> restart : > with(DifferentialGeometry) : > with(Tools) : with(LinearAlgebra) : > DGsetup([z, y, u[1], u[2]], [a, d, e], M, verbose);The following coordinates have been protected: $[z, y, u_1, u_2, a, d, e]$ The following vector fields have been defined and protected: $[D_z, D_y, D_u_1, D_u_2, D_a, D_d, D_e]$ The following differential 1-forms have been defined and protected: $[dz, dy, du_1, du_2, da, dd, de]$ frame name: M (1) > $g := Matrix([[a^3, 0, 0, 0], [0, a^2, 0, 0], [d, 0, a, 0], [e, 0, 0, a]]);$ $g := \left| \begin{array}{cccc} 0 & a^2 & 0 & 0 \\ d & 0 & a & 0 \\ & & & 2 & 0 & a \end{array} \right|$ (2) $\rightarrow h := MatrixInverse(g)$: > $A \coloneqq map(evalDG, (ExteriorDerivative(g).h));$ $A := \begin{bmatrix} \frac{3 \, da}{a} & 0 \, dz & 0 \, dz & 0 \, dz \\ 0 \, dz & \frac{2 \, da}{a} & 0 \, dz & 0 \, dz \\ -\frac{d \, da}{a^4} + \frac{dd}{a^3} & 0 \, dz & \frac{da}{a} & 0 \, dz \\ -\frac{e \, da}{a^4} + \frac{de}{a^3} & 0 \, dz & 0 \, dz & \frac{da}{a} \end{bmatrix}$ (3) $\begin{bmatrix} \mathbf{M} > t[1] \coloneqq \frac{da}{a} : \\ \mathbf{M} > t[2] \coloneqq -\frac{d \, da}{a^4} + \frac{dd}{a^3} : \\ \mathbf{M} > t[3] \coloneqq -\frac{e \, da}{a^4} + \frac{de}{a^3} : \end{aligned}$ $\begin{bmatrix} M > t[8] := \frac{1}{4} Iy^2 dz - \frac{1}{4} Iz^2 dy + \left(-\frac{1}{2} z - \frac{1}{2} y\right) du_1 + \frac{1}{4} du_2:$ **M** > $t[9] := -\frac{1}{2} Iy dz + \frac{1}{2} Iz dy + \frac{1}{2} du_1$: $\mathbf{M} > V \coloneqq Vector([t[8], t[9], dz, dy]):$ M > W := g.V:

M > FD := FrameData([t[1], t[2], t[3], W[1], W[2], W[3], W[4]], N): $M > DGsetup(FD, [E], [alpha[1], alpha[2], alpha[3], sigma, rho, zeta, <math>\zeta^{\#}$], verbose); The following coordinates have been protected: $[z, y, u_1, u_2, a, d, e]$ The following vector fields have been defined and protected: [*E1*, *E2*, *E3*, *E4*, *E5*, *E6*, *E7*] The following differential 1-forms have been defined and protected: $\left[\alpha_{1}, \alpha_{2}, \alpha_{3}, \sigma, \rho, \zeta, \zeta^{\#}\right]$ frame name: N (4) N > ExteriorDerivative(sigma); $3 \alpha_1 \wedge \sigma + \frac{(d+e) \sigma \wedge \rho}{\sigma^3} + \rho \wedge \zeta + \rho \wedge \zeta^{\sharp}$ (5) **N** > *ExteriorDerivative*(rho); $2\alpha_1 \wedge \rho + \frac{\mathrm{I}e\,\sigma\,\wedge\,\zeta}{\alpha^3} - \frac{\mathrm{I}d\,\sigma\,\wedge\,\zeta^{\sharp}}{\alpha^3} + \mathrm{I}\,\zeta\,\wedge\,\zeta^{\sharp}$ (6) **N** > *ExteriorDerivative*(zeta); $\alpha_1 \wedge \zeta + \alpha_2 \wedge \sigma + \frac{d(d+e) \sigma \wedge \rho}{a^6} + \frac{d\rho \wedge \zeta}{a^3} + \frac{d\rho \wedge \zeta^r}{a^3}$ (7) **N** > ExteriorDerivative $(\zeta^{\#})$; $\alpha_1 \wedge \zeta^{\sharp} + \alpha_3 \wedge \sigma + \frac{e(d+e)\sigma \wedge \rho}{a^6} + \frac{e\rho \wedge \zeta}{a^3} + \frac{e\rho \wedge \zeta^{\sharp}}{a^3}$ (8) n >