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> restart :
> K :=proc(x) local y; y := op(1, x) : if (type(x, '+' ) = true) then add(K(op(i, x)), i = 1
  .. nops(x)) elif
      (type(x, '*' ) = true) then expand( K(y) ·  $\frac{x}{y}$  + y · K(  $\frac{x}{y}$  ) ) elif
      (type(x, '^' ) = true) then op(2, x) · y(op(2, x) - 1) · K(y) elif
      (type(x, function) = true) then Kfunction(x) elif
      (type(x, symbol) = true) then Ksymbol(x) else 0 fi end proc:
> Ksymbol :=proc(x); if x = k# then 0 elif x = P then (-L(k) · P - L(L(k))) elif x = P1 then (
  -L#(k) · P - L(L#(k)) - 2 · I · Tau(k)) else 'K'(x) fi end proc:
> recherche :=proc(x) local y; y := op(1, x); while (type(y, function) = true) do y := op(1, y)
  od; y; end proc:
> Kfunction :=proc(x) local y; y := recherche(x); if y = k then 'K'(x) else Kfunction1(x) fi
  end proc:

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> Kfunction1 :=proc(x) local y, J; if x = k# then 0 elif x = P then (-L(k) · P - L(L(k))) elif x
  = P1 then (-L#(k) · P - L(L#(k)) - 2 · I · Tau(k)) else J := op(0, x) : y := op(1, x) : if J
  = L then L(Kfunction1(y)) - 'L'(k) · L(y) elif
      J = L#
  then L#(Kfunction1(y)) - 'L#'(k) · L(y) elif
      J = K#
  then K#(Kfunction1(y)) elif J = Tau then Tau(Kfunction1(y)) - 'L'(k) · Tau(y) - 'Tau'(k)
  · L(y) fi fi end proc:
> L :=proc(x) local y; y := op(1, x) : if (type(x, '+' ) = true) then add(L(op(i, x)), i = 1
  .. nops(x)) elif
      (type(x, '*' ) = true) then expand( L(y) ·  $\frac{x}{y}$  + y · L(  $\frac{x}{y}$  ) ) elif
      (type(x, '^' ) = true) then op(2, x) · y(op(2, x) - 1) · L(y) elif
      (type(x, function) = true) then 'L'(x) elif
      (type(x, symbol) = true) then 'L'(x) else 0 fi end proc:

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> L# :=proc(x) local y; y := op(1, x) : if (type(x, '+' ) = true) then add(L#(op(i, x)), i = 1
  .. nops(x)) elif
      (type(x, '*' ) = true) then expand( L#(y) ·  $\frac{x}{y}$  + y · L#(  $\frac{x}{y}$  ) ) elif
      (type(x, '^' ) = true) then op(2, x) · y(op(2, x) - 1) · L#(y) elif
      (type(x, function) = true) then 'L#'(x) elif
      (type(x, symbol) = true) then 'L#'(x) else 0 fi end proc:
> Tau :=proc(x) local y; y := op(1, x) : if (type(x, '+' ) = true) then add(Tau(op(i, x)), i = 1
  .. nops(x)) elif
      (type(x, '*' ) = true) then expand( Tau(y) ·  $\frac{x}{y}$  + y · Tau(  $\frac{x}{y}$  ) ) elif
      (type(x, '^' ) = true) then op(2, x) · y(op(2, x) - 1) · Tau(y) elif
      (type(x, function) = true) then 'Tau'(x) elif
      (type(x, symbol) = true) then 'Tau'(x) else 0 fi end proc:

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>  $K^\# := \text{proc}(x) \text{ local } y; y := \text{op}(1, x) : \text{if } (\text{type}(x, \text{'+'}) = \text{true}) \text{ then } \text{add}(K^\#(\text{op}(i, x)), i = 1 \dots \text{nops}(x)) \text{ elif}$

$(\text{type}(x, \text{'*'}) = \text{true}) \text{ then } \text{expand}\left(K^\#(y) \cdot \frac{x}{y} + y \cdot K^\#\left(\frac{x}{y}\right)\right) \text{ elif}$

