

> restart :
 > with(LinearAlgebra) :
 > with(DifferentialGeometry) : with(Tools) :
 > DGsetup([c, e, cl, el, z[1], z[2], w[1], w[2], v], M2, verbose);

The following coordinates have been protected:

$$[c, e, cl, el, z_1, z_2, w_1, w_2, v]$$

The following vector fields have been defined and protected:

$$[D_c, D_e, D_{cl}, D_{el}, D_{z_1}, D_{z_2}, D_{w_1}, D_{w_2}, D_v]$$

The following differential 1-forms have been defined and protected:

$$[dc, de, dcl, del, dz_1, dz_2, dw_1, dw_2, dv]$$

frame name: M2

(1)

> $q[1] := \frac{dc}{c} : q[2] := \frac{-Icl de - Ie dcl}{c cl} + \frac{I dc e}{c^2} : q[3] := \frac{dcl}{cl} : q[4]$
 $:= \frac{I el dc + I c del}{c cl} - \frac{I dcl el}{cl^2} :$

> $Q[1] := -\frac{1}{2} I c cl (w_1 + w_2 z_1) dz_1 + \frac{\frac{1}{4} I c cl (w_1^2 + 2 w_2 z_1 w_1 + z_1^2 w_2^2) dz_2}{-1 + z_2 w_2}$
 $+ \frac{1}{2} I c cl (z_1 + w_1 z_2) dw_1 - \frac{\frac{1}{4} I c cl (z_1^2 + 2 z_2 z_1 w_1 + w_1^2 z_2^2) dw_2}{-1 + z_2 w_2} + \frac{1}{2} c cl (-1$
 $+ z_2 w_2) dv :$

> $Q[2] := \left(c - \frac{1}{2} w_1 e cl - \frac{1}{2} e w_2 z_1 cl \right) dz_1$
 $+ \frac{1}{4} \frac{(-4 c w_1 - 4 c w_2 z_1 + e w_1^2 cl + 2 w_1 e w_2 z_1 cl + z_1^2 w_2^2 e cl) dz_2}{-1 + z_2 w_2} + \frac{1}{2} e cl (z_1$
 $+ w_1 z_2) dw_1 - \frac{1}{4} \frac{e cl (z_1^2 + 2 z_2 z_1 w_1 + w_1^2 z_2^2) dw_2}{-1 + z_2 w_2} - \frac{1}{2} I e cl (-1 + z_2 w_2) dv :$

> $Q[3] := \left(e - \frac{1}{4} \frac{e^2 cl w_1}{c} - \frac{1}{4} \frac{e^2 cl w_2 z_1}{c} \right) dz_1$
 $+ \frac{1}{4} \frac{1}{cl (-1 + z_2 w_2)} \left(\left(\frac{1}{2} \frac{e^2 cl^2 z_1^2 w_2^2}{c} - 4 e w_2 z_1 cl + \frac{e^2 cl^2 w_2 z_1 w_1}{c} + 4 c \right. \right.$
 $\left. \left. - 4 w_1 e cl + \frac{1}{2} \frac{e^2 cl^2 w_1^2}{c} \right) dz_2 \right) + \frac{1}{4} \frac{e^2 cl (z_1 + w_1 z_2) dw_1}{c}$
 $- \frac{1}{8} \frac{e^2 cl (z_1^2 + 2 z_2 z_1 w_1 + w_1^2 z_2^2) dw_2}{c (-1 + z_2 w_2)} - \frac{1}{4} \frac{I e^2 cl (-1 + z_2 w_2) dv}{c} :$

> $Q[4] := \frac{1}{2} el c (w_1 + w_2 z_1) dz_1 - \frac{1}{4} \frac{el c (w_1^2 + 2 w_2 z_1 w_1 + z_1^2 w_2^2) dz_2}{-1 + z_2 w_2} + \left(cl$

$$\begin{aligned}
& -\frac{1}{2} e l z_1 c - \frac{1}{2} e l w_1 z_2 c \Big) dw_1 \\
& -\frac{1}{4} \frac{(4 c l z_1 + 4 c l w_1 z_2 - e l c z_1^2 - 2 e l c z_2 z_1 w_1 - e l c w_1^2 z_2^2) dw_2}{-1 + z_2 w_2} + \frac{1}{2} I e l c (-1 \\
& + z_2 w_2) dv :
\end{aligned}$$

