

> *restart* :  
 $K := \mathbf{proc}(x) \mathbf{local} y; y := \mathit{op}(1, x) : \mathbf{if} (\mathit{type}(x, \text{'+'}) = \mathit{true}) \mathbf{then} \mathit{add}(K(\mathit{op}(i, x)), i = 1$   
 $\dots \mathit{nops}(x)) \mathbf{elif}$

$(\mathit{type}(x, \text{'*'}) = \mathit{true}) \mathbf{then} \mathit{expand}\left(K(y) \cdot \frac{x}{y} + y \cdot K\left(\frac{x}{y}\right)\right) \mathbf{elif}$

$(\mathit{type}(x, \text{'^'}) = \mathit{true}) \mathbf{then} \mathit{op}(2, x) \cdot y^{(\mathit{op}(2, x) - 1)} \cdot K(y) \mathbf{elif}$

$(\mathit{type}(x, \mathit{function}) = \mathit{true}) \mathbf{then} K\mathit{function}(x) \mathbf{elif}$

$(\mathit{type}(x, \mathit{symbol}) = \mathit{true}) \mathbf{then} K\mathit{symbol}(x) \mathbf{else} 0 \mathbf{fi} \mathbf{end} \mathbf{proc}:$

>  $K\mathit{symbol} := \mathbf{proc}(x); \mathbf{if} x = k^\# \mathbf{then} 0 \mathbf{elif} x = P \mathbf{then} (-L(k) \cdot P - L(L(k))) \mathbf{elif} x = P1 \mathbf{then} (-L^\#(k) \cdot P - L(L^\#(k)) - 2 \cdot I \cdot \mathit{Tau}(k)) \mathbf{else} 'K'(x) \mathbf{fi} \mathbf{end} \mathbf{proc}:$

>  $\mathit{recherche} := \mathbf{proc}(x) \mathbf{local} y; y := \mathit{op}(1, x); \mathbf{while} (\mathit{type}(y, \mathit{function}) = \mathit{true}) \mathbf{do} y := \mathit{op}(1, y) \mathbf{od}; y; \mathbf{end} \mathbf{proc}:$

>  $K\mathit{function} := \mathbf{proc}(x) \mathbf{local} y; y := \mathit{recherche}(x); \mathbf{if} y = k \mathbf{then} 'K'(x) \mathbf{else} K\mathit{function}1(x) \mathbf{fi} \mathbf{end} \mathbf{proc}:$

>  $K\mathit{function}1 := \mathbf{proc}(x) \mathbf{local} y, J; \mathbf{if} x = k^\# \mathbf{then} 0 \mathbf{elif} x = P \mathbf{then} (-L(k) \cdot P - L(L(k))) \mathbf{elif} x = P1 \mathbf{then} (-L^\#(k) \cdot P - L(L^\#(k)) - 2 \cdot I \cdot \mathit{Tau}(k)) \mathbf{else} J := \mathit{op}(0, x) : y := \mathit{op}(1, x) : \mathbf{if} J = L \mathbf{then} L(K\mathit{function}1(y)) - 'L(k)' \cdot L(y) \mathbf{elif}$

$J = L^\#$

$\mathbf{then} L^\#(K\mathit{function}1(y)) - 'L^\#(k)' \cdot L(y) \mathbf{elif}$

$J = K^\#$

$\mathbf{then} K^\#(K\mathit{function}1(y)) \mathbf{elif} J = \mathit{Tau} \mathbf{then} \mathit{Tau}(K\mathit{function}1(y)) - 'L(k)' \cdot \mathit{Tau}(y) - '\mathit{Tau}(k)' \cdot L(y) \mathbf{fi} \mathbf{fi} \mathbf{end} \mathbf{proc}:$

>  $L := \mathbf{proc}(x) \mathbf{local} y; y := \mathit{op}(1, x) : \mathbf{if} (\mathit{type}(x, \text{'+'}) = \mathit{true}) \mathbf{then} \mathit{add}(L(\mathit{op}(i, x)), i = 1$   
 $\dots \mathit{nops}(x)) \mathbf{elif}$

$(\mathit{type}(x, \text{'*'}) = \mathit{true}) \mathbf{then} \mathit{expand}\left(L(y) \cdot \frac{x}{y} + y \cdot L\left(\frac{x}{y}\right)\right) \mathbf{elif}$

$(\mathit{type}(x, \text{'^'}) = \mathit{true}) \mathbf{then} \mathit{op}(2, x) \cdot y^{(\mathit{op}(2, x) - 1)} \cdot L(y) \mathbf{elif}$

$(\mathit{type}(x, \mathit{function}) = \mathit{true}) \mathbf{then} 'L'(x) \mathbf{elif}$

$(\mathit{type}(x, \mathit{symbol}) = \mathit{true}) \mathbf{then} 'L'(x) \mathbf{else} 0 \mathbf{fi} \mathbf{end} \mathbf{proc}:$

>  $L^\# := \mathbf{proc}(x) \mathbf{local} y; y := \mathit{op}(1, x) : \mathbf{if} (\mathit{type}(x, \text{'+'}) = \mathit{true}) \mathbf{then} \mathit{add}(L^\#(\mathit{op}(i, x)), i = 1$   
 $\dots \mathit{nops}(x)) \mathbf{elif}$