$(\text{type}(x, \text{'^'}) = \text{true}) \text{ then } \text{op}(2, x) \cdot y^{(\text{op}(2, x) - 1)} \cdot K^\#(y) \text{ elif}$

$(\text{type}(x, \text{function}) = \text{true}) \text{ then } K\text{function}^\#(x) \text{ elif}$

$(\text{type}(x, \text{symbol}) = \text{true}) \text{ then } K\text{symbol}^\#(x) \text{ else } 0 \text{ fi end proc:}$

>  $K\text{function}^\# := \text{proc}(x) \text{ local } y; y := \text{recherche}(x); \text{if } y = k^\# \text{ then } 'K^\#'(x) \text{ else } K\text{function}I^\#(x) \text{ fi end proc:}$

>  $K\text{function}I^\# := \text{proc}(x) \text{ local } y, J : \text{if } x = k \text{ then } 0 \text{ elif } x = P1 \text{ then } (-L^\#(k^\#) \cdot P1 - L^\#(L^\#(k^\#))) \text{ elif } x = P \text{ then } (-L(k^\#) \cdot P1 - L^\#(L(k^\#)) + 2 \cdot I \cdot \text{Tau}(k^\#)) \text{ else } J$

$:= \text{op}(0, x) : y := \text{op}(1, x) : \text{if } J = L \text{ then } L(K\text{function}I^\#(y)) - 'L(k^\#)'\cdot L^\#(y) \text{ elif}$

$J = L^\#$

$\text{then } L^\#(K\text{function}I^\#(y)) - 'L^\#'(k^\#) \cdot L^\#(y) \text{ elif}$

$J = K$

$\text{then } K(K\text{function}I^\#(y)) \text{ elif } J = \text{Tau} \text{ then } \text{Tau}(K\text{function}I^\#(y)) - 'L^\#(k^\#)'\cdot \text{Tau}(y) - 'L^\#(k^\#)'\cdot L^\#(y) \text{ fi fi end proc:}$

$K\text{symbol}^\# := \text{proc}(x); \text{if } x = k \text{ then } 0 \text{ elif } x = P1 \text{ then } (-L^\#(k^\#) \cdot P1 - L^\#(L^\#(k^\#))) \text{ elif } x = P$

$\text{then } (-L(k^\#) \cdot P1 - L^\#(L(k^\#)) + 2 \cdot I \cdot \text{Tau}(k^\#)) \text{ else } 'K^\#'(x) \text{ fi end proc:}$

>  $Der := \text{proc}(x) \text{ local } y; y := \text{op}(1, x) : \text{if } (\text{type}(x, \text{'+'}) = \text{true}) \text{ then } \text{add}(Der(\text{op}(i, x)), i = 1 \dots \text{nops}(x)) \text{ elif}$

$(\text{type}(x, \text{'*'}) = \text{true}) \text{ then } \text{expand}\left(\frac{x}{y} \cdot Der(y) + y \cdot Der\left(\frac{x}{y}\right)\right) \text{ elif}$

$(\text{type}(x, \text{'^'}) = \text{true}) \text{ then } \text{op}(2, x) \cdot y^{(\text{op}(2, x) - 1)} \cdot Der(y) \text{ elif}$

$( (\text{type}(x, \text{function}) = \text{true}) \text{ or } (\text{type}(x, \text{symbol}) = \text{true}) ) \text{ then } \text{Tau}(x) \cdot W[1] + L(x) \cdot W[2] + K(x) \cdot W[3] + L^\#(x) \cdot W[4] + K^\#(x) \cdot W[5]$

$\text{else } 0 \text{ fi end proc:}$

$\text{derivation} := \text{proc}(x) : \text{collect}(Der(x), [W[1], W[2], W[3], W[4], W[5]]) : \text{end proc:}$