$$\begin{aligned}
> Q[5] := & \frac{1}{4} \frac{e l^2 c (w_1 + w_2 z_1) dz_1}{c l} - \frac{1}{8} \frac{e l^2 c (w_1^2 + 2 w_2 z_1 w_1 + z_1^2 w_2^2) dz_2}{c l (-1 + z_2 w_2)} + \left(e l \right. \\
& \left. - \frac{1}{4} \frac{e l^2 c z_1}{c l} - \frac{1}{4} \frac{e l^2 c w_1 z_2}{c l} \right) dw_1 \\
& - \frac{1}{4} \frac{1}{c (-1 + z_2 w_2)} \left(\left(-\frac{1}{2} \frac{e l^2 c^2 w_1^2 z_2^2}{c l} + 4 e l w_1 z_2 c - \frac{e l^2 c^2 z_2 z_1 w_1}{c l} - 4 c l \right. \right. \\
& \left. \left. + 4 e l z_1 c - \frac{1}{2} \frac{e l^2 c^2 z_1^2}{c l} \right) dw_2 \right) + \frac{1}{4} \frac{I e l^2 c (-1 + z_2 w_2) dv}{c l} :
\end{aligned}$$

> *Fr* := *FrameData*([*q*[1], *q*[2], *q*[3], *q*[4], *Q*[1], *Q*[2], *Q*[3], *Q*[4], *Q*[5]], *P*) :

M2 **>** *DGsetup*(*Fr*, [*E*], [*delta*[1], *delta*[2], *delta*[3], *delta*[4], *rho*, *kappa*, *zeta*, $\kappa^\#$, $\zeta^\#$]);
frame name: P (2)

M2 **>** *visualisation* := **proc** (*l*); *subs*({*w*[1] = *conjugate*(*z*[1]), *w*[2] = *conjugate*(*z*[2]),
*c*1 = *conjugate*(*c*), *e*1 = *conjugate*(*e*), $\kappa^\#$ = *conjugate*(*kappa*), $\zeta^\#$
= *conjugate*(*zeta*) }, *l*); **end proc**:

M2 **>** *visualisation*(*ExteriorDerivative*(*rho*));

$$\begin{aligned}
\delta_1 \wedge \rho + \delta_3 \wedge \rho - \frac{(-e \bar{c}^2 \bar{z}_2 + \bar{e} c^2) \rho \wedge \kappa}{\bar{c} c^2} - \frac{\bar{z}_2 \bar{c} \rho \wedge \zeta}{c} + \frac{(-e \bar{c}^2 + \bar{e} c^2 z_2) \rho \wedge \kappa^\#}{\bar{c}^2 c} \\
- \frac{z_2 c \rho \wedge \zeta^\#}{c} + I \kappa \wedge \kappa^\#
\end{aligned} \tag{3}$$

M2 **>** *visualisation*(*ExteriorDerivative*(*kappa*));

$$\begin{aligned}
\delta_1 \wedge \kappa + \delta_2 \wedge \rho - \frac{\frac{1}{2} I e^2 \bar{c} \bar{z}_2 \rho \wedge \kappa}{c^3} + \frac{I \bar{e} \rho \wedge \zeta}{c} - \frac{\frac{1}{2} I e (-e \bar{c}^2 + 2 \bar{e} c^2 z_2) \rho \wedge \kappa^\#}{\bar{c}^2 c^2} \\
+ \frac{I e z_2 \rho \wedge \zeta^\#}{c} - \frac{\bar{z}_2 \bar{c} \kappa \wedge \zeta}{c} + \zeta \wedge \kappa^\#
\end{aligned} \tag{4}$$