$(\mathit{type}(x, \text{'*'}) = \mathit{true}) \mathbf{then} \mathit{expand}\left(L^\#(y) \cdot \frac{x}{y} + y \cdot L^\#\left(\frac{x}{y}\right)\right) \mathbf{elif}$

$(\mathit{type}(x, \text{'^'}) = \mathit{true}) \mathbf{then} \mathit{op}(2, x) \cdot y^{(\mathit{op}(2, x) - 1)} \cdot L^\#(y) \mathbf{elif}$

$(\mathit{type}(x, \mathit{function}) = \mathit{true}) \mathbf{then} 'L^\#(x)' \mathbf{elif}$

$(\mathit{type}(x, \mathit{symbol}) = \mathit{true}) \mathbf{then} 'L^\#(x)' \mathbf{else} 0 \mathbf{fi} \mathbf{end} \mathbf{proc}:$

>  $\mathit{Tau} := \mathbf{proc}(x) \mathbf{local} y; y := \mathit{op}(1, x) : \mathbf{if} (\mathit{type}(x, \text{'+'}) = \mathit{true}) \mathbf{then} \mathit{add}(\mathit{Tau}(\mathit{op}(i, x)), i = 1$   
 $\dots \mathit{nops}(x)) \mathbf{elif}$

$(\mathit{type}(x, \text{'*'}) = \mathit{true}) \mathbf{then} \mathit{expand}\left(\mathit{Tau}(y) \cdot \frac{x}{y} + y \cdot \mathit{Tau}\left(\frac{x}{y}\right)\right) \mathbf{elif}$

$(\mathit{type}(x, \text{'^'}) = \mathit{true}) \mathbf{then} \mathit{op}(2, x) \cdot y^{(\mathit{op}(2, x) - 1)} \cdot \mathit{Tau}(y) \mathbf{elif}$

$(\mathit{type}(x, \mathit{function}) = \mathit{true}) \mathbf{then} '\mathit{Tau}'(x) \mathbf{elif}$

$(\mathit{type}(x, \mathit{symbol}) = \mathit{true}) \mathbf{then} '\mathit{Tau}'(x) \mathbf{else} 0 \mathbf{fi} \mathbf{end} \mathbf{proc}:$

>  $K^\# := \mathbf{proc}(x) \mathbf{local} y; y := \mathit{op}(1, x) : \mathbf{if} (\mathit{type}(x, \text{'+'}) = \mathit{true}) \mathbf{then} \mathit{add}(K^\#(\mathit{op}(i, x)), i = 1$

.. nops(x) ) elif

(type(x, `\*`) = true) then expand( $K^\#(y) \cdot \frac{x}{y} + y \cdot K^\#(\frac{x}{y})$ ) elif

(type(x, `^`) = true) then op(2, x) · y<sup>(op(2, x) - 1)</sup> · K<sup>#</sup>(y) elif

(type(x, function) = true) then Kfunction<sup>#</sup>(x) elif

(type(x, symbol) = true) then Ksymbol<sup>#</sup>(x) else 0 fi end proc:

> Kfunction<sup>#</sup> := **proc**(x) **local** y; y := recherche(x); **if** y = k<sup>#</sup> **then** 'K<sup>#</sup>'(x) **else** KfunctionI<sup>#</sup>(x) **fi** **end proc**:

> KfunctionI<sup>#</sup> := **proc**(x) **local** y, J: **if** x = k **then** 0 **elif** x = P1 **then** (-L<sup>#</sup>(k<sup>#</sup>) · P1 - L<sup>#</sup>(L<sup>#</sup>(k<sup>#</sup>))) **elif** x = P **then** (-L(k<sup>#</sup>) · P1 - L<sup>#</sup>(L(k<sup>#</sup>)) + 2 · I · Tau(k<sup>#</sup>)) **else** J := op(0, x) : y := op(1, x) : **if** J = L **then** L(KfunctionI<sup>#</sup>(y)) - 'L(k<sup>#</sup>)' · L<sup>#</sup>(y) **elif** J = L<sup>#</sup>

**then** L<sup>#</sup>(KfunctionI<sup>#</sup>(y)) - 'L<sup>#</sup>'(k<sup>#</sup>) · L<sup>#</sup>(y) **elif**

J = K

**then** K(KfunctionI<sup>#</sup>(y)) **elif** J = Tau **then** Tau(KfunctionI<sup>#</sup>(y)) - 'L<sup>#</sup>(k<sup>#</sup>)' · Tau(y) - 'Tau(k<sup>#</sup>)' · L<sup>#</sup>(y) **fi** **fi** **end proc**:

Ksymbol<sup>#</sup> := **proc**(x); **if** x = k **then** 0 **elif** x = P1 **then** (-L<sup>#</sup>(k<sup>#</sup>) · P1 - L<sup>#</sup>(L<sup>#</sup>(k<sup>#</sup>))) **elif** x = P **then** (-L(k<sup>#</sup>) · P1 - L<sup>#</sup>(L(k<sup>#</sup>)) + 2 · I · Tau(k<sup>#</sup>)) **else** 'K<sup>#</sup>'(x) **fi** **end proc**:

> Der := **proc**(x) **local** y; y := op(1, x) : **if** (type(x, `+`) = true) **then** add(Der(op(i, x)), i = 1 .. nops(x)) **elif**

(type(x, `\*`) = true) **then** expand( $\frac{x}{y} \cdot Der(y) + y \cdot Der(\frac{x}{y})$ ) **elif**

(type(x, `^`) = true) **then** op(2, x) · y<sup>(op(2, x) - 1)</sup> · Der(y) **elif**

( (type(x, function) = true) **or** (type(x, symbol) = true) ) **then** Tau(x) · W[1]

+ L(x) · W[2] + K(x) · W[3] + L<sup>#</sup>(x) · W[4] + K<sup>#</sup>(x) · W[5]

**else** 0 **fi** **end proc**:

derivation := **proc**(x) : collect( Der(x), [W[1], W[2], W[3], W[4], W[5]] ) : **end proc**:

> g :=  $\frac{\frac{1}{3} IL^\#(L^\#(k))}{L^\#(k)} - \frac{1}{3} IP1$  :

> g1 :=  $-\frac{\frac{1}{3} IL(L(k^\#))}{L(k^\#)} + \frac{1}{3} IP$  :

> dg := derivation(g) :

> dg1 := derivation(g1) :

> with(LinearAlgebra) :

> m := Matrix( [[1, 0, 0, 0, 0], [g, 1, 0, 0], [0, 0, L<sup>#</sup>(k), 0, 0], [g1, 0, 0, 1, 0], [0, 0, 0, 0, L(k<sup>#</sup>)] ] ) :

> minv := MatrixInverse(m) :

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> dg := derivation(g) :
> dg1 := derivation(g1) :
> with(LinearAlgebra) :
> m := Matrix([[1, 0, 0, 0, 0], [g, 1, 0, 0], [0, 0, L#(k), 0, 0], [g1, 0, 0, 1, 0], [0, 0, 0, 0,
  L(k#) ]]) :
> minv := MatrixInverse(m) :
> W := minv.Vector([V[1], V[2], V[3], V[4], V[5]]) :

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> X := Der(L#(k)) :
> X1 := Der(L(k#)) :
> with(DifferentialGeometry) :
> with(Tools) :
> DGsetup([x, y, z, y1, z1], [c, c1, d, d1, e, e1], M, verbose) :
  The following coordinates have been protected:
    [x, y, z, y1, z1, c, c1, d, d1, e, e1]
  The following vector fields have been defined and protected:
    [D_x, D_y, D_z, D_y1, D_z1, D_c, D_c1, D_d, D_d1, D_e, D_e1]
  The following differential 1-forms have been defined and protected:
    [dx, dy, dz, dy1, dz1, dc, dc1, dd, dd1, de, de1]

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> gr := Matrix([[c*c1, 0, 0, 0, 0], [-I*e*c1, c, 0, 0, 0], [d, e, c/c1, 0, 0], [+I*e1*c, 0, 0, c1, 0],
  [d1, 0, 0, e1, c1/c]]) :

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M > h := MatrixInverse(gr) :
M > A := map(evalDG, (ExteriorDerivative(gr).h));

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A := [[ [dc/c + dc1/c1, 0 dx, 0 dx, 0 dx, 0 dx],
  [ Ie dc/c^2 - Ie dc1/c1c - Ide/c, dc/c, 0 dx, 0 dx, 0 dx ],
  [ -(dc + Ie^2 c1) dc/c^3 c1 + (dc + Ie^2 c1) dc1/c^2 c1^2 + dd/c c1 + Ie de/c^2, -e dc/c^2 + e dc1/c1c + de/c,
  dc/c - dc1/c1, 0 dx, 0 dx ],
  [ Ie1 dc/c1c - Ie1 dc1/c1^2 + Ide1/c1, 0 dx, 0 dx, dc1/c1, 0 dx ],
  [ -(-d1 c1 + Ie1^2 c) dc/c1^2 c^2 + (-d1 c1 + Ie1^2 c) dc1/c1^3 c + dd1/c c1 - Ie1 de1/c1^2, 0 dx, 0 dx,
  e1 dc/c c1 - e1 dc1/c1^2 + de1/c1, -dc/c + dc1/c1 ] ]

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M > t[1] := dc/c : t[2] := Ie dc/c^2 - Ie dc1/c1c - Ide/c :