>  $\text{with}(\text{DifferentialGeometry}) :$

>  $\text{with}(\text{Tools}) : \text{with}(\text{LinearAlgebra}) :$

>  $\text{DGsetup}([x, y, z, y1, z1], [b, b1, c, c1, d, d1, e, e1], M, \text{verbose});$

*The following coordinates have been protected:*

$[x, y, z, y1, z1, b, b1, c, c1, d, d1, e, e1]$

*The following vector fields have been defined and protected:*

$[D_x, D_y, D_z, D_y1, D_z1, D_b, D_b1, D_c, D_c1, D_d, D_d1, D_e, D_e1]$

*The following differential 1-forms have been defined and protected:*

$[dx, dy, dz, dy1, dz1, db, db1, dc, dc1, dd, dd1, de, de1]$

*frame name: M*

(1)

**M** >  $g := \text{Matrix}\left(\left[\left[ [c \cdot c1, 0, 0, 0, 0], [b, c, 0, 0, 0], \left[d, e, \frac{c}{c1}, 0, 0\right], [b1, 0, 0, c1, 0], [d1, 0,$

$$0, e1, \frac{c1}{c} \Big] \Big] \Big] \Big];$$

$$g := \begin{bmatrix} c1 & 0 & 0 & 0 & 0 \\ b & c & 0 & 0 & 0 \\ d & e & \frac{c}{c1} & 0 & 0 \\ b1 & 0 & 0 & c1 & 0 \\ d1 & 0 & 0 & e1 & \frac{c1}{c} \end{bmatrix}$$

(2)

$$\mathbf{M} > h := \text{MatrixInverse}(g) :$$

$$\mathbf{M} > A := \text{map}(\text{evalDG}, (\text{ExteriorDerivative}(g).h));$$

$$A := \left[ \left[ \frac{dc}{c} + \frac{dc1}{c1}, 0 dx, 0 dx, 0 dx, 0 dx \right], \right.$$

$$\left[ \frac{db}{c1} - \frac{b dc}{c^2 c1}, \frac{dc}{c}, 0 dx, 0 dx, 0 dx \right],$$

$$\left[ \frac{(-dc + eb) dc}{c^3 c1} - \frac{(-dc + eb) dc1}{c^2 c1^2} + \frac{dd}{c1} - \frac{b de}{c^2 c1}, -\frac{e dc}{c^2} + \frac{e dc1}{c1 c} + \frac{de}{c}, \frac{dc}{c} - \frac{dc1}{c1}, 0 dx, 0 dx \right],$$

$$\left[ \frac{db1}{c1} - \frac{b1 dc1}{c c1^2}, 0 dx, 0 dx, \frac{dc1}{c1}, 0 dx \right],$$

$$\left[ -\frac{(-d1 c1 + e1 b1) dc}{c1^2 c^2} + \frac{(-d1 c1 + e1 b1) dc1}{c1^3 c} + \frac{dd1}{c1} - \frac{b1 de1}{c c1^2}, 0 dx, 0 dx, \frac{e1 dc}{c c1} - \frac{e1 dc1}{c1^2} + \frac{de1}{c1}, -\frac{dc}{c} + \frac{dc1}{c1} \right] \Big] \Big] \Big] \Big]$$

(3)

$$\mathbf{M} > t[1] := \frac{dc}{c} :$$

$$\mathbf{M} > t[2] := \frac{db}{c1} - \frac{b dc}{c^2 c1} :$$

$$\mathbf{M} > t[3] := \frac{(-dc + eb) dc}{c^3 c1} - \frac{(-dc + eb) dc1}{c^2 c1^2} + \frac{dd}{c1} - \frac{b de}{c^2 c1} :$$

$$\mathbf{M} > t[4] := -\frac{e dc}{c^2} + \frac{e dc1}{c1 c} + \frac{de}{c} :$$

$$\mathbf{M} > t[5] := \frac{dc1}{c1} :$$

$$\mathbf{M} > t[6] := \frac{db1}{c1} - \frac{b1 dc1}{c c1^2} :$$

$$\mathbf{M} > t[7] := -\frac{(-d1 c1 + e1 b1) dc}{c1^2 c^2} + \frac{(-d1 c1 + e1 b1) dc1}{c1^3 c} + \frac{dd1}{c1} - \frac{b1 de1}{c c1^2} :$$

