- > restart:
- > with(DifferentialGeometry):
- with(Tools) : with(LinearAlgebra) :
- $\rightarrow$  DGsetup([x, y, z, z1], [a, a1, b, b1, c, d, e], M, verbose);

The following coordinates have been protected:

The following vector fields have been defined and protected:

$$[D_x, D_y, D_z, D_zl, D_a, D_al, D_b, D_bl, D_c, D_d, D_e]$$

The following differential 1-forms have been defined and protected:

>  $g := Matrix([[a^2 \cdot a1, 0, 0, 0], [c, a \cdot a1, 0, 0], [d, b, a, 0], [e, b1, 0, a1]]);$ 

$$g := \begin{bmatrix} a^2 a1 & 0 & 0 & 0 \\ c & a a1 & 0 & 0 \\ d & b & a & 0 \\ e & b1 & 0 & a1 \end{bmatrix}$$
 (2)

- $\rightarrow h := MatrixInverse(g) :$
- $\rightarrow$  Mat := map(evalDG, (ExteriorDerivative(g).h));

$$Mat := \begin{bmatrix} \frac{2da}{a} + \frac{da1}{a1} & 0 dx & 0 dx & 0 dx \\ -\frac{c da}{a1 a^3} - \frac{c da1}{a1^2 a^2} + \frac{dc}{a^2 a1} & \frac{da}{a} + \frac{da1}{a1} & 0 dx & 0 dx \\ -\frac{(d a a1 - b c) da}{a^4 a1^2} - \frac{c db}{a^3 a1^2} + \frac{dd}{a^2 a1} & -\frac{b da}{a^2 a1} + \frac{db}{a a1} & \frac{da}{a} & 0 dx \\ -\frac{(e a a1 - b1 c) da1}{a^3 a1^3} - \frac{c db1}{a^3 a1^2} + \frac{de}{a^2 a1} & -\frac{b1 da1}{a a1^2} + \frac{db1}{a a1} & 0 dx & \frac{da1}{a1} \end{bmatrix}$$

$$\Rightarrow t[1] := \frac{da}{a} :$$

$$> t[1] := \frac{da}{a}$$

**M** > 
$$t[2] := -\frac{b \, da}{a^2 \, a \, l} + \frac{db}{a \, a \, l}$$
:

$$M > t[3] := -\frac{c \, da}{a1 \, a^3} - \frac{c \, da1}{a1^2 \, a^2} + \frac{dc}{a^2 \, a1}$$

$$\begin{bmatrix} \mathbf{M} > t[3] := -\frac{c \, da}{a1 \, a^3} - \frac{c \, da1}{a1^2 \, a^2} + \frac{dc}{a^2 \, a1} : \\ \mathbf{M} > t[4] := -\frac{(d \, a \, a1 - b \, c) \, da}{a^4 \, a1^2} - \frac{c \, db}{a^3 \, a1^2} + \frac{dd}{a^2 \, a1} : \\ \end{bmatrix}$$

$$\begin{bmatrix} \mathbf{M} > t[5] := -\frac{(e \ a \ al - bl \ c) \ dal}{a^3 \ al^3} - \frac{c \ dbl}{a^3 \ al^2} + \frac{de}{a^2 \ al} :$$

$$\mathbf{M} > t[6] := \frac{da1}{a!}$$
:

**M** > 
$$t[7] := -\frac{b1 \, da1}{a \, a1^2} + \frac{db1}{a \, a1}$$
:

ightharpoonup FD := FrameData([t[1], t[2], t[3], t[4], t[5], t[6], t[7], dx, dy, dz, dz1], N): $DGsetup(FD, [E], [alpha[1], alpha[2], alpha[3], alpha[4], alpha[5], <math>\alpha^{\#}[1], \alpha^{\#}[2], sigma, \alpha^{\#}[1], \alpha^{\#}[2], sigma, \alpha^{\#}[1], \alpha^{\#}[2], sigma, \alpha^{\#}[2], \alpha^{\#}[2], sigma, \alpha^{\#}[2], \alpha^{\#}[2], \alpha^{\#}[2], sigma, \alpha^{\#}[2], \alpha^{\#}[2],$ rho, zeta,  $\zeta^{\#}$ ], verbose);

