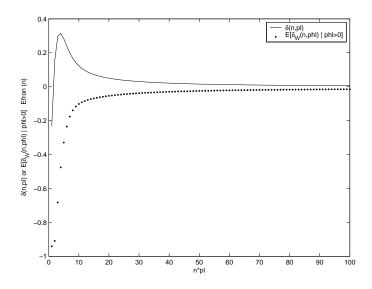
Theoretical comparison of weights: reminder

$$\mathbb{E}\left[\mathsf{pen}_{\mathrm{id}}(m)\right] = \frac{1}{n} \sum_{\lambda \in m} \left(2 + \delta_{n, p_{\lambda}}\right) \sigma_{\lambda}^{2}$$

and 
$$\mathbb{E}[\operatorname{pen}_W(m)] = \frac{1}{n} \sum_{\lambda \in m} \left(2 + \overline{\delta}_{n,\widehat{p}_{\lambda}}^{(\operatorname{pen}W)}\right) \sigma_{\lambda}^2$$

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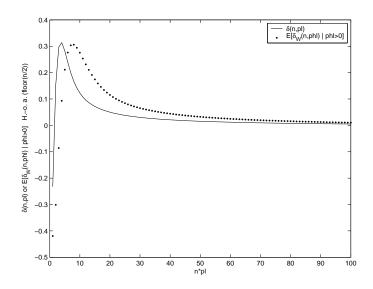
Model selection via penalization, resampling and cross-validation, with application to change-point detection



Model selection via penalization, resampling and cross-validation, with application to change-point detection

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Regressograms & resampling  $\overline{\varsigma}(\text{penW})$ vs.  $\delta_{n,p_{\lambda}}$ : Rho $(n/2) \approx \text{Rad}(1/2)$  $\delta$  $n, \widehat{p}_{\lambda}$ 

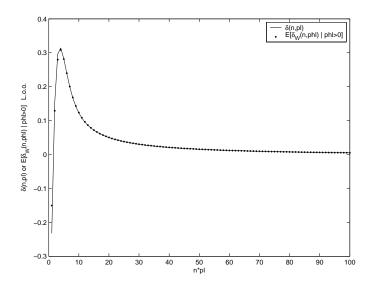


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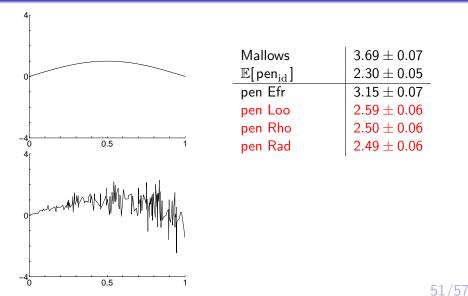
 $\overline{\delta}_{n,\widehat{\rho}_{\lambda}}^{(\text{penW})} \text{ vs. } \delta_{n,p_{\lambda}}: \ \text{Leave-one-out} \\ \hline \end{array} \\ \overline{\delta}_{n,\widehat{\rho}_{\lambda}}^{(\text{penW})} \text{ vs. } \delta_{n,p_{\lambda}}: \ begin{tabular}{c} & \text{Restrict} &$ 



Model selection via penalization, resampling and cross-validation, with application to change-point detection

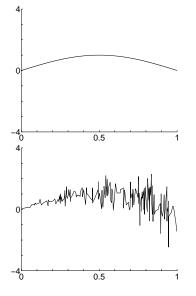
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Mallows	$3.69\pm0.07$
$\mathbb{E}[pen_{\mathrm{id}}]$	$2.30\pm0.05$
pen Efr	$3.15\pm0.07$
pen Loo	$2.59\pm0.06$
pen Rho	$2.50\pm0.06$
pen Rad	$2.49\pm0.06$
Mallows $\times 1.25$	$3.17\pm0.07$
$\mathbb{E}[pen_{\mathrm{id}}]  imes 1.25$	$2.03\pm0.04$
pen Efr $\times 1.25$	$2.60\pm0.06$
pen Loo $ imes$ 1.25	$2.22\pm0.05$
pen Rho $ imes$ 1.25	$2.14\pm0.05$
pen Rad $\times 1.25$	$2.14\pm0.05$

Model selection via penalization, resampling and cross-validation, with application to change-point detection

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Regressograms 0000000	Shape of the penalty	Resampling 00000000000	Regressograms & resampling	Density 000	Conclusion
Outline					

- Regressograms in heteroscedastic regression
- 2 The shape of the penalty must be estimated
- 3 Resampling
- 4 Theoretical guarantees for regressograms
- 5 Least-squares density estimation

#### 6 Conclusion

### Least-squares density estimation

- $\mu$  reference measure on  $\Xi$
- $f = dP/d\mu \in \mathbb{S} = L^2(\mu)$



Density •00

### Least-squares density estimation

- $\mu$  reference measure on  $\Xi$
- $f = dP/d\mu \in \mathbb{S} = L^2(\mu)$

• 
$$\gamma(t;\xi) = \|t\|_{L^{2}(\mu)}^{2} - 2t(\xi)$$
  
 $\Rightarrow P\gamma(t) = \|t\|_{L^{2}(\mu)}^{2} - 2\langle t, f \rangle_{L^{2}(\mu)}$   
 $\Rightarrow s^{\star} = f \text{ and } \ell(s^{\star}, t) = \|t - s^{\star}\|_{L^{2}(\mu)}^{2}$ 