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M > t[3] := -  $\frac{(dc + Ie^2 cl) dc}{c^3 cl} + \frac{(dc + Ie^2 cl) dc l}{c^2 cl^2} + \frac{dd}{c cl} + \frac{Ie de}{c^2}$  :
M > t[4] :=  $\frac{dcl}{cl}$  : t[5] :=  $\frac{Iel dc}{cl c} - \frac{Iel dcl}{cl^2} + \frac{I del}{cl}$  : t[6] := -  $\frac{(-dl cl + Iel^2 c) dc}{cl^2 c^2}$ 
+  $\frac{(-dl cl + Iel^2 c) dcl}{cl^3 c} + \frac{ddl}{c cl} - \frac{Iel del}{cl^2}$  :
M > FD := FrameData([t[1], t[2], t[3], t[4], t[5], t[6], dx, dy, dz, dy1, dz1], N) :
M > DGsetup(FD, [E], [alpha[1], alpha[2], alpha[3],  $\alpha^{\#}[1]$ ,  $\alpha^{\#}[2]$ ,  $\alpha^{\#}[3]$ , rho, kappa, zeta,
 $\kappa^{\#}$ ,  $\zeta^{\#}$ ]);

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*frame name: N*

(3)

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M > T := Vector([rho, kappa, zeta,  $\kappa^{\#}$ ,  $\zeta^{\#}$ ]) :
N > V := h.T :
>
dV[1] := P · (W[1]&wedge W[2]) - L(k) · (W[1]&wedge W[3]) + P1 · (W[1]
&wedge W[4]) - L#(k#) · (W[1] &wedge W[5]) + I · (W[2] &wedge W[4]) :
> dW[2] := -L(k) · (W[2]&wedge W[3]) + L#(k) · (W[3]&wedge W[4]) - Tau(k) · (W[1]
&wedge W[3]) :
> dV[2] := dW[2] + dg &wedge W[1] + g · dV[1] :
> dV[3] := (X &wedge W[3]) :
> dW[4] := -L#(k#) · (W[4]&wedge W[5]) + L(k#) · (W[5]&wedge W[2]) - Tau(k#) · (W[1]
&wedge W[5]) :
> dV[4] := dW[4] + dg1 &wedge W[1] + g1 &wedge dV[1] :
> dV[5] := (X1 &wedge W[5]) :

```

Omega := map(evalDG, gr.Vector([dV[1], dV[2], dV[3], dV[4], dV[5]])) :

```

N > A := (map(evalDG, (ExteriorDerivative(gr).h))) :

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B := A &MatrixWedge T :

SE := map(evalDG, (B &MatrixPlus Omega)) :

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N > List := GenerateForms([alpha[1], alpha[2], alpha[3],  $\alpha^{\#}[1]$ ,  $\alpha^{\#}[2]$ ,  $\alpha^{\#}[3]$ , rho, kappa,
zeta,  $\kappa^{\#}$ ,  $\zeta^{\#}$ ], 2) :

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N > result := proc(l) local k, t, X; X := 0 : t := expand(GetComponents(l, List)) : for k
from 1 to 55 do X := X + t[k] · List[k] od; X; end proc:

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N > Res1 := result(SE[1]) :

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N > Res2 := result(SE[2]) :

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N > Res3 := result(SE[3]) :

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N > List2 := GenerateForms([rho, kappa, zeta,  $\kappa^{\#}$ ,  $\zeta^{\#}$ ], 2) :

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N > Torsion := proc(S, i, j) local k, X; k :=  $5 \cdot (i - 1) - \frac{i \cdot (i - 1)}{2} + j - i$ ; X
:= map(expand, GetComponents(S, List2)); X[k]; end proc:

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N > expr := expand(I · Torsion(Omega[2], 1, 4) - Torsion(Omega[3], 2, 4)) : expr1

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$:= \text{expand}(-I \cdot \text{Torsion}(\text{Omega}[4], 1, 2) + \text{Torsion}(\text{Omega}[5], 2, 4)) :$

**N** >  $\text{Normalisation} := \text{expand}(\text{solve}(\text{expr}, d)) : \text{Normalisation1} := \text{expand}(\text{solve}(\text{expr1}, d1)) :$

**N** > **for**  $i$  **from** 1 **to** 3 **do**  $Z[i] := \text{result}(\text{subs}(\{d = \text{Normalisation}, d1 = \text{Normalisation1}\}, \text{Omega}[i])) ;$  **od**:

**N** >  $H := \text{expand}\left(\frac{\left(\text{Normalisation} - \left(-I \cdot \frac{e^2 \cdot c1}{2 \cdot c}\right)\right) \cdot c1}{I \cdot c}\right);$

$$H := \frac{2}{9} \frac{L^\#(L^\#(k))^2}{L^\#(k)^2} + \frac{1}{18} \frac{L^\#(L^\#(k)) PI}{L^\#(k)} - \frac{1}{9} PI^2 - \frac{1}{6} \frac{L^\#(L^\#(L^\#(k)))}{L^\#(k)} + \frac{1}{6} L^\#(PI) \quad (4)$$