**M** >  $t[8] := \frac{e1\ dc}{c\ c1} - \frac{e1\ dc1}{c1^2} + \frac{de1}{c1} :$   
**M** >  $FD := \text{FrameData}([t[1], t[2], t[3], t[4], t[5], t[6], t[7], t[8], dx, dy, dz, dy1, dz1], N) :$   
**M** >  $DGsetup(FD, [E], [\text{alpha}[1], \text{alpha}[2], \text{alpha}[3], \text{alpha}[4], \alpha^\#[1], \alpha^\#[2], \alpha^\#[3], \alpha^\#[4], \text{rho}, \text{kappa}, \text{zeta}, \kappa^\#, \zeta^\#]) ;$   
*frame name: N* (4)

**N** >  $T := \text{Vector}([\text{rho}, \text{kappa}, \text{zeta}, \kappa^\#, \zeta^\#]) :$   
**N** >  $X := \text{Der}(L^\#(k)); XI := \text{Der}(L(k^\#)); XX := \text{subs}\left(\left\{W[3] = \frac{W[3]}{L^\#(k)}, W[5] = \frac{W[5]}{L(k^\#)}\right\}, X\right) ; XXI := \text{subs}\left(\left\{W[3] = \frac{W[3]}{L^\#(k)}, W[5] = \frac{W[5]}{L(k^\#)}\right\}, XI\right) ;$   
 $X := T(L^\#(k)) W_1 + L(L^\#(k)) W_2 + K(L^\#(k)) W_3 + L^\#(L^\#(k)) W_4 - L^\#(k^\#) L^\#(k) W_5$   
 $XI := T(L(k^\#)) W_1 + L(L(k^\#)) W_2 - L(k) L(k^\#) W_3 + L^\#(L(k^\#)) W_4 + K^\#(L(k^\#)) W_5$  (5)

**N** >  $W := h.T :$   
 $Eq1 := P \cdot (W[1] \wedge W[2]) - \frac{L(k)}{L^\#(k)} \cdot (W[1] \wedge W[3]) + P1 \cdot (W[1] \wedge W[4]) - \frac{L^\#(k^\#)}{L(k^\#)} \cdot (W[1] \wedge W[5]) + I \cdot (W[2] \wedge W[4]) :$

**N** >  $Eq2 := -\frac{L(k)}{L^\#(k)} \cdot (W[2] \wedge W[3]) + (W[3] \wedge W[4]) - \frac{\text{Tau}(k)}{L^\#(k)} \cdot (W[1] \wedge W[3]) :$

**N** >  $Eq3 := \left(\frac{XX}{L^\#(k)} \wedge W[3]\right) :$

**N** >  $Eq4 := -\frac{L^\#(k^\#)}{L(k^\#)} \cdot (W[4] \wedge W[5]) + (W[5] \wedge W[2]) - \frac{\text{Tau}(k^\#)}{L(k^\#)} \cdot (W[1] \wedge W[5]) :$

**N** >  $Eq5 := \left(\frac{XXI}{L(k^\#)} \wedge W[5]\right) :$

$\text{omega} := \text{Vector}([Eq1, Eq2, Eq3, Eq4, Eq5]) :$

$\text{Omega} := \text{map}(\text{evalDG}, g.\text{omega}) :$

**N** >  $A := \text{map}(\text{evalDG}, (\text{ExteriorDerivative}(g).h)) :$

$B := A \ \&\text{MatrixWedge} \ T :$

**N** >  $SE := \text{map}(\text{evalDG}, (B \ \&\text{MatrixPlus} \ \text{Omega})) :$

**N** >  $List := \text{GenerateForms}([\text{alpha}[1], \text{alpha}[2], \text{alpha}[3], \text{alpha}[4], \alpha^\#[1], \alpha^\#[2], \alpha^\#[3], \alpha^\#[4], \text{rho}, \text{kappa}, \text{zeta}, \kappa^\#, \zeta^\#], 2) :$