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Regressograms & resampling

Density Concl

### Least-squares density estimation

- $\mu$  reference measure on  $\Xi$
- $f = dP/d\mu \in \mathbb{S} = L^2(\mu)$

• 
$$\gamma(t;\xi) = \|t\|_{L^{2}(\mu)}^{2} - 2t(\xi)$$
  
 $\Rightarrow P\gamma(t) = \|t\|_{L^{2}(\mu)}^{2} - 2\langle t, f \rangle_{L^{2}(\mu)}$   
 $\Rightarrow s^{\star} = f \text{ and } \ell(s^{\star}, t) = \|t - s^{\star}\|_{L^{2}(\mu)}^{2}$ 

•  $(\psi_{\lambda})_{\lambda \in m}$  orthonormal basis of  $S_m$  $\Rightarrow s_m^* = \sum_{\lambda \in m} (P\psi_{\lambda})\psi_{\lambda}$  and  $\widehat{s}_m = \sum_{\lambda \in m} (P_n\psi_{\lambda})\psi_{\lambda}$  Least-squares density estimation

Regressograms

- $\mu$  reference measure on  $\Xi$
- $f = dP/d\mu \in \mathbb{S} = L^2(\mu)$

• 
$$\gamma(t;\xi) = \|t\|_{L^{2}(\mu)}^{2} - 2t(\xi)$$
  
 $\Rightarrow P\gamma(t) = \|t\|_{L^{2}(\mu)}^{2} - 2\langle t, f \rangle_{L^{2}(\mu)}$   
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•  $(\psi_{\lambda})_{\lambda \in m}$  orthonormal basis of  $S_m$  $\Rightarrow s_m^* = \sum_{\lambda \in m} (P\psi_{\lambda})\psi_{\lambda}$  and  $\widehat{s}_m = \sum_{\lambda \in m} (P_n\psi_{\lambda})\psi_{\lambda}$ 

$$pen_{id}(m) = (P - P_n)\gamma(\widehat{s}_m) = 2(P_n - P)(\widehat{s}_m)$$
$$= 2 \|s_m^{\star} - \widehat{s}_m\|_{L^2(\mu)}^2 + 2(P_n - P)(s_m^{\star})$$

Regressograms & resampling

Density •00

Sylvain Arlot

Density Cond 0●0

## I.i.d. framework (Lerasle 2009)

$$\operatorname{pen}_{\operatorname{id}}(m) = 2(P_n - P)(\widehat{s}_m)$$

$$\mathsf{pen}_W(m) = \mathcal{C}_W \mathbb{E}_W \left[ 2(P_n^W - \overline{W} P_n)(\widehat{s}_m^W) 
ight]$$

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Shape of the penalty 00000000000 Resampling

Regressograms & resampling

Density Cor

I.i.d. framework (Lerasle 2009)

$$\mathsf{pen}_W(m) = \mathcal{C}_W \mathbb{E}_W \left[ 2(\mathcal{P}_n^W - \overline{W}\mathcal{P}_n)(\widehat{s}_m^W) 
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 $\Rightarrow$  pen<sub>W</sub>(m) only depends on W through a multiplicative factor

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Model selection via penalization, resampling and cross-validation, with application to change-point detection

Shape of the penalty 00000000000 Resampling

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I.i.d. framework (Lerasle 2009)

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 $\Rightarrow$  pen<sub>W</sub>(m) only depends on W through a multiplicative factor

- $\Rightarrow \mathbb{E}\left[\operatorname{pen}_{W}(m)\right] = C_{W}\operatorname{var}\left(W_{1} \overline{W}\right)\mathbb{E}\left[\operatorname{pen}_{\operatorname{id}}(m)\right]$
- + concentration of  $pen_W(m)$  around its expectation (faster than  $pen_{id}(m)$ )

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Shape of the penalty 00000000000 Resampling

Regressograms & resampling

Density Cor

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- + concentration of  $pen_W(m)$  around its expectation (faster than  $pen_{id}(m)$ )
- $\Rightarrow$  oracle inequality with constant 1 + o(1) under well-chosen assumptions on P and  $\mathcal{M}_n$

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hape of the penalty

Resampling

Regressograms & resampling

Density Conc

## Dependent case (Lerasle 2010)

- Mixing ( $\beta$  or  $\tau$ )
- Split the data into several blocks  $\Rightarrow$  keep one every two blocks
- Resample the blocks (which are almost independent)
- $\Rightarrow$  Oracle inequality (with an oracle only based on part of the original sample)

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Regressograms 0000000	Shape of the penalty	Resampling 00000000000	Regressograms & resampling	Density 000	Conclusion
Outline					

- Regressograms in heteroscedastic regression
- 2 The shape of the penalty must be estimated
- 3 Resampling
- 4 Theoretical guarantees for regressograms
- 5 Least-squares density estimation

### 6 Conclusion

# Limits of resampling

- Computational complexity
- $\Rightarrow$  alternative: non-exchangeable weights (e.g., V-fold)
  - Non-asymptotic results: can we have some without closed-form expressions?

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