The following coordinates have been protected:

The following vector fields have been defined and protected:

[E1, E2, E3, E4, E5, E6, E7, E8, E9, E10, E11]

The following differential 1-forms have been defined and protected:

$$\left[\alpha_{1}, \alpha_{2}, \alpha_{3}, \alpha_{4}, \alpha_{5}, \alpha_{1}^{\sharp}, \alpha_{2}^{\sharp}, \sigma, \rho, \zeta, \zeta^{\sharp}\right]$$
frame name: N
(4)

 $\mathbf{M} > T := Vector(|\operatorname{sigma}, \operatorname{rho}, \operatorname{zeta}, \zeta^{\#}|)$ :

 $\mathit{Eq1} \coloneqq H \cdot (\mathit{W} [1] \& \mathit{wedge} \ \mathit{W} [2]) + F \cdot (\mathit{W} [1] \& \mathit{wedge} \ \mathit{W} [4]) + Q \cdot (\mathit{W} [1] \& \mathit{wedge} \ \mathit{W} [3]) + B \cdot (\mathit{W} [2] ) + B \cdot (\mathit{W}$ & wedge W[4]) + (W[2] & wedge W[3]);

$$\frac{H\sigma \wedge \rho}{a^3 a l^2} + F\left(-\frac{b l \sigma \wedge \rho}{a^3 a l^3} + \frac{\sigma \wedge \xi^{\sharp}}{a l^2 a^2}\right) + Q\left(-\frac{b \sigma \wedge \rho}{a^4 a l^2} + \frac{\sigma \wedge \zeta}{a l a^3}\right) + B\left(\frac{e \sigma \wedge \rho}{a^3 a l^3}\right) - \frac{c \sigma \wedge \xi^{\sharp}}{a^3 a l^3} + \frac{\rho \wedge \xi^{\sharp}}{a a l^2}\right) + \frac{d \sigma \wedge \rho}{a^4 a l^2} - \frac{c \sigma \wedge \zeta}{a^4 a l^2} + \frac{\rho \wedge \zeta}{a^2 a l}$$
(5)

$$\begin{array}{l} \mathbf{M} > Eq2 \coloneqq G \cdot (W[1] \& wedge \ W[2]) + E \cdot (W[1] \& wedge \ W[4]) + P \cdot (W[1] \\ \& wedge \ W[3]) + A \cdot (W[2] \& wedge \ W[4]) + I \cdot (W[3] \& wedge \ W[4]); \\ Eq2 \coloneqq \frac{G \sigma \wedge \rho}{a^3 \ al^2} + E \left( -\frac{bl \sigma \wedge \rho}{a^3 \ al^3} + \frac{\sigma \wedge \zeta^{\#}}{al^2 \ a^2} \right) + P \left( -\frac{b \sigma \wedge \rho}{a^4 \ al^2} + \frac{\sigma \wedge \zeta}{al \ a^3} \right) \\ + A \left( \frac{e \sigma \wedge \rho}{a^3 \ al^3} - \frac{c \sigma \wedge \zeta^{\#}}{a^3 \ al^3} + \frac{\rho \wedge \zeta^{\#}}{a \ al^2} \right) + I \left( -\frac{(b \ e - bl \ d) \ \sigma \wedge \rho}{a^4 \ al^3} \right) \\ + \frac{(e \ a \ al - bl \ c) \ \sigma \wedge \zeta}{a^4 \ al^3} - \frac{(d \ a \ al - b \ c) \ \sigma \wedge \zeta^{\#}}{a^4 \ al^3} + \frac{bl \ \rho \wedge \zeta}{a^2 \ al^2} - \frac{b \ \rho \wedge \zeta^{\#}}{a^2 \ al^2} \\ + \frac{\zeta \wedge \zeta^{\#}}{a \ al} \right) \\ = \mathbf{N} > Eq3 \coloneqq 0 : \end{array}$$

$$\mathbf{N} > Eq3 \coloneqq 0$$
:

$$\mathbf{N} > Eq4 \coloneqq 0$$
:

$$\triangleright$$
 omega :=  $Vector([Eq1, Eq2, Eq3, Eq4])$ :

Mat := map(evalDG, (ExteriorDerivative(g).h)):