M2 **>** *visualisation*(*ExteriorDerivative*(*zeta*));

$$\begin{aligned}
\delta_1 \wedge \zeta + I \delta_2 \wedge \kappa - \delta_3 \wedge \zeta + \frac{\frac{1}{2} I e \bar{e} (-e \bar{c}^2 + \bar{e} c^2 z_2) \rho \wedge \kappa}{c^2 \bar{c}^3} \\
- \frac{\frac{1}{2} I (\bar{e}^2 z_2 c^4 + e^2 \bar{z}_2 \bar{c}^4 - 2 \bar{e} e c^2 \bar{c}^2) \rho \wedge \zeta}{c^3 \bar{c}^3} - \frac{\bar{c} e \bar{z}_2 \kappa \wedge \zeta}{c^2}
\end{aligned} \tag{5}$$

$$\begin{aligned}
& + \frac{1}{2} \frac{e(-e\bar{c}^2 + 2\bar{e}c^2z_2)}{c^2\bar{c}^2} \kappa \wedge \kappa^\# - \frac{ez_2 \kappa \wedge \zeta^\#}{c} - \frac{(-e\bar{c}^2 + \bar{e}c^2z_2) \zeta \wedge \kappa^\#}{\bar{c}^2c} \\
& + \frac{z_2c \zeta \wedge \zeta^\#}{c}
\end{aligned}$$

P > *visualisation*(*ExteriorDerivative*($\kappa^\#$));

$$\begin{aligned}
\delta_3 \wedge \kappa^\# + \delta_4 \wedge \rho - \frac{\frac{1}{2} I \bar{e} (-2e\bar{c}^2\bar{z}_2 + \bar{e}c^2) \rho \wedge \kappa}{c^2\bar{c}^2} - \frac{I \bar{e} \bar{z}_2 \rho \wedge \zeta}{c} + \frac{\frac{1}{2} I \bar{e}^2 z_2 c \rho \wedge \kappa^\#}{\bar{c}^3} \\
- \frac{I e \rho \wedge \zeta^\#}{c} - \kappa \wedge \zeta^\# - \frac{z_2 c \kappa^\# \wedge \zeta^\#}{c}
\end{aligned} \tag{6}$$

> *visualisation*(*ExteriorDerivative*($\zeta^\#$));

$$\begin{aligned}
-\delta_1 \wedge \zeta^\# + \delta_3 \wedge \zeta^\# - I \delta_4 \wedge \kappa^\# + \frac{\frac{1}{2} I \bar{e} e (-e\bar{c}^2\bar{z}_2 + \bar{e}c^2) \rho \wedge \kappa^\#}{\bar{c}^2c^3} \\
+ \frac{\frac{1}{2} I (\bar{e}^2 z_2 c^4 + e^2 \bar{z}_2 \bar{c}^4 - 2\bar{e} e c^2 \bar{c}^2) \rho \wedge \zeta^\#}{c^3 \bar{c}^3} + \frac{\frac{1}{2} \bar{e} (-2e\bar{c}^2\bar{z}_2 + \bar{e}c^2) \kappa \wedge \kappa^\#}{c^2 \bar{c}^2} \\
- \frac{(-e\bar{c}^2\bar{z}_2 + \bar{e}c^2) \kappa \wedge \zeta^\#}{\bar{c}^2} + \frac{\bar{e} \bar{z}_2 \zeta \wedge \kappa^\#}{c} - \frac{\bar{z}_2 \bar{c} \zeta \wedge \zeta^\#}{c} - \frac{\bar{e} z_2 c \kappa^\# \wedge \zeta^\#}{\bar{c}^2}
\end{aligned} \tag{7}$$

$$\begin{aligned}
\mathbf{P} > r[1] := \text{evalDG} \left(q[1] - \frac{\frac{1}{4} I (cl^4 e^2 w_2 - 2el e c^2 cl^2 + c^4 el^2 z_2)}{c^3 cl^3} \cdot Q[1] \right. \\
\left. + \frac{(-e cl^2 w_2 + el c^2)}{cl c^2} \cdot Q[2] + \frac{w[2] \cdot cl}{c} \cdot Q[3] \right);
\end{aligned}$$