**N** >  $R := \text{result}(\text{evalDG}(\text{Der}(H) \& \text{wedge rho})) :$

>  $Z[3] := \text{result}\left(\text{evalDG}\left(Z[3] + \frac{I \cdot R}{cI^2}\right)\right);$

$$\begin{aligned} Z_3 := & \left( \frac{1}{3} \frac{T(k) e^2}{L^\#(k) c^3} - \frac{1}{9} \frac{IL(L^\#(k)) PI^2}{cI^2 L^\#(k) c} + \frac{1}{18} \frac{IL(L(k^\#)) L^\#(PI)}{cI^2 c L(k^\#)} \right. \\ & - \frac{1}{27} \frac{IL(L(k^\#)) PI^2}{cI^2 c L(k^\#)} - \frac{1}{9} \frac{IP L^\#(L^\#(L^\#(k)))}{cI^2 L^\#(k) c} - \frac{1}{18} \frac{IeL(L^\#(L^\#(k)) PI}{cI^3 L^\#(k)} \\ & + \frac{1}{2} \frac{IeL^\#(k^\#) eI^2}{cI^3 L(k^\#)} + \frac{4}{27} \frac{IPL^\#(L^\#(k))^2}{cI^2 L^\#(k)^2 c} + \frac{1}{6} \frac{IL(L^\#(k)) L^\#(PI)}{cI^2 L^\#(k) c} \\ & - \frac{2}{9} \frac{IeL^\#(L^\#(k)) L(L(k^\#))}{L^\#(k) L(k^\#) cI c^2} - \frac{1}{3} \frac{IeL(L^\#(L^\#(k)))}{L^\#(k) cI c^2} + \frac{1}{3} \frac{IePI eI}{cI^2 c} \\ & - \frac{1}{3} \frac{Ie^2 L^\#(L^\#(k)) K(L^\#(k))}{L^\#(k)^3 c^3} + \frac{1}{3} \frac{L^\#(T(k)) e}{cI L^\#(k) c^2} + \frac{1}{6} \frac{IL(L^\#(L^\#(L^\#(k))))}{cI^2 L^\#(k) c} \\ & + \frac{2}{9} \frac{IPI L(PI)}{cI^2 c} - \frac{1}{6} \frac{IL^\#(P) e}{cI c^2} + \frac{1}{6} \frac{IL(PI) e}{cI c^2} - \frac{eT(L^\#(k))}{L^\#(k) cI c^2} - \frac{1}{6} \frac{IeL^\#(PI)}{cI^3} \\ & + \frac{1}{9} \frac{IeLPI^2}{cI^3} - \frac{1}{3} \frac{IPe^2}{c^3} - \frac{1}{9} \frac{IePIL(L(k^\#))}{L(k^\#) cI c^2} + \frac{2}{3} \frac{IeL^\#(L^\#(k)) eI}{L^\#(k) cI^2 c} \\ & + \frac{1}{3} \frac{Ie^2 K(L^\#(L^\#(k)))}{L^\#(k)^2 c^3} - \frac{1}{6} \frac{IL(L^\#(PI))}{cI^2 c} - \frac{1}{18} \frac{IL^\#(L^\#(k)) PI K(L^\#(k)) e}{cI L^\#(k)^3 c^2} \\ & \left. + \frac{1}{9} \frac{L^\#(L^\#(k)) T(k) e}{cI L^\#(k)^2 c^2} - \frac{4}{9} \frac{PI T(k) e}{cI L^\#(k) c^2} + \frac{1}{3} \frac{IL^\#(L^\#(k)) Pe}{cI L^\#(k) c^2} \right) \quad (5) \end{aligned}$$