Mat2 := Mat & Matrix Wedge T:

 $\triangleright$  SE := map(evalDG, (Mat2 &MatrixPlus Omega)):

N > List := GenerateForms([alpha[1], alpha[2], alpha[3], alpha[4], alpha[5],  $\alpha^{\#}[1]$ ,  $\alpha^{\#}[2]$ , sigma, rho, zeta,  $\zeta^{\#}[2]$ :

N > Torsion :=  $\operatorname{proc}(S, i, j) \operatorname{local} k, X; \ k := 11 \cdot (i - 1) - \frac{i \cdot (i - 1)}{2} + j - i; \ X$ :=  $\operatorname{GetComponents}(S, \operatorname{List}); \ X[k]; \ \operatorname{end} \operatorname{proc}:$ 

N > result :=  $\operatorname{proc}(l) \operatorname{local} k$ ,  $t, X; X := 0 : t := \operatorname{expand}(\operatorname{GetComponents}(l, \operatorname{List})) : \operatorname{for} k$ from 1 to 55 do  $X := X + t[k] \cdot \operatorname{List}[k]$  od; X; end  $\operatorname{proc}$ :

 $\mathbf{N} > Res1 := result(SE[1]);$ 

$$Res1 := 2 \alpha_1 \wedge \sigma + \alpha_1^{\sharp} \wedge \sigma + \left(\frac{d}{a^2 a l} + \frac{e B}{a a l^2} - \frac{Q b}{a l a^2} - \frac{F b l}{a l^2 a} + \frac{H}{a l a}\right) \sigma \wedge \rho + \left(7\right)$$

$$-\frac{c}{a^2 a l} + \frac{Q}{a}\right) \sigma \wedge \zeta + \left(-\frac{c B}{a a l^2} + \frac{F}{a l}\right) \sigma \wedge \zeta^{\sharp} + \rho \wedge \zeta + \frac{a B \rho \wedge \zeta^{\sharp}}{a l}$$

 $\mathbf{N} > Res2 := result(SE[2]);$ 

$$Res2 := \alpha_{1} \wedge \rho + \alpha_{3} \wedge \sigma + \alpha_{1}^{\sharp} \wedge \rho + \left(-\frac{1be}{a^{3}al^{2}} + \frac{1bld}{a^{3}al^{2}} + \frac{Ae}{a^{2}al^{2}} - \frac{bP}{a^{3}al} - \frac{blE}{a^{2}al^{2}}\right)$$

$$+ \frac{G}{a^{2}al} + \frac{dc}{a^{4}al^{2}} + \frac{eBc}{a^{3}al^{3}} - \frac{cQb}{a^{4}al^{2}} - \frac{cFbl}{a^{3}al^{3}} + \frac{cH}{a^{3}al^{2}}\right) \sigma \wedge \rho + \left(\frac{1e}{a^{2}al} - \frac{1blc}{a^{2}al} + \frac{P}{a^{2}} - \frac{c^{2}}{a^{4}al^{2}} + \frac{cQ}{a^{3}al}\right) \sigma \wedge \zeta + \left(-\frac{1d}{a^{2}al} + \frac{1bc}{a^{3}al^{2}} - \frac{Ac}{a^{2}al^{2}} + \frac{E}{aal}\right)$$

$$- \frac{Bc^{2}}{a^{3}al^{3}} + \frac{cF}{a^{2}al^{2}}\right) \sigma \wedge \zeta^{\sharp} + \left(\frac{1bl}{aal} + \frac{c}{a^{2}al}\right) \rho \wedge \zeta + \left(-\frac{1b}{aal} + \frac{A}{al} + \frac{cB}{aal^{2}}\right) \rho \wedge \zeta^{\sharp} + 1\zeta \wedge \zeta^{\sharp}$$