**N** >  $\text{result} := \text{proc}(l) \ \text{local} \ k, t, X; X := 0 : t := \text{expand}(\text{GetComponents}(l, List)) : \text{for} \ k \ \text{from} \ 1 \ \text{to} \ 78 \ \text{do} \ X := X + t[k] \cdot List[k] \ \text{od}; X; \text{end proc} :$

**N** >  $\text{Res1} := \text{result}(SE[1]) ;$

(6)

$$\begin{aligned}
\text{Res1} := & \alpha_1 \wedge \rho + \alpha_1^\# \wedge \rho + \left( \frac{\text{I}b l}{c c l} + \frac{c l L(k) e}{c^2 L^\#(k)} + \frac{P}{c} \right) \rho \wedge \kappa - \frac{L(k) c l \rho \wedge \zeta}{L^\#(k) c} + \left( -\frac{\text{I}b}{c c l} \right. \\
& \left. + \frac{c L^\#(k^\#) e l}{c l^2 L(k^\#)} + \frac{P l}{c l} \right) \rho \wedge \kappa^\# - \frac{L^\#(k^\#) c \rho \wedge \zeta^\#}{L(k^\#) c l} + \text{I} \kappa \wedge \kappa^\#
\end{aligned} \tag{6}$$

**N** >  $\text{Res2} := \text{result}(\text{SE}[2]);$

$$\begin{aligned}
\text{Res2} := & \alpha_1 \wedge \kappa + \alpha_2 \wedge \rho + \left( \frac{\text{T}(k) e}{c^2 L^\#(k)} - \frac{e b l}{c^2 c l} - \frac{L(k) d}{c^2 L^\#(k)} + \frac{\text{I}b b l}{c^2 c l^2} + \frac{L(k) e b}{c^3 L^\#(k)} \right. \\
& \left. + \frac{b P}{c^2 c l} \right) \rho \wedge \kappa + \left( -\frac{\text{T}(k)}{c L^\#(k)} + \frac{b l}{c c l} \right) \rho \wedge \zeta + \left( -\frac{d}{c c l} + \frac{e b}{c l c^2} - \frac{\text{I}b^2}{c^2 c l^2} \right. \\
& \left. + \frac{b L^\#(k^\#) e l}{c l^3 L(k^\#)} + \frac{b P l}{c c l^2} \right) \rho \wedge \kappa^\# - \frac{b L^\#(k^\#) \rho \wedge \zeta^\#}{L(k^\#) c l^2} - \frac{L(k) c l \kappa \wedge \zeta}{L^\#(k) c} + \left( -\frac{e}{c} \right. \\
& \left. + \frac{\text{I}b}{c c l} \right) \kappa \wedge \kappa^\# + \zeta \wedge \kappa^\#
\end{aligned} \tag{7}$$