$$\begin{aligned}
& - \frac{\frac{1}{9} \text{IPI} L(L^\#(k)) e}{c l L^\#(k) c^2} + \frac{\frac{4}{9} \text{IL}^\#(L^\#(k)) K(L^\#(L^\#(k))) e}{c l L^\#(k)^3 c^2} \\
& + \frac{\frac{1}{9} \text{IL}^\#(L^\#(k)) \text{PIL}(L^\#(k))}{c l^2 L^\#(k)^2 c} + \frac{\frac{1}{6} \text{IL}^\#(L^\#(L^\#(k))) K(L^\#(k)) e}{c l L^\#(k)^3 c^2} \\
& + \frac{\frac{1}{18} \text{IPI} K(L^\#(L^\#(k))) e}{c l L^\#(k)^2 c^2} + \frac{\frac{11}{18} \text{IL}^\#(L^\#(k)) L(L^\#(k)) e}{c l L^\#(k)^2 c^2} \\
& - \frac{\frac{4}{9} \text{IL}^\#(L^\#(k))^2 K(L^\#(k)) e}{c l L^\#(k)^4 c^2} - \frac{\frac{1}{18} \text{IL}(L(k^\#)) L^\#(L^\#(L^\#(k)))}{c l^2 L^\#(k) c L(k^\#)} \\
& + \frac{\frac{2}{27} \text{IL}(L(k^\#)) L^\#(L^\#(k))^2}{c l^2 L^\#(k)^2 c L(k^\#)} + \frac{\frac{2}{9} \text{Ie} L^\#(k^\#) L(L(k^\#))^2}{c l c^2 L(k^\#)^3} \\
& - \frac{\frac{1}{6} \text{Ie} L^\#(k^\#) L(L(L(k^\#)))}{c l c^2 L(k^\#)^2} - \frac{\frac{1}{9} \text{Ie} L^\#(k^\#) P^2}{c l c^2 L(k^\#)} + \frac{\frac{1}{27} \text{IPL}^\#(L^\#(k)) \text{PI}}{c l^2 L^\#(k) c} \\
& + \frac{\frac{1}{6} \text{Ie} L^\#(k^\#) L(P)}{c l c^2 L(k^\#)} + \frac{\frac{1}{18} \text{Ie} L^\#(k^\#) L(L(k^\#)) P}{c l c^2 L(k^\#)^2} + \frac{\frac{1}{54} \text{IL}(L(k^\#)) L^\#(L^\#(k)) \text{PI}}{c l^2 L^\#(k) c L(k^\#)} \\
& - \frac{\frac{4}{9} \text{IL}^\#(L^\#(k)) L(L^\#(L^\#(k)))}{c l^2 L^\#(k)^2 c} - \frac{\frac{1}{18} \text{IPI} L(L^\#(L^\#(k)))}{c l^2 L^\#(k) c} \\
& - \frac{\frac{1}{18} \text{IL}^\#(L^\#(k)) L(\text{PI})}{c l^2 L^\#(k) c} - \frac{\frac{1}{3} \text{IL}^\#(L^\#(L^\#(k))) L(L^\#(k))}{c l^2 L^\#(k)^2 c} \\
& + \frac{\frac{2}{3} \text{IL}^\#(L^\#(k))^2 L(L^\#(k))}{c l^2 L^\#(k)^3 c} - \frac{\frac{1}{6} \text{IL}^\#(L(L^\#(k))) e}{c l L^\#(k) c^2} - \frac{\frac{1}{6} \text{IK}(L^\#(L^\#(L^\#(k)))) e}{c l L^\#(k)^2 c^2} \\
& - \frac{\frac{1}{2} \text{Ie}^2 e l}{c l c^2} + \frac{\frac{1}{9} \text{IPL}^\#(\text{PI})}{c l^2 c} - \frac{\frac{2}{27} \text{IPIP}^2}{c l^2 c} + \frac{\frac{1}{6} \text{Ie} l L^\#(L^\#(L^\#(k)))}{c l^3 L^\#(k)} \\
& - \left. \begin{aligned} & - \frac{\frac{1}{6} \text{Ie}^2 L(L^\#(k))}{L^\#(k) c^3} + \frac{\frac{1}{6} \text{Ie}^2 L(L(k^\#))}{c^3 L(k^\#)} - \frac{\frac{2}{9} \text{Ie} l L^\#(L^\#(k))^2}{c l^3 L^\#(k)^2} \end{aligned} \right\} \rho \wedge \kappa \\
& + \left( \frac{\frac{1}{9} \text{IL}^\#(k^\#) P^2}{c l c L(k^\#)} - \frac{\frac{2}{9} \text{IL}^\#(k^\#) L(L(k^\#))^2}{c l c L(k^\#)^3} - \frac{\frac{1}{6} \text{IL}^\#(k^\#) L(P)}{c l c L(k^\#)} \right)
\end{aligned}$$