$$\begin{aligned}
\mathbf{M2} > r[2] := \text{evalDG} \left(q[2] - I \cdot \frac{\frac{1}{2} I e e l (-e cl^2 + el c^2 z_2)}{c^2 cl^3} \cdot Q[1] - \left(-\frac{\frac{1}{2} I e^2 cl w_2}{c^3} \right. \right. \\
\left. \left. + \frac{\frac{1}{4} I (cl^4 e^2 w_2 - 2el e c^2 cl^2 + c^4 el^2 z_2)}{c^3 cl^3} \right) \cdot Q[2] - \frac{I \cdot el}{cl} \cdot Q[3] \right. \\
\left. + \frac{\frac{1}{2} I e (-e cl^2 + 2el c^2 z_2)}{c^2 cl^2} \cdot Q[4] - \frac{I e z_2}{cl} \cdot Q[5] \right);
\end{aligned}$$

$$\begin{aligned}
\mathbf{M2} > r[3] := \text{evalDG} \left(q[3] + \frac{\frac{1}{4} I (cl^4 e^2 w_2 - 2el e c^2 cl^2 + c^4 el^2 z_2)}{c^3 cl^3} \cdot Q[1] \right. \\
\left. - \frac{-e cl^2 + el c^2 z_2}{c cl^2} \cdot Q[4] + \frac{z_2 c}{cl} \cdot Q[5] \right);
\end{aligned}$$

$$\begin{aligned}
\mathbf{M2} > r[4] := \text{evalDG} \left(q[4] + I \cdot \frac{\frac{1}{2} I e l e (-e c l^2 w_2 + e l c^2)}{c l^2 c^3} \cdot Q[1] - \left(\frac{\frac{1}{2} I e l^2 c z_2}{c l^3} \right. \right. \\
& \left. \left. - \frac{\frac{1}{4} I (c l^4 e^2 w_2 - 2 e l e c^2 c l^2 + c^4 e l^2 z_2)}{c^3 c l^3} \right) \cdot Q[4] + \frac{I e}{c} \cdot Q[5] \right. \\
& \left. + \frac{\frac{1}{2} I e l (-2 e c l^2 w_2 + e l c^2)}{c l^2 c^2} \cdot Q[2] + \frac{I e l w_2}{c} \cdot Q[3] \right);
\end{aligned}$$

$\mathbf{M2} > \text{antivisualisation} := \mathbf{proc}(l); \text{subs}(\{ \text{conjugate}(z[1]) = w[1], \text{conjugate}(z[2]) = w[2], \text{conjugate}(c) = c l, \text{conjugate}(e) = e l, \}, l); \mathbf{end proc};$

$List := \text{GenerateForms}([\text{delta}[1], \text{delta}[2], \text{delta}[3], \text{delta}[4], \text{rho}, \text{kappa}, \text{zeta}, \kappa^\#, \zeta^\#], 2);$

$$\begin{aligned}
& [\delta_1 \wedge \delta_2, \delta_1 \wedge \delta_3, \delta_1 \wedge \delta_4, \delta_1 \wedge \rho, \delta_1 \wedge \kappa, \delta_1 \wedge \zeta, \delta_1 \wedge \kappa^\#, \delta_1 \wedge \zeta^\#, \delta_2 \wedge \delta_3, \delta_2 \wedge \delta_4, \delta_2 \wedge \rho, \\
& \delta_2 \wedge \kappa, \delta_2 \wedge \zeta, \delta_2 \wedge \kappa^\#, \delta_2 \wedge \zeta^\#, \delta_3 \wedge \delta_4, \delta_3 \wedge \rho, \delta_3 \wedge \kappa, \delta_3 \wedge \zeta, \delta_3 \wedge \kappa^\#, \delta_3 \wedge \zeta^\#, \delta_4 \wedge \rho, \\
& \delta_4 \wedge \kappa, \delta_4 \wedge \zeta, \delta_4 \wedge \kappa^\#, \delta_4 \wedge \zeta^\#, \rho \wedge \kappa, \rho \wedge \zeta, \rho \wedge \kappa^\#, \rho \wedge \zeta^\#, \kappa \wedge \zeta, \kappa \wedge \kappa^\#, \kappa \wedge \zeta^\#, \\
& \zeta \wedge \kappa^\#, \zeta \wedge \zeta^\#, \kappa^\# \wedge \zeta^\#]
\end{aligned} \tag{8}$$

$Torsion := \mathbf{proc}(S, i, j) \mathbf{local} k, X; k := 9 \cdot (i - 1) - \frac{i \cdot (i - 1)}{2} + j - i; X := \text{GetComponents}(S, List);$