**N** >  $\text{Res3} := \text{result}(\text{SE}[3]);$

$$\begin{aligned}
\text{Res3} := & \alpha_1 \wedge \zeta + \alpha_3 \wedge \rho + \alpha_4 \wedge \kappa - \alpha_1^\# \wedge \zeta + \left( \frac{L(L^\#(k)) d}{c l c^2 L^\#(k)} - \frac{e L^\#(k^\#) d l}{L(k^\#) c l^2 c} \right. \\
& \left. + \frac{e L^\#(k^\#) e l b l}{L(k^\#) c l^3 c} + \frac{e L^\#(L^\#(k)) b l}{c l^2 c^2 L^\#(k)} - \frac{e \text{T}(L^\#(k))}{c l c^2 L^\#(k)} + \frac{e^2 \text{T}(k)}{c^3 L^\#(k)} - \frac{e^2 b l}{c l c^3} + \frac{\text{I}d b l}{c l^2 c^2} \right. \\
& \left. + \frac{d P}{c l c^2} \right) \rho \wedge \kappa + \left( \frac{d l L^\#(k^\#)}{L(k^\#) c l^2} - \frac{e l L^\#(k^\#) b l}{L(k^\#) c l^3} - \frac{L^\#(L^\#(k)) b l}{c l^2 c L^\#(k)} - \frac{L(L^\#(k)) b}{c l c^2 L^\#(k)} \right. \\
& \left. + \frac{\text{T}(L^\#(k))}{c l c L^\#(k)} - \frac{\text{T}(k) e}{c^2 L^\#(k)} + \frac{e b l}{c^2 c l} + \frac{L(k) e b}{c^3 L^\#(k)} - \frac{L(k) d}{c^2 L^\#(k)} \right) \rho \wedge \zeta + \left( \frac{2 L^\#(k^\#) e l d}{L(k^\#) c l^3} \right. \\
& \left. - \frac{L^\#(k^\#) e l e b}{L(k^\#) c l^3 c} + \frac{L^\#(L^\#(k)) d}{c l^2 c L^\#(k)} - \frac{L^\#(L^\#(k)) e b}{c l^2 c^2 L^\#(k)} - \frac{e d}{c l c^2} + \frac{e^2 b}{c l c^3} - \frac{\text{I}d b}{c l^2 c^2} \right. \\
& \left. + \frac{d P l}{c l^2 c} \right) \rho \wedge \kappa^\# + \left( -\frac{2 L^\#(k^\#) d}{c l^2 L(k^\#)} + \frac{L^\#(k^\#) e b}{c l^2 L(k^\#) c} \right) \rho \wedge \zeta^\# + \left( \frac{L(L^\#(k))}{L^\#(k) c} \right. \\
& \left. - \frac{c l L(k) e}{c^2 L^\#(k)} \right) \kappa \wedge \zeta + \left( \frac{e L^\#(k^\#) e l}{L(k^\#) c l^2} + \frac{e L^\#(L^\#(k))}{L^\#(k) c l c} - \frac{e^2}{c^2} + \frac{\text{I}d}{c l c} \right) \kappa \wedge \kappa^\# \\
& - \frac{L^\#(k^\#) e \kappa \wedge \zeta^\#}{c l L(k^\#)} + \left( -\frac{c L^\#(k^\#) e l}{c l^2 L(k^\#)} - \frac{L^\#(L^\#(k))}{L^\#(k) c l} + \frac{e}{c} \right) \zeta \wedge \kappa^\# + \frac{L^\#(k^\#) c \zeta \wedge \zeta^\#}{L(k^\#) c l}
\end{aligned} \tag{8}$$

**N** >  $\text{Torsion} := \text{proc}(S, i, j) \text{ local } k, X; k := 13 \cdot (i - 1) - \frac{i \cdot (i - 1)}{2} + j - i; X$   
 $:= \text{GetComponents}(S, \text{List}); X[k]; \text{end proc};$

**N** >  $\text{eq} := \text{expand}(2 \cdot \text{Torsion}(\text{SE}[2], 10, 12) - \text{Torsion}(\text{SE}[3], 11, 12) - \text{Torsion}(\text{SE}[1], 9, 12));$

$$\text{eq} := -\frac{3 e}{c} + \frac{3 \text{I}b}{c c l} + \frac{L^\#(L^\#(k))}{L^\#(k) c l} - \frac{P l}{c l} \tag{9}$$

**N** >  $\text{Normalisation} := \text{expand}(\text{solve}(\text{eq}, b));$

$$Normalisation := -I e c I + \frac{\frac{1}{3} I L^\#(L^\#(k)) c}{L^\#(k)} - \frac{1}{3} I P I c \quad (10)$$

$$\mathbf{N} > g := \text{expand}\left(\frac{(Normalisation + I \cdot e \cdot c I)}{c}\right);$$

$$g := \frac{\frac{1}{3} I L^\#(L^\#(k))}{L^\#(k)} - \frac{1}{3} I P I \quad (11)$$