$$\begin{aligned}
& + \frac{\frac{1}{6} \text{IL}^\#(k^\#) L(L(L(k^\#)))}{c l c L(k^\#)^2} - \frac{\frac{1}{2} \text{I} c L^\#(k^\#) e l^2}{c l^3 L(k^\#)} - \frac{1}{3} \frac{L^\#(\text{T}(k))}{c l L^\#(k) c} \\
& + \frac{\frac{1}{6} \text{IL}^\#(L(L^\#(k)))}{c l L^\#(k) c} + \frac{\frac{1}{6} \text{IK}(L^\#(L^\#(L^\#(k))))}{c l L^\#(k)^2 c} + \frac{\frac{1}{6} \text{IL}(k) L^\#(L^\#(L^\#(k)))}{L^\#(k)^2 c l c} \\
& - \frac{\frac{1}{2} \text{I} c l e^2 L(k)}{L^\#(k) c^3} - \frac{\frac{2}{9} \text{IL}(k) L^\#(L^\#(k))^2}{L^\#(k)^3 c l c} + \frac{\frac{1}{9} \text{IL}(k) P l^2}{L^\#(k) c l c} - \frac{\frac{1}{6} \text{IL}(k) L^\#(P l)}{L^\#(k) c l c} \\
& - \frac{\frac{2}{9} \text{I} P l P}{c l c} + \frac{\frac{1}{3} \text{I} e L^\#(L^\#(k)) K(L^\#(k))}{L^\#(k)^3 c^2} - \frac{\frac{1}{18} \text{IL}(k) L^\#(L^\#(k)) P l}{L^\#(k)^2 c l c} \\
& - \frac{1}{3} \frac{e \text{T}(k)}{L^\#(k) c^2} + \frac{\frac{1}{3} \text{IL}^\#(L^\#(k)) L(L(k^\#))}{L^\#(k) L(k^\#) c l c} - \frac{\frac{1}{3} \text{I} e L(L(k^\#))}{L(k^\#) c^2} - \frac{\text{IL}^\#(L^\#(k)) e l}{L^\#(k) c l^2} \\
& + \frac{\frac{2}{3} \text{IL}(L^\#(k)) e}{L^\#(k) c^2} - \frac{\frac{1}{3} \text{I} e K(L^\#(L^\#(k)))}{L^\#(k)^2 c^2} + \frac{\text{I} e e l}{c l c} + \frac{\text{T}(L^\#(k))}{L^\#(k) c l c} + \frac{\frac{1}{6} \text{IL}(P l)}{c l c} \\
& + \frac{\frac{1}{6} \text{IL}^\#(P)}{c l c} + \frac{\frac{1}{18} \text{IL}^\#(L^\#(k)) P l K(L^\#(k))}{c l L^\#(k)^3 c} - \frac{\frac{1}{18} \text{IL}^\#(k^\#) L(L(k^\#)) P}{c l c L(k^\#)^2} \\
& - \frac{1}{9} \frac{L^\#(L^\#(k)) \text{T}(k)}{c l L^\#(k)^2 c} + \frac{4}{9} \frac{P l \text{T}(k)}{c l L^\#(k) c} - \frac{\frac{1}{18} \text{I} P l K(L^\#(L^\#(k)))}{c l L^\#(k)^2 c} \\
& + \frac{\frac{4}{9} \text{IL}^\#(L^\#(k))^2 K(L^\#(k))}{c l L^\#(k)^4 c} - \frac{\frac{1}{9} \text{IL}^\#(L^\#(k)) P}{c l L^\#(k) c} - \frac{\frac{1}{6} \text{IL}^\#(L^\#(L^\#(k))) K(L^\#(k))}{c l L^\#(k)^3 c} \\
& + \left. \frac{\frac{1}{9} \text{I} P l L(L^\#(k))}{c l L^\#(k) c} - \frac{\frac{5}{18} \text{IL}^\#(L^\#(k)) L(L^\#(k))}{c l L^\#(k)^2 c} - \frac{\frac{4}{9} \text{IL}^\#(L^\#(k)) K(L^\#(L^\#(k)))}{c l L^\#(k)^3 c} \right) \\
\rho \wedge \zeta + & \left( \frac{\frac{20}{27} \text{IL}^\#(L^\#(k))^3}{c l^3 L^\#(k)^3} - \frac{\frac{1}{6} \text{IL}^\#(L^\#(P l))}{c l^3} + \frac{\frac{5}{18} \text{IL}^\#(L^\#(k))^2 P l}{c l^3 L^\#(k)^2} \right. \\
& - \frac{\frac{1}{9} \text{IL}^\#(L^\#(k)) P l^2}{L^\#(k) c l^3} - \frac{\frac{5}{6} \text{IL}^\#(L^\#(k)) L^\#(L^\#(L^\#(k)))}{c l^3 L^\#(k)^2} + \frac{\frac{1}{6} \text{IL}^\#(L^\#(k)) L^\#(P l)}{c l^3 L^\#(k)} \\
& \left. - \frac{\frac{1}{6} \text{I} P l L^\#(L^\#(L^\#(k)))}{c l^3 L^\#(k)} + \frac{\frac{1}{3} \text{I} P l L^\#(P l)}{c l^3} + \frac{\frac{1}{6} \text{IL}^\#(L^\#(L^\#(L^\#(k))))}{c l^3 L^\#(k)} \right)
\end{aligned}$$

$$\begin{aligned}
& - \frac{2}{27} \frac{IPI^3}{cI^3} \Big) \rho \wedge \kappa^\# + \left( \frac{L(L^\#(k))}{L^\#(k) c} - \frac{eL(k) cI}{c^2 L^\#(k)} \right) \kappa \wedge \zeta + \left( \frac{eL^\#(k^\#) eI}{cI^2 L(k^\#)} \right. \\
& + \frac{2}{3} \frac{eL^\#(L^\#(k))}{c cI L^\#(k)} + \frac{1}{3} \frac{ePI}{c cI} - \frac{1}{2} \frac{e^2}{c^2} - \frac{2}{9} \frac{L^\#(L^\#(k))^2}{cI^2 L^\#(k)^2} - \frac{1}{18} \frac{L^\#(L^\#(k)) PI}{cI^2 L^\#(k)} \\
& + \left. \frac{1}{9} \frac{PI^2}{cI^2} + \frac{1}{6} \frac{L^\#(L^\#(L^\#(k)))}{cI^2 L^\#(k)} - \frac{1}{6} \frac{L^\#(PI)}{cI^2} \right) \kappa \wedge \kappa^\# - \frac{L^\#(k^\#) e \kappa \wedge \zeta^\#}{cI L(k^\#)} + \left( \right. \\
& - \left. \frac{eI L^\#(k^\#) c}{cI^2 L(k^\#)} - \frac{L^\#(L^\#(k))}{cI L^\#(k)} + \frac{e}{c} \right) \zeta \wedge \kappa^\# + \frac{L^\#(k^\#) c \zeta \wedge \zeta^\#}{cI L(k^\#)}
\end{aligned}$$