$X[k]; \mathbf{end proc};$

$\text{result} := \mathbf{proc}(l) \mathbf{local} k, t, X; X := 0 : t := (\text{expand}(\text{simplify}(\text{GetComponents}(l, List)))) : \mathbf{for} k$
 $\mathbf{from} 1 \mathbf{to} 36 \mathbf{do} X := X + t[k] \cdot List[k] \mathbf{od}; X; \mathbf{end proc};$

$\mathbf{M2} > \text{ExteriorDerivative}(\text{rho});$

$$\begin{aligned}
& \delta_1 \wedge \rho + \delta_3 \wedge \rho - \frac{(-e c l^2 w_2 + e l c^2) \rho \wedge \kappa}{c l c^2} - \frac{w_2 c l \rho \wedge \zeta}{c} + \frac{(-e c l^2 + e l c^2 z_2) \rho \wedge \kappa^\#}{c l^2 c} \\
& - \frac{z_2 c \rho \wedge \zeta^\#}{c l} + I \kappa \wedge \kappa^\#
\end{aligned} \tag{9}$$

$\mathbf{P} > \text{visualisation}(\text{result}(\text{ExteriorDerivative}(\text{rho})));$

$$\begin{aligned}
& \delta_1 \wedge \rho + \delta_3 \wedge \rho + \left(\frac{\bar{c} e \bar{z}_2}{c^2} - \frac{\bar{e}}{c} \right) \rho \wedge \kappa - \frac{\bar{z}_2 \bar{c} \rho \wedge \zeta}{c} + \left(-\frac{e}{c} + \frac{\bar{e} z_2 c}{c^2} \right) \rho \wedge \kappa^\# \\
& - \frac{z_2 c \rho \wedge \zeta^\#}{c} + I \kappa \wedge \kappa^\#
\end{aligned} \tag{10}$$

$\mathbf{P} > \text{visualisation}(\text{result}(\text{ExteriorDerivative}(\text{kappa})));$

$$\begin{aligned}
& \delta_1 \wedge \kappa + \delta_2 \wedge \rho - \frac{\frac{1}{2} I e^2 \bar{c} \bar{z}_2 \rho \wedge \kappa}{c^3} + \frac{I \bar{e} \rho \wedge \zeta}{c} + \left(\frac{\frac{1}{2} I e^2}{c^2} - \frac{I e \bar{e} z_2}{c^2} \right) \rho \wedge \kappa^\# \\
& + \frac{I e z_2 \rho \wedge \zeta^\#}{c} - \frac{\bar{z}_2 \bar{c} \kappa \wedge \zeta}{c} + \zeta \wedge \kappa^\#
\end{aligned} \tag{11}$$

$\mathbf{P} > \text{visualisation}(\text{result}(\text{ExteriorDerivative}(\text{zeta})));$

$$\begin{aligned}
& \delta_1 \wedge \zeta + i\delta_2 \wedge \kappa - \delta_3 \wedge \zeta + \left(-\frac{1}{2} \frac{I e^2 \bar{e}}{c^2 \bar{c}} + \frac{1}{2} \frac{I e \bar{e}^2 z_2}{\bar{c}^3} \right) \rho \wedge \kappa + \left(-\frac{1}{2} \frac{I \bar{e}^2 z_2 c}{\bar{c}^3} \right. \\
& \quad \left. - \frac{1}{2} \frac{I e^2 \bar{c} \bar{z}_2}{c^3} + \frac{I \bar{e} e}{c \bar{c}} \right) \rho \wedge \zeta - \frac{\bar{c} e \bar{z}_2 \kappa \wedge \zeta}{c^2} + \left(-\frac{1}{2} \frac{e^2}{c^2} + \frac{e \bar{e} z_2}{\bar{c}^2} \right) \kappa \wedge \kappa^\# \\
& \quad - \frac{e z_2 \kappa \wedge \zeta^\#}{c} + \left(\frac{e}{c} - \frac{\bar{e} z_2 c}{\bar{c}^2} \right) \zeta \wedge \kappa^\# + \frac{z_2 c \zeta \wedge \zeta^\#}{c}
\end{aligned}$$

(12)

P >