- > restart:
- > with(DifferentialGeometry):
- > with(Tools):
- > DGsetup([z, y, u[1], u[2], u[3]], M, verbose);

The following coordinates have been protected:

$$[z, y, u_1, u_2, u_3]$$

The following vector fields have been defined and protected:

$$[D_z, D_y, D_u_1, D_u_2, D_u_3]$$

The following differential 1-forms have been defined and protected:

$$[dz, dy, du_1, du_2, du_3]$$

frame name: M (1)

>
$$L := evalDG(D_z + I \cdot y \cdot D_u[1] + I \cdot (2 \cdot z \cdot y + y^2) \cdot D_u_2 + I \cdot (3 \cdot z^2 \cdot y + 3 \cdot z \cdot y^2 + y^3) \cdot D_u_3);$$

 $L := D_z + I_y D_u_1 + I_y (2z + y) D_u_2 + I_y (3z^2 + 3zy + y^2) D_u_2$ (2)

$$L^{\#} := D_{y} - \operatorname{Iz} D_{u_{1}} - \operatorname{Iz} (2y + z) D_{u_{2}} - \operatorname{Iz} (3zy + 3y^{2} + z^{2}) D_{u_{3}}$$
(3)

 $M > T := evalDG(I \cdot LieBracket(L, L^{\#}));$

$$T := 2D \ u_1 + (4z + 4y) D \ u_2 + (6z^2 + 12zy + 6y^2) D \ u_3$$
 (4)

 $\mathbf{M} > S := LieBracket(L, T);$

$$S := 4 D_{u_2} + (12 z + 12 y) D_{u_3}$$
 (5)

 $\mathbf{M} > R := LieBracket(L, S);$

$$R := 12 D_{u_3}$$
 (6)

 $\mathbf{M} > Fr := FrameData([R, S, T, L, L^{\#}], N) :$

M > $DGsetup(Fr, [E], [tau[0], sigma[0], rho[0], zeta[0], <math>\zeta^{\#}[0]], verbose)$:

The following coordinates have been protected:

$$[z, y, u_1, u_2, u_3]$$

The following vector fields have been defined and protected:

The following differential 1-forms have been defined and protected:

$$\left[\tau_{0},\sigma_{0},\rho_{0},\zeta_{0},\zeta_{0}^{\sharp}\right] \tag{7}$$

N > ExteriorDerivative(tau[0]);

$$\sigma_0 \wedge \zeta_0 + \sigma_0 \wedge \zeta_0^{\sharp} \tag{8}$$

N > ExteriorDerivative(sigma[0]);

$$\rho_0 \wedge \zeta_0 + \rho_0 \wedge \zeta_0^{\sharp} \tag{9}$$

 $\mathbf{N} > ExteriorDerivative(zeta[0]);$

$$\theta \tau_0 \wedge \sigma_0$$
 (10)

$$\mathbf{N}$$
 > ExteriorDerivative $(\zeta^{\sharp}[0])$;

$$\theta \tau_0 \wedge \sigma_0$$
 (11)

N > ExteriorDerivative(rho[0]);

$$I\zeta_0 \wedge \zeta_0^{\sharp} \tag{12}$$

$$\begin{bmatrix}
\mathbf{N} > DualBasis([R, S, T, L, L^{\#}]); \\
\left[-\frac{1}{12} Iy^{3} dz + \frac{1}{12} Iz^{3} dy + \left(\frac{1}{4} z^{2} + \frac{1}{2} zy + \frac{1}{4} y^{2} \right) du_{1} + \left(-\frac{1}{4} z - \frac{1}{4} y \right) du_{2} \\
+ \frac{1}{12} du_{3}, \frac{1}{4} Iy^{2} dz - \frac{1}{4} Iz^{2} dy + \left(-\frac{1}{2} z - \frac{1}{2} y \right) du_{1} + \frac{1}{4} du_{2}, -\frac{1}{2} Iy dz + \frac{1}{2} Iz dy \\
+ \frac{1}{2} du_{1}, dz, dy
\end{bmatrix}$$

$$\begin{bmatrix}
\mathbf{M} > DualBasis([R, S, T, L, L^{\#}]); \\
+ \frac{1}{4} z^{2} dy + \left(-\frac{1}{4} z^{2} - \frac{1}{4} y^{2} \right) du_{1} + \left(-\frac{1}{4} z - \frac{1}{4} y^{2} \right) du_{2}$$

$$+ \frac{1}{4} du_{3}, \frac{1}{4} Iy^{2} dz - \frac{1}{4} Iz^{2} dy + \left(-\frac{1}{2} z - \frac{1}{2} y \right) du_{1} + \frac{1}{4} du_{2}, -\frac{1}{2} Iy dz + \frac{1}{2} Iz dy$$

$$\begin{bmatrix}
\mathbf{M} > \mathbf{M} > \mathbf{M} > \mathbf{M} & \mathbf{M} \\
\end{bmatrix}$$