**>** result(evalDG(Der(J)) &wedge rho) :

$$\begin{aligned}
\text{> } Q[1] := & \left( \text{evalDG} \left( \text{subs} \left( \left\{ c = J^{\frac{1}{3}}, cI = JI^{\frac{1}{3}} \right\}, \left( \frac{1}{3} \frac{\text{Der}(J)}{(J)} + \frac{1}{3} \frac{\text{Der}(JI)}{JI} \right) \&wedge \text{rho} \right. \right. \right. \\
& \left. \left. \left. + Z[1] \right) \right) \right) :
\end{aligned}$$

**N** > Torsion(Q[1], 1, 4);

$$\begin{aligned}
& - \frac{e}{J^{1/3}} + \frac{1}{3} \frac{L^\#(L^\#(k))}{JI^{1/3} L^\#(k)} + \frac{2}{3} \frac{PI}{JI^{1/3}} + \frac{J^{1/3} eI L^\#(k^\#)}{JI^{2/3} L(k^\#)} + \frac{1}{3} \frac{J^{1/3} K^\#(JI) eI}{JI^{5/3} L(k^\#)} - \frac{1}{3} \frac{L^\#(JI)}{JI^{4/3}} \\
& + \frac{1}{3} \frac{K^\#(J) eI}{J^{2/3} JI^{2/3} L(k^\#)} - \frac{1}{3} \frac{L^\#(J)}{JJI^{1/3}}
\end{aligned} \tag{6}$$

$$\text{N } > Y[1] := \text{subs} \left( \left\{ e = \frac{e}{J^{\frac{-1}{3}}}, eI = \frac{eI}{JI^{\frac{-1}{3}}} \right\}, Q[1] \right) :$$

**N** > Col := Torsion(Y[1], 1, 4);

$$\begin{aligned}
\text{Col} := & -e + \frac{1}{3} \frac{L^\#(L^\#(k))}{JI^{1/3} L^\#(k)} + \frac{2}{3} \frac{PI}{JI^{1/3}} + \frac{J^{1/3} eI L^\#(k^\#)}{JI^{1/3} L(k^\#)} + \frac{1}{3} \frac{J^{1/3} K^\#(JI) eI}{JI^{4/3} L(k^\#)} \\
& - \frac{1}{3} \frac{L^\#(JI)}{JI^{4/3}} + \frac{1}{3} \frac{K^\#(J) eI}{J^{2/3} JI^{1/3} L(k^\#)} - \frac{1}{3} \frac{L^\#(J)}{JJI^{1/3}}
\end{aligned} \tag{7}$$

$$\begin{aligned}
\text{N } > Q[3] := & \left( \text{evalDG} \left( \text{subs} \left( \left\{ c = J^{\frac{1}{3}}, cI = JI^{\frac{1}{3}} \right\}, \left( \frac{e \cdot \text{Der}(JI)}{3 \cdot JI^{\frac{1}{3}} \cdot J^{\frac{1}{3}}} \&wedge \text{kappa} \right) \right. \right. \right. \\
& \left. \left. \left. + \left( \frac{1}{3} \frac{\text{Der}(J)}{(J)} - \frac{1}{3} \frac{\text{Der}(JI)}{JI} \right) \&wedge \text{zeta} + Z[3] \right) \right) \right) :
\end{aligned}$$

$$\text{N } > Y[3] := \text{subs} \left( \left\{ e = \frac{e}{J^{\frac{-1}{3}}}, eI = \frac{eI}{JI^{\frac{-1}{3}}} \right\}, Q[3] \right) :$$

**N** > Co2 := Torsion(Y[3], 3, 4);

(8)

$$\begin{aligned}
Co2 := & -\frac{J^{1/3} e l L^\#(k^\#)}{J I^{1/3} L(k^\#)} - \frac{L^\#(L^\#(k))}{J I^{1/3} L^\#(k)} + e - \frac{1}{3} \frac{J^{1/3} K^\#(J I) e l}{J I^{4/3} L(k^\#)} + \frac{1}{3} \frac{L^\#(J I)}{J I^{4/3}} \\
& + \frac{1}{3} \frac{K^\#(J) e l}{J^{2/3} J I^{1/3} L(k^\#)} - \frac{1}{3} \frac{L^\#(J)}{J J I^{1/3}}
\end{aligned} \tag{8}$$

**N** > `expr := expand(simplify(-Co1 + Co2));`

$$\begin{aligned}
expr := & 2 e - \frac{4}{3} \frac{L^\#(L^\#(k))}{J I^{1/3} L^\#(k)} - \frac{2}{3} \frac{P I}{J I^{1/3}} - \frac{2 J^{1/3} e l L^\#(k^\#)}{J I^{1/3} L(k^\#)} - \frac{2}{3} \frac{J^{1/3} K^\#(J I) e l}{J I^{4/3} L(k^\#)} \\
& + \frac{2}{3} \frac{L^\#(J I)}{J I^{4/3}}
\end{aligned} \tag{9}$$

**N** > `expand(subs(K^\#(J I) = -3 * J I * L^\#(k^\#), \frac{expr}{2}));`

$$e - \frac{2}{3} \frac{L^\#(L^\#(k))}{J I^{1/3} L^\#(k)} - \frac{1}{3} \frac{P I}{J I^{1/3}} + \frac{1}{3} \frac{L^\#(J I)}{J I^{4/3}} \tag{10}$$