 $\mathbf{N} > Res3 := result(SE[3]);$ 

$$Res3 := \alpha_{1} \wedge \zeta + \alpha_{2} \wedge \rho + \alpha_{4} \wedge \sigma + \left( -\frac{1b^{2}e}{a^{4}aI^{3}} + \frac{1bbId}{a^{4}aI^{3}} + \frac{bAe}{a^{3}aI^{3}} - \frac{Pb^{2}}{a^{4}aI^{2}} - \frac{bEbI}{a^{3}aI^{3}} \right)$$

$$+ \frac{bG}{a^{3}aI^{2}} + \frac{d^{2}}{a^{4}aI^{2}} + \frac{dBe}{a^{3}aI^{3}} - \frac{dQb}{a^{4}aI^{2}} - \frac{dFbI}{a^{3}aI^{3}} + \frac{dH}{a^{3}aI^{2}} \right) \sigma \wedge \rho + \left( \frac{1be}{a^{3}aI^{2}} - \frac{1bIbC}{a^{4}aI^{3}} + \frac{bP}{a^{3}aI} - \frac{dC}{a^{4}aI^{2}} + \frac{dQ}{a^{3}aI} \right) \sigma \wedge \zeta + \left( -\frac{1bd}{a^{3}aI^{2}} + \frac{1b^{2}C}{a^{4}aI^{3}} - \frac{bAC}{a^{3}aI^{3}} + \frac{bE}{a^{2}aI^{2}} - \frac{dBC}{a^{3}aI^{3}} + \frac{dF}{a^{2}aI^{2}} \right) \sigma \wedge \zeta^{\#} + \left( \frac{1bbI}{a^{2}aI^{2}} + \frac{d}{a^{2}aI} \right) \rho \wedge \zeta + \left( -\frac{1b^{2}}{aI^{2}a^{2}} + \frac{dB}{aaI^{2}} \right) \rho \wedge \zeta^{\#} + \frac{1b\zeta \wedge \zeta^{\#}}{aaI}$$

 $\overset{-}{\mathbf{N}} > Res4 := result(SE[4]);$ 

$$Res4 := \alpha_{5} \wedge \sigma + \alpha_{1}^{\#} \wedge \zeta^{\#} + \alpha_{2}^{\#} \wedge \rho + \left( -\frac{IbIbe}{a^{4}aI^{3}} + \frac{IbI^{2}d}{a^{4}aI^{3}} + \frac{bIAe}{a^{3}aI^{3}} - \frac{bIPb}{a^{4}aI^{2}} \right)$$

$$- \frac{EbI^{2}}{a^{3}aI^{3}} + \frac{bIG}{a^{3}aI^{2}} + \frac{ed}{a^{4}aI^{2}} + \frac{Be^{2}}{a^{3}aI^{3}} - \frac{eQb}{a^{4}aI^{2}} - \frac{eFbI}{a^{3}aI^{3}} + \frac{eH}{a^{3}aI^{2}} \right) \sigma \wedge \rho$$

$$(10)$$

$$+ \left(\frac{\mathrm{I}b1\,e}{a^3\,al^2} - \frac{\mathrm{I}bl^2\,c}{a^4\,al^3} + \frac{b1\,P}{a^3\,al} - \frac{e\,c}{a^4\,al^2} + \frac{e\,Q}{a^3\,al}\right) \sigma\,\Lambda\,\zeta + \left(-\frac{\mathrm{I}b1\,d}{a^3\,al^2} + \frac{\mathrm{I}bl\,b\,c}{a^4\,al^3} - \frac{b1\,A\,c}{a^3\,al^3} + \frac{b1\,E}{a^2\,al^2} - \frac{e\,B\,c}{a^3\,al^3} + \frac{e\,F}{a^2\,al^2}\right) \sigma\,\Lambda\,\zeta^{\sharp} + \left(\frac{\mathrm{I}bl^2}{al^2\,a^2} + \frac{e}{al\,a^2}\right) \rho\,\Lambda\,\zeta + \left(-\frac{\mathrm{I}bl\,b\,c}{a^3\,al^3} + \frac{e\,B}{al\,a^2}\right) \rho\,\Lambda\,\zeta^{\sharp} + \frac{\mathrm{I}bl\,\zeta\,\Lambda\,\zeta^{\sharp}}{a\,al}$$

$$- \frac{\mathrm{I}bl\,b}{al^2\,a^2} + \frac{bl\,A}{al^2\,a} + \frac{e\,B}{a\,al^2\,a}\right) \rho\,\Lambda\,\zeta^{\sharp} + \frac{\mathrm{I}bl\,\zeta\,\Lambda\,\zeta^{\sharp}}{a\,